

# RF Power Modules

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Philips Semiconductors



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## SELECTION GUIDE

# RF power modules

# Selection guide

## INTRODUCTION

The following tables represent our complete range of RF power modules.

### VHF modules for mobile transmitters

$P_L$ (W)	$V_s$ (V)	f (MHz)	$G_p$ (dB)	ENVELOPE	TYPE NUMBER	PAGE
18	12.5	68 to 88	22.6	SOT132B	BGY32	25
18	12.5	80 to 108	22.6	SOT132B	BGY33	25
18	12.5	132 to 156	20.8	SOT132B	BGY35	25
18	12.5	148 to 174	20.8	SOT132B	BGY36	25
13	12.5	148 to 174	19.4	SOT132B	BGY43	35
7	7.5	68 to 88	38.5	SOT288C	BGY112A	97
7	7.5	132 to 156	38.5	SOT288C	BGY112B	97
7	7.5	146 to 174	38.5	SOT288C	BGY112C	97
29	12.5	68 to 88	22.9	SOT183A	BGY145A	105
28	12.5	148 to 174	19.7	SOT183A	BGY145B	113
40	12.5	174 to 200	19.5	SOT183A	BGY145C	121

### UHF modules for portable transmitters

$P_L$ (W)	$V_s$ (V)	f (MHz)	$G_p$ (dB)	ENVELOPE	TYPE NUMBER	PAGE
1.4	9.6	400 to 440	15	SOT181	BGY46A	43
1.4	9.6	430 to 470	15	SOT181	BGY46B	49
3.2	9.6	400 to 440	18	SOT181	BGY47A	55
7	7.5	400 to 440	38.5	SOT288D	BGY113A	101
7	7.5	430 to 470	38.5	SOT288D	BGY113B	101

### SHF modules for portable transmitters

$P_L$ (W)	$V_s$ (V)	f (MHz)	$G_p$ (dB)	ENVELOPE	TYPE NUMBER	PAGE
2.2	7.5	824 to 849	20.4	SOT200	BGY95A	63
2.2	7.5	890 to 915	20.4	SOT200	BGY95B	63
2.5	9.6	824 to 849	21	SOT200	BGY96A	73
2.5	9.6	890 to 915	21	SOT200	BGY96B	73
1.2	6	824 to 849	30.8	SOT246	BGY110A	81
1.2	6	872 to 905	30.8	SOT246	BGY110B	83
1.7	7.2	824 to 849	32.3	SOT246	BGY110D	85
1.7	7.2	872 to 905	32.3	SOT246	BGY110E	85
1.7	7.2	890 to 915	32.3	SOT246	BGY110F	85

TYPE NUMBER SURVEY

## RF power modules

## Type number survey

## INTRODUCTION

In this alphanumeric list we present all RF power modules mentioned in this handbook, together with the most important data.

TYPE NUMBER	ENVELOPE	$V_s$ (V)	f (MHz)	$P_L$ (W)	$G_p$ (dB)	PAGE
BGY32	SOT132	12.5	68 to 88	> 18	22.6	25
BGY33	SOT132	12.5	80 to 108	> 18	22.6	25
BGY35	SOT132	12.5	132 to 156	> 18	20.6	25
BGY36	SOT132	12.5	148 to 174	> 18	20.8	25
BGY43	SOT132	12.5	148 to 174	> 13	19.4	35
BGY46A	SOT181	9.6	400 to 440	> 1.4	15	43
BGY46B	SOT181	9.6	430 to 470	> 1.4	15	49
BGY47A	SOT181	9.6	400 to 470	> 3.2	18	55
BGY95A	SOT200	7.5	824 to 849	> 2.2	20.4	63
BGY95B	SOT200	7.5	890 to 915	> 2.2	20.4	63
BGY96A	SOT200	9.6	824 to 849	> 2.5	21	73
BGY96B	SOT200	9.6	890 to 915	> 2.5	21	73
BGY110A	SOT246	6	824 to 849	> 1.2	30.8	81
BGY110B	SOT246	6	872 to 905	> 1.2	30.8	83
BGY110D	SOT246	7.2	824 to 849	> 1.7	32.3	85
BGY110E	SOT246	7.2	872 to 905	> 1.7	32.3	85
BGY110F	SOT246	7.2	890 to 915	> 1.7	32.3	85
BGY112A	SOT288C	7.5	68 to 88	> 7	38.5	97
BGY112B	SOT288C	7.5	132 to 156	> 7	38.5	97
BGY112C	SOT288C	7.5	146 to 174	> 7	38.5	97
BGY113A	SOT288D	7.5	400 to 440	> 7	38.5	101
BGY113B	SOT288D	7.5	430 to 470	> 7	38.5	101
BGY145A	SOT183A	12.5	68 to 88	> 29	22.9	105
BGY145B	SOT183A	12.5	146 to 174	> 28	19.7	113
BGY145C	SOT183A	12.5	174 to 200	> 27	19.5	121



## GENERAL

**Type designation**

**Rating systems**

**Letter symbols**

**s-parameters**

**Mounting recommendations**



## PRO ELECTRON TYPE DESIGNATION CODE FOR SEMICONDUCTOR DEVICES

This type designation code applies to discrete semiconductor devices — as opposed to integrated circuits —, multiples of such devices and semiconductor chips.

“Although not all type numbers accord with the Pro Electron system, the following explanation is given for the ones that do.”

A basic type number consists of:

*TWO LETTERS FOLLOWED BY A SERIAL NUMBER*

### FIRST LETTER

The first letter gives information about the material used for the active part of the devices.

- A. GERMANIUM or other material with band gap of 0,6 to 1,0 eV.
- B. SILICON or other material with band gap of 1,0 to 1,3 eV.
- C. GALLIUM-ARSENIDE or other material with band gap of 1,3 eV or more.
- R. COMPOUND MATERIALS (e.g. Cadmium-Sulphide).

### SECOND LETTER

The second letter indicates the function for which the device is primarily designed.

- A. DIODE; signal, low power
- B. DIODE; variable capacitance
- C. TRANSISTOR; low power, audio frequency ( $R_{th j-mb} > 15 \text{ K/W}$ )
- D. TRANSISTOR; power, audio frequency ( $R_{th j-mb} \leq 15 \text{ K/W}$ )
- E. DIODE; tunnel
- F. TRANSISTOR; low power, high frequency ( $R_{th j-mb} > 15 \text{ K/W}$ )
- G. MULTIPLE OF DISSIMILAR DEVICES — MISCELLANEOUS; e.g. oscillator
- H. DIODE; magnetic sensitive
- L. TRANSISTOR; power, high frequency ( $R_{th j-mb} \leq 15 \text{ K/W}$ )
- N. PHOTO-COUPLER
- P. RADIATION DETECTOR; e.g. high sensitivity phototransistor
- Q. RADIATION GENERATOR; e.g. light-emitting diode (LED)
- R. CONTROL AND SWITCHING DEVICE; e.g. thyristor, low power ( $R_{th j-mb} > 15 \text{ K/W}$ )
- S. TRANSISTOR; low power, switching ( $R_{th j-mb} > 15 \text{ K/W}$ )
- T. CONTROL AND SWITCHING DEVICE; e.g. thyristor, power ( $R_{th j-mb} \leq 15 \text{ K/W}$ )
- U. TRANSISTOR; power, switching ( $R_{th j-mb} \leq 15 \text{ K/W}$ )
- X. DIODE; multiplier, e.g. varactor, step recovery
- Y. DIODE; rectifying, booster
- Z. DIODE; voltage reference or regulator (transient suppressor diode, with third letter W)

## SERIAL NUMBER

Three figures, running from 100 to 999, for devices primarily intended for consumer equipment.\* One letter (Z, Y, X, etc.) and two figures, running from 10 to 99, for devices primarily intended for industrial/professional equipment.\*

This letter has no fixed meaning except W, which is used for transient suppressor diodes.

## VERSION LETTER

It indicates a minor variant of the basic type either electrically or mechanically. The letter never has a fixed meaning, except letter R, indicating reverse voltage, e.g. collector to case or anode to stud.

## SUFFIX

Sub-classification can be used for devices supplied in a wide range of variants called associated types. Following sub-coding suffixes are in use:

### 1. VOLTAGE REFERENCE and VOLTAGE REGULATOR DIODES: *ONE LETTER and ONE NUMBER*

The LETTER indicates the nominal tolerance of the Zener (regulation, working or reference) voltage

- A. 1% (according to IEC 63: series E96)
- B. 2% (according to IEC 63: series E48)
- C. 5% (according to IEC 63: series E24)
- D. 10% (according to IEC 63: series E12)
- E. 20% (according to IEC 63: series E6)

The number denotes the typical operating (Zener) voltage related to the nominal current rating for the whole range.

The letter 'V' is used instead of the decimal point.

### 2. TRANSIENT SUPPRESSOR DIODES: *ONE NUMBER*

The NUMBER indicates the maximum recommended continuous reversed (stand-off) voltage  $V_R$ . The letter 'V' is used as above.

### 3. CONVENTIONAL and CONTROLLED AVALANCHE RECTIFIER DIODES and THYRISTORS: *ONE NUMBER*

The NUMBER indicates the rated maximum repetitive peak reverse voltage ( $V_{RRM}$ ) or the rated repetitive peak off-state voltage ( $V_{DRM}$ ), whichever is the lower. Reversed polarity is indicated by letter R, immediately after the number.

### 4. RADIATION DETECTORS: *ONE NUMBER*, preceded by a hyphen (-)

The NUMBER indicates the depletion layer in  $\mu\text{m}$ . The resolution is indicated by a version LETTER.

### 5. ARRAY OF RADIATION DETECTORS and GENERATORS: *ONE NUMBER*, preceded by a stroke (/).

The NUMBER indicates how many basic devices are assembled into the array.

\* When these serial numbers are exhausted the serial number for consumer types may be extended to four figures, and that for industrial types to three figures.

## RATING SYSTEMS

The rating systems described are those recommended by the International Electrotechnical Commission (IEC) in its Publication 134.

### DEFINITIONS OF TERMS USED

*Electronic device.* An electronic tube or valve, transistor or other semiconductor device.

#### Note

This definition excludes inductors, capacitors, resistors and similar components.

*Characteristic.* A characteristic is an inherent and measurable property of a device. Such a property may be electrical, mechanical, thermal, hydraulic, electro-magnetic, or nuclear, and can be expressed as a value for stated or recognized conditions. A characteristic may also be a set of related values, usually shown in graphical form.

*Bogey electronic device.* An electronic device whose characteristics have the published nominal values for the type. A bogey electronic device for any particular application can be obtained by considering only those characteristics which are directly related to the application.

*Rating.* A value which establishes either a limiting capability or a limiting condition for an electronic device. It is determined for specified values of environment and operation, and may be stated in any suitable terms.

#### Note

Limiting conditions may be either maxima or minima.

*Rating system.* The set of principles upon which ratings are established and which determine their interpretation.

#### Note

The rating system indicates the division of responsibility between the device manufacturer and the circuit designer, with the object of ensuring that the working conditions do not exceed the ratings.

### ABSOLUTE MAXIMUM RATING SYSTEM

Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, which should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, equipment control adjustment, load variations, signal variation, environmental conditions, and variations in characteristics of the device under consideration and of all other electronic devices in the equipment.

## DESIGN MAXIMUM RATING SYSTEM

Design maximum ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking responsibility for the effects of changes in operating conditions due to variations in the characteristics of the electronic device under consideration.

The equipment manufacturer should design so that, initially and throughout life, no design maximum value for the intended service is exceeded with a bogey device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, variation in characteristics of all other devices in the equipment, equipment control adjustment, load variation, signal variation and environmental conditions.

## DESIGN CENTRE RATING SYSTEM

Design centre ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under normal conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device in average applications, taking responsibility for normal changes in operating conditions due to rated supply voltage variation, equipment component variation, equipment control adjustment, load variation, signal variation, environmental conditions, and variations in the characteristics of all electronic devices.

The equipment manufacturer should design so that, initially, no design centre value for the intended service is exceeded with a bogey electronic device in equipment operating at the stated normal supply voltage.

## LETTER SYMBOLS FOR TRANSISTORS AND SIGNAL DIODES

based on IEC Publication 148

## LETTER SYMBOLS FOR CURRENTS, VOLTAGES AND POWERS

**Basic letters**

The basic letters to be used are:

I, i = current  
 V, v = voltage  
 P, p = power.

Lower-case basic letters shall be used for the representation of instantaneous values which vary with time.

In all other instances upper-case basic letters shall be used.

**Subscripts**

A, a	Anode terminal
(AV), (av)	Average value
B, b	Base terminal, for MOS devices; Substrate
(BR)	Breakdown
C, c	Collector terminal
D, d	Drain terminal
E, e	Emitter terminal
F, f	Forward
G, g	Gate terminal
K, k	Cathode terminal
M, m	Peak value
O, o	As third subscript: The terminal not mentioned is open circuited
R, r	As first subscript: Reverse. As second subscript: Repetitive. As third subscript: With a specified resistance between the terminal not mentioned and the reference terminal.
(RMS), (rms)	Root-mean-square value
S, s	{ As first or second subscript: Source terminal (for FETS only) As second subscript: Non-repetitive (not for FETS) As third subscript: Short circuit between the terminal not mentioned and the reference terminal
X, x	Specified circuit
Z, z	Replaces R to indicate the actual working voltage, current or power of voltage reference and voltage regulator diodes.

Note: No additional subscript is used for DC values.

Upper-case subscripts shall be used for the indication of:

- a) continuous (DC) values (without signal)  
Example  $I_B$
- b) instantaneous total values  
Example  $i_B$
- c) average total values  
Example  $I_{B(AV)}$
- d) peak total values  
Example  $I_{BM}$
- e) root-mean-square total values  
Example  $I_{B(RMS)}$

Lower-case subscripts shall be used for the indication of values applying to the varying component alone :

- a) instantaneous values  
Example  $i_b$
- b) root-mean-square values  
Example  $I_b(rms)$
- c) peak values  
Example  $I_{bm}$
- d) average values  
Example  $I_{b(av)}$

Note : If more than one subscript is used, subscript for which both styles exist shall either be all upper-case or all lower-case.

## **Additional rules for subscripts**

### Subscripts for currents

Transistors : If it is necessary to indicate the terminal carrying the current, this should be done by the first subscript (conventional current flow from the external circuit into the terminal is positive).

Examples :  $I_B$ ,  $i_B$ ,  $i_b$ ,  $I_{bm}$

Diodes : To indicate a forward current (conventional current flow into the anode terminal) the subscript F or f should be used; for a reverse current (conventional current flow out of the anode terminal) the subscript R or r should be used.

Examples :  $I_F$ ,  $I_R$ ,  $i_F$ ,  $I_f(rms)$



Subscripts for voltages

**Transistors:** If it is necessary to indicate the points between which a voltage is measured, this should be done by the first two subscripts. The first subscript indicates the terminal at which the voltage is measured and the second the reference terminal or the circuit node. Where there is no possibility of confusion, the second subscript may be omitted.

Examples:  $V_{BE}$ ,  $v_{BE}$ ,  $v_{be}$ ,  $V_{bem}$

**Diodes:** To indicate a forward voltage (anode positive with respect to cathode), the subscript F or f should be used; for a reverse voltage (anode negative with respect to cathode) the subscript R or r should be used.

Examples:  $V_F$ ,  $V_R$ ,  $v_F$ ,  $V_{rm}$

Subscripts for supply voltages or supply currents

Supply voltages or supply currents shall be indicated by repeating the appropriate terminal subscript.

Examples:  $V_{CC}$ ,  $I_{EE}$

Note: If it is necessary to indicate a reference terminal, this should be done by a third subscript

Example:  $V_{CCE}$

Subscripts for devices having more than one terminal of the same kind

If a device has more than one terminal of the same kind, the subscript is formed by the appropriate letter for the terminal followed by a number; in the case of multiple subscripts, hyphens may be necessary to avoid misunderstanding.

Examples:  $I_{B2}$  = continuous (DC) current flowing into the second base terminal

$V_{B2-E}$  = continuous (DC) voltage between the terminals of second base and emitter

Subscripts for multiple devices

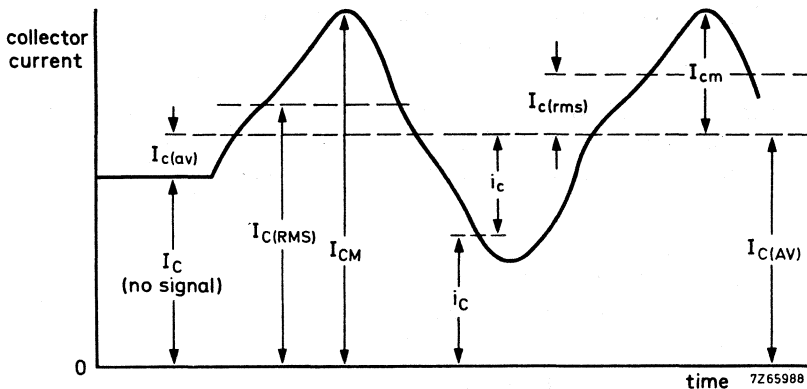
For multiple unit devices, the subscripts are modified by a number preceding the letter subscript; in the case of multiple subscripts, hyphens may be necessary to avoid misunderstanding.

Examples:  $I_{2C}$  = continuous (DC) current flowing into the collector terminal of the second unit

$V_{1C-2C}$  = continuous (DC) voltage between the collector terminals of the first and the second unit.

## Application of the rules

The figure below represents a transistor collector current as a function of time. It consists of a continuous (DC) current and a varying component.



## LETTER SYMBOLS FOR ELECTRICAL PARAMETERS

### Definition

For the purpose of this Publication, the term "electrical parameter" applies to four-pole matrix parameters, elements of electrical equivalent circuits, electrical impedances and admittances, inductances and capacitances.

### Basic letters

The following is a list of the most important basic letters used for electrical parameters of semiconductor devices.

- B, b = susceptance; imaginary part of an admittance
- C = capacitance
- G, g = conductance; real part of an admittance
- H, h = hybrid parameter
- L = inductance
- R, r = resistance; real part of an impedance
- X, x = reactance; imaginary part of an impedance
- Y, y = admittance;
- Z, z = impedance;

Upper-case letters shall be used for the representation of:

- a) electrical parameters of external circuits and of circuits in which the device forms only a part;
- b) all inductances and capacitances.

Lower-case letters shall be used for the representation of electrical parameters inherent in the device (with the exception of inductances and capacitances).

### Subscripts

#### General subscripts

The following is a list of the most important general subscripts used for electrical parameters of semiconductor devices:

F, f	= forward; forward transfer
I, i (or 1)	= input
L, l	= load
O, o (or 2)	= output
R, r	= reverse; reverse transfer
S, s	= source

Examples:  $Z_S$ ,  $h_f$ ,  $h_F$

The upper-case variant of a subscript shall be used for the designation of static (d.c.) values.

Examples :  $h_{FE}$  = static value of forward current transfer ratio in common-emitter configuration (DC current gain)

$R_E$  = DC value of the external emitter resistance

Note: The static value is the slope of the line from the origin to the operating point on the appropriate characteristic curve, i.e. the quotient of the appropriate electrical quantities at the operating point.

The lower-case variant of a subscript shall be used for the designation of small-signal values.

Examples:  $h_{fe}$  = small-signal value of the short-circuit forward current transfer ratio in common-emitter configuration

$Z_e = R_e + jX_e$  = small-signal value of the external impedance

Note: If more than one subscript is used, subscripts for which both styles exist shall either be all upper-case or all lower-case

Examples:  $h_{FE}$ ,  $y_{RE}$ ,  $h_{fe}$

## Subscripts for four-pole matrix parameters

The first letter subscript (or double numeric subscript) indicates input, output, forward transfer or reverse transfer

Examples:  $h_i$  (or  $h_{11}$ )  
 $h_o$  (or  $h_{22}$ )  
 $h_f$  (or  $h_{21}$ )  
 $h_r$  (or  $h_{12}$ )

A further subscript is used for the identification of the circuit configuration. When no confusion is possible, this further subscript may be omitted.

Examples:  $h_{fe}$  (or  $h_{21e}$ ),  $h_{FE}$  (or  $h_{21E}$ )

### **Distinction between real and imaginary parts**

If it is necessary to distinguish between real and imaginary parts of electrical parameters, no additional subscripts should be used. If basic symbols for the real and imaginary parts exist, these may be used.

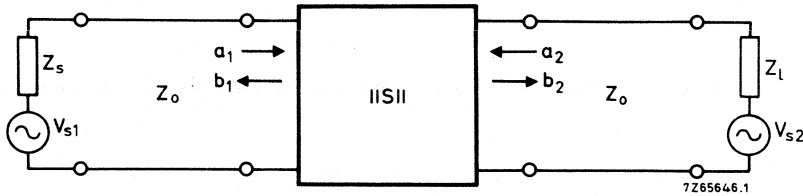
Examples:  $Z_i = R_i + jX_i$   
 $y_{fe} = g_{fe} + jb_{fe}$

If such symbols do not exist or if they are not suitable, the following notation shall be used:

Examples:  $\text{Re}(h_{ib})$  etc. for the real part of  $h_{ib}$   
 $\text{Im}(h_{ib})$  etc. for the imaginary part of  $h_{ib}$

## SCATTERING PARAMETERS

In distinction to the conventional h, y and z-parameters, s-parameters relate to traveling wave conditions. The figure below shows a two-port network with the incident and reflected waves  $a_1$ ,  $b_1$ ,  $a_2$  and  $b_2$ .



$$a_1 = \frac{V_{i1}}{\sqrt{Z_o}}$$

$$a_2 = \frac{V_{i2}}{\sqrt{Z_o}}$$

1)

$$b_1 = \frac{V_{r1}}{\sqrt{Z_o}}$$

$$b_2 = \frac{V_{r2}}{\sqrt{Z_o}}$$

$Z_o$  = characteristic impedance of the transmission line in which the two-port is connected.

$V_i$  = incident voltage

$V_r$  = reflected (generated) voltage

The four-pole equations for s-parameters are:

$$b_1 = s_{11}a_1 + s_{12}a_2$$

$$b_2 = s_{21}a_1 + s_{22}a_2$$

Using the subscripts i for 11, r for 12, f for 21 and o for 22, it follows that:

$$s_i = s_{11} = \left. \frac{b_1}{a_1} \right|_{a_2 = 0}$$

$$s_r = s_{12} = \left. \frac{b_1}{a_2} \right|_{a_1 = 0}$$

$$s_f = s_{21} = \left. \frac{b_2}{a_1} \right|_{a_2 = 0}$$

$$s_o = s_{22} = \left. \frac{b_2}{a_2} \right|_{a_1 = 0}$$

<sup>1)</sup> The squares of these quantities have the dimension of power.

## S-PARAMETERS

The s-parameters can be named and expressed as follows:

$s_i = s_{11}$  = Input reflection coefficient.

The complex ratio of the reflected wave and the incident wave at the input, under the conditions  $Z_1 = Z_0 = 50 \Omega$  and  $V_{s2} = 0$ .

$s_r = s_{12}$  = Reverse transmission coefficient.

The complex ratio of the generated wave at the input and the incident wave at the output, under the conditions  $Z_s = Z_0 = 50 \Omega$  and  $V_{s1} = 0$ .

$s_f = s_{21}$  = Forward transmission coefficient.

The complex ratio of the generated wave at the output and the incident wave at the input, under the conditions  $Z_1 = Z_0 = 50 \Omega$  and  $V_{s2} = 0$ .

$s_o = s_{22}$  = Output reflection coefficient.

The complex ratio of the reflected wave and the incident wave at the output, under the conditions  $Z_s = Z_0 = 50 \Omega$  and  $V_{s1} = 0$ .

## RF power modules

## Mounting recommendations

### RECOMMENDATIONS FOR MOUNTING OF RF POWER MODULES

The modules are manufactured using a ceramic substrate soldered to a copper flange; this causes a small thermal mismatch between these two components. A further thermal mismatch will exist between the module flange and the heatsink to which it is mounted. Because of these mismatches, precautions must be taken to avoid unnecessary mechanical stresses being applied to the ceramic substrate and other components within the module resulting from variations in temperature during operating cycles.

#### Design of heatsink

To ensure that the maximum specified flange temperature will not be exceeded under maximum fault conditions, the module should always be mounted on a heatsink of suitable thermal resistance.

The mounting area of the heatsink should be flat and free from burrs. Particular attention should be paid to the mounting hole areas. The maximum amount of bowing along the plane of the module should not exceed 0.1 mm. Where anodizing is used, the area under the module should be milled clean as the presence of anodizing under the module can result in high resistance earth paths, leading to oscillation and early failure, in addition to poor thermal contact.

The heatsink should be rigid and not prone to bowing under thermal cycling conditions. The thickness of a solid heatsink should not be less than 5 mm, to ensure a rigid assembly. On finned heatsinks, the module should be mounted along a plane parallel to the fins.

#### Mounting of module

To ensure a good thermal contact and to prevent mechanical stresses when bolted down, the flatness of the module flange is designed to be typically better than 0.02 mm.

The module should be mounted to the heatsink using 3 mm bolts with flat washers, tightened to a maximum torque of 0.5 Nm. Over-tightening can result in bowing of the flange. Locking washers should not be used.

A thin, even layer of thermal compound should be used between the module and the heatsink to achieve the best possible contact thermal resistance, which should be in the order of 0.2 K/W. Excessive use of thermal compound will result in an increase in thermal resistance

and possible bowing of the flange; too little will result in poor thermal resistance.

#### Electrical connections

The main earth return path of all modules is via the flange; it is therefore important that the heatsink is well earthed and that return paths are kept as short as possible. Failure to ensure this may result in loss of output power or oscillation, which in turn will have a detrimental effect on the module life.

The RF output connection should be to correctly designed 50  $\Omega$  terminations. Failure to do this will result in a mismatch being presented to the module, with a resulting reduction in module life.

#### CAUTION

Under no circumstances must the maximum specified operating or storage temperatures be exceeded, even for short periods.





## MODULE DATA



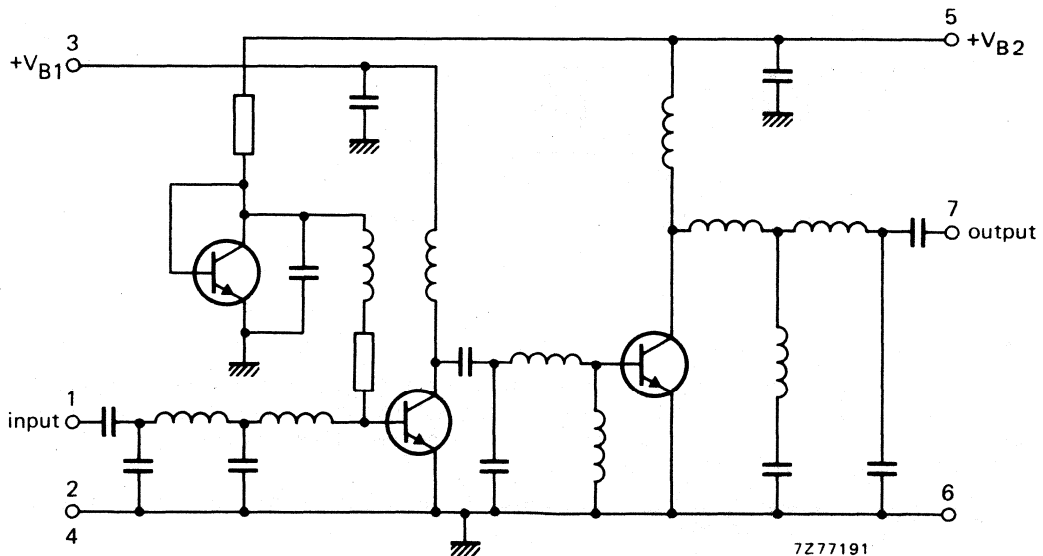
## VHF POWER AMPLIFIER MODULES

A range of broadband amplifier modules designed for mobile communications equipments, operating directly from 12 V vehicle electrical systems. The devices will produce 18 W output into a 50 Ω load. The modules consist of a two stage RF amplifier using npn transistor chips, together with lumped-element matching components.

### QUICK REFERENCE DATA

type number	mode of operation	frequency range f (MHz)	nominal supply voltages $V_{B1} = V_{B2}$ (V)	drive power $P_D$ (mW)	load power $P_L$ (W)	nominal input impedance $z_i$ (Ω)	nominal load impedance $Z_L$ (Ω)
BGY32	cw	68 to 88	12.5	100	> 18 typ 23	50	50
BGY33	cw	80 to 108	12.5	100	> 18 typ 22	50	50
BGY35	cw	132 to 156	12.5	150	> 18 typ 22	50	50
BGY36	cw	148 to 174	12.5	150	> 18 typ 21	50	50

### CIRCUIT DIAGRAM

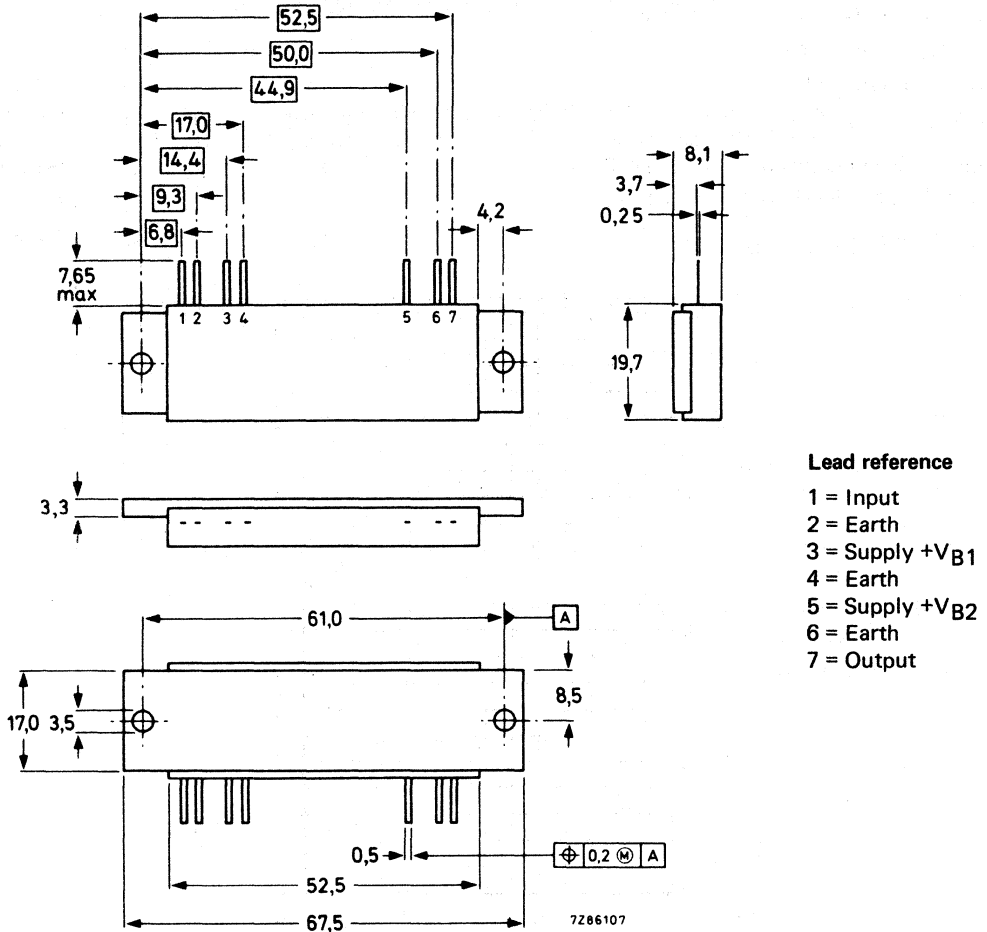


**PRODUCT SAFETY** This device incorporates beryllium oxide, the dust of which is toxic. The device is entirely safe provided that the BeO disc is not damaged.

**MECHANICAL DATA**

Fig. 1 SOT132B.

Dimensions in mm



**Mounting and soldering recommendations**

To ensure good thermal transfer the module should be mounted using heatsink compound onto a heatsink with a flat surface; if an isolation washer is used heatsink compound should be used on both sides of the insulator. Burrs and thickening of the holes in the heatsink should be removed and 3 mm bolts tightened to torques of 0,5 Nm minimum.

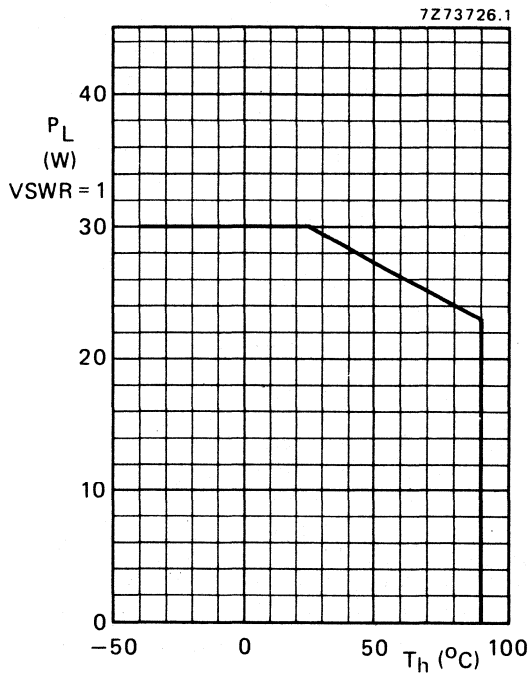
Devices may be soldered directly into a circuit with a soldering iron at maximum iron temperature of 245 °C for 10 seconds at least 1 mm from the plastic.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**DC voltages (with respect to flange)**

DC supply terminals	$V_{B1}$ and $V_{B2}$	max	15 V
RF input terminal	$\pm V_I$	max	25 V
RF output terminal	$\pm V_O$	max	25 V
Input drive power BGY32 and BGY33	$P_D$	max	200 mW
Input drive power BGY35 and BGY36	$P_D$	max	300 mW
Load power	$P_L$	max	30 W



Storage temperature range	$T_{stg}$	-40 to 100 °C
Operating heatsink temperature	$T_h$	max 90 °C

**CHARACTERISTICS**

$T_h = 25\text{ }^\circ\text{C}$

**Quiescent current**

$V_{B1} = V_{B2} = 12.5\text{ V}; P_D = 0;$

$R_S = R_L = 50\ \Omega$

		BGY32	BGY33	BGY35	BGY36
$I_{BQ1}$	typ	6	6	6	6 mA
$I_{BQ2}$	typ	13	13	13	13 mA
Frequency range	$f >$	68	80	132	148 MHz
	$f <$	88	108	156	174 MHz
Load power	$P_L >$	18	18	—	— W
		typ	23	22	—
	$\eta >$	40	40	—	— %
		typ	50	50	—
BGY35 and BGY36; $P_D = 150\text{ mW}$	$P_L >$	—	—	18	18 W
		typ	—	22	21 W
	$\eta >$	—	—	40	40 %
		typ	—	50	50 %

**Frequency range**

**Load power**

$V_{B1} = V_{B2} = 12.5\text{ V}; R_S = R_L = 50\ \Omega$

BGY32 and BGY33;  $P_D = 100\text{ mW}$

BGY35 and BGY36;  $P_D = 150\text{ mW}$

Any single harmonic will be at least 25 dB down relative to carrier

**Harmonic output**

**Input VSWR with respect to  $50\ \Omega$**

typ

1,5

**Stability**

The module is stable with a load VSWR up to 3 : 1 (all phases) when operated within the following conditions:  $V_{S1} = 6\text{ to }15\text{ V}; V_{S2} = 10\text{ to }15\text{ V}; V_{S1} \leq V_{S2}; P_D = 50\text{ to }200\text{ mW};$  frequency within operating frequency range, provided the maximum ratings of the module are not exceeded.

**Ruggedness**

The modules are capable of withstanding load mismatch of up to 50 VSWR for short period overload conditions, with  $P_D, V_{B1}$  and  $V_{B2}$  at maximum values providing the combination does not result in the matched RF output power rating being exceeded.

**APPLICATION INFORMATION**

**Supply**

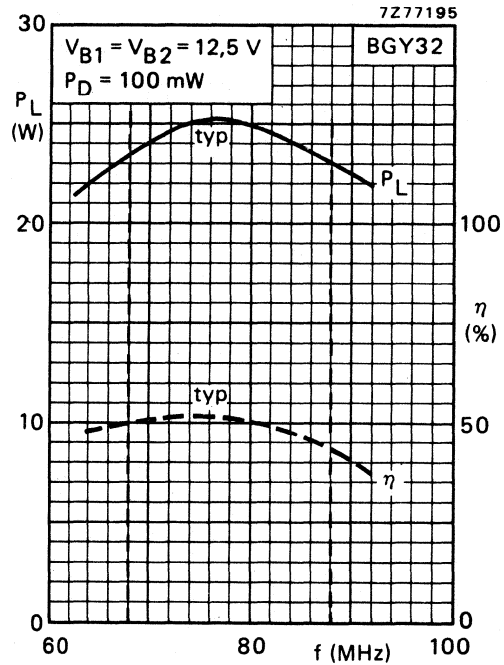
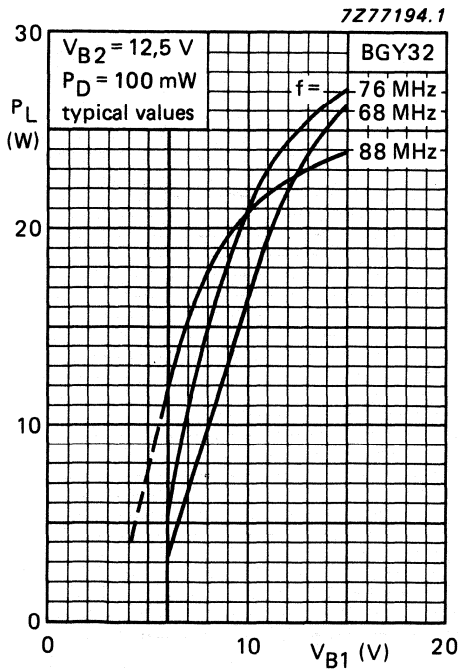
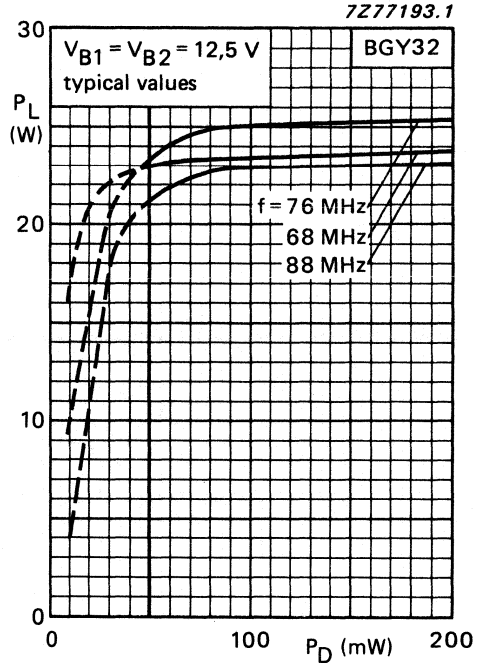
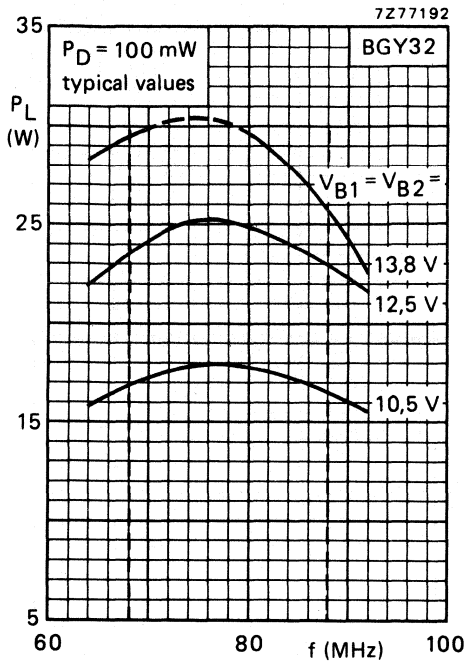
An electrolytic capacitor of  $10\ \mu\text{F}$  (25 V), in parallel with a polyester capacitor of  $100\text{ nF}$  to earth, is recommended as decoupling arrangement for each power supply pin.

**Power rating**

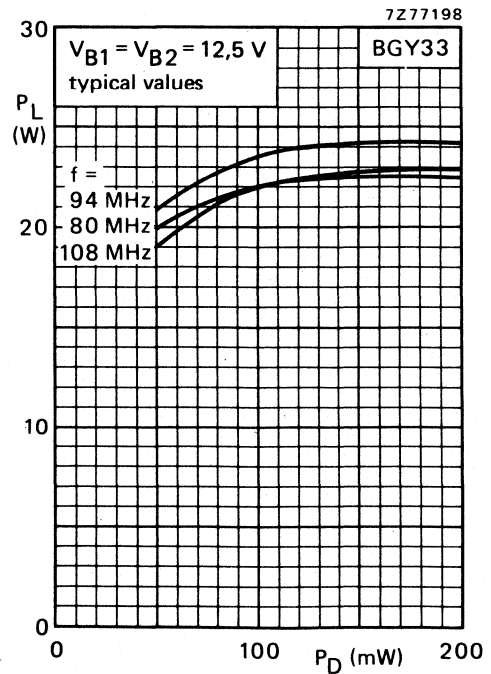
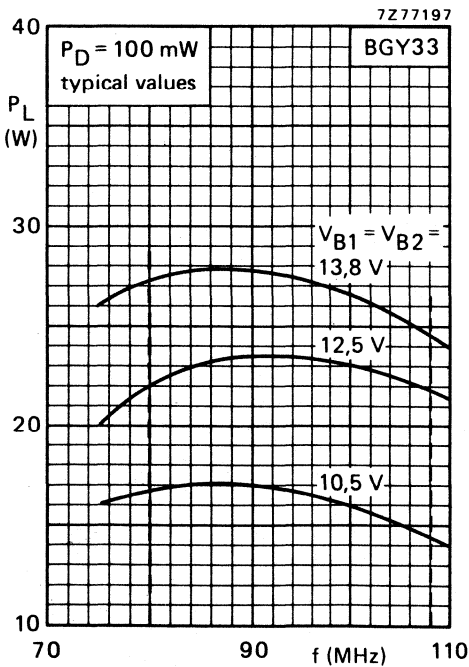
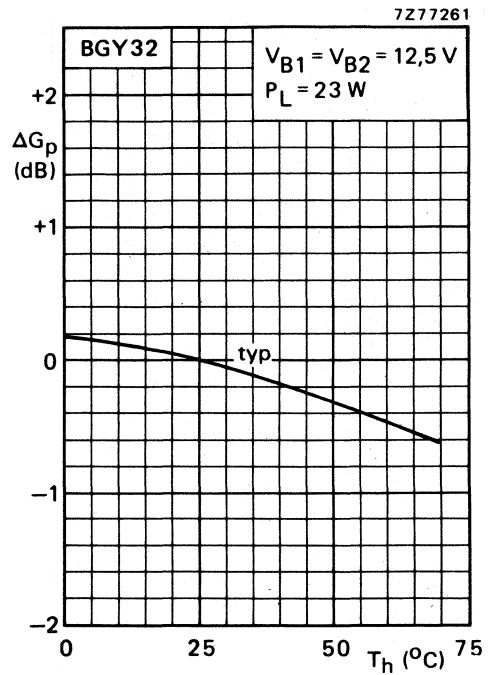
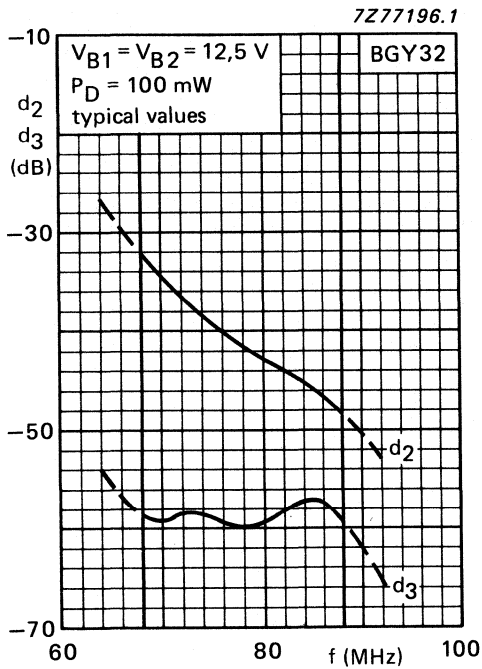
In general it is recommended that the output power from the module under nominal design conditions should not exceed 23 W in order to provide adequate safety margin under fault conditions.

**Output power control**

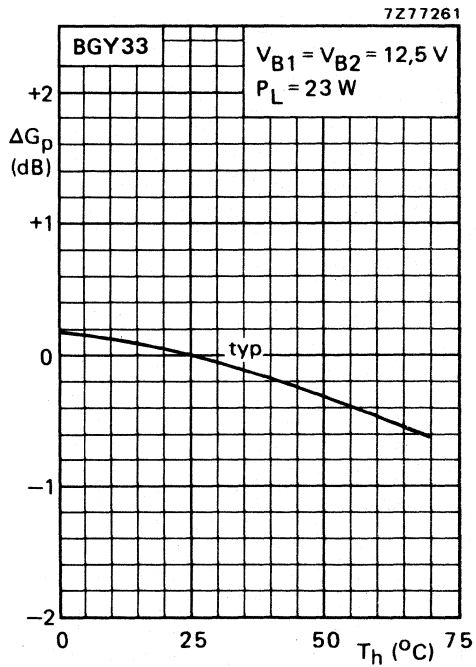
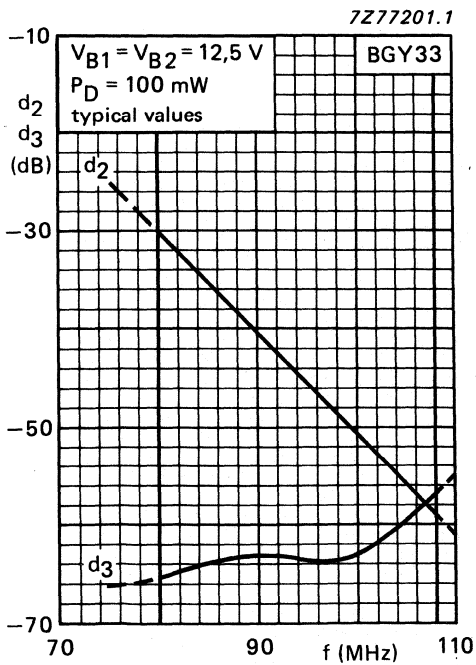
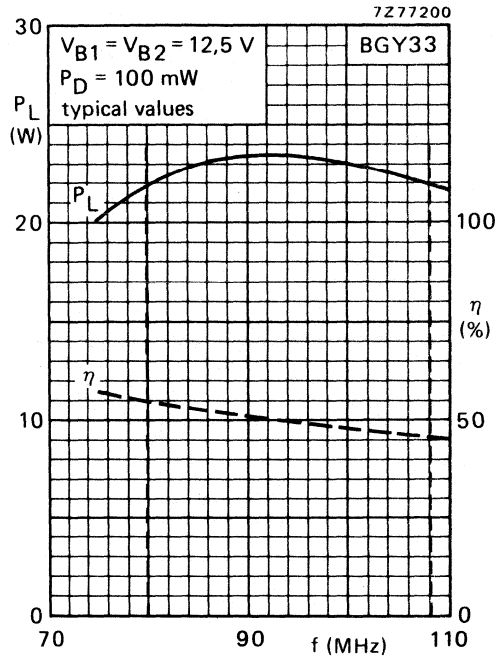
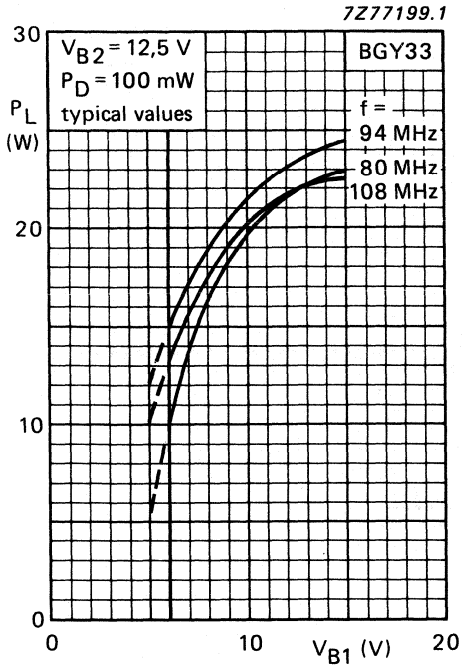
The module is not designed to be operated over a large range of output power levels. The purpose of the output power control is to set the nominal output power level. The preferred method of output power control is by varying the drive power between 50 and 200 mW. The next option is by varying  $V_{S1}$  between 6 and 12.5 V.

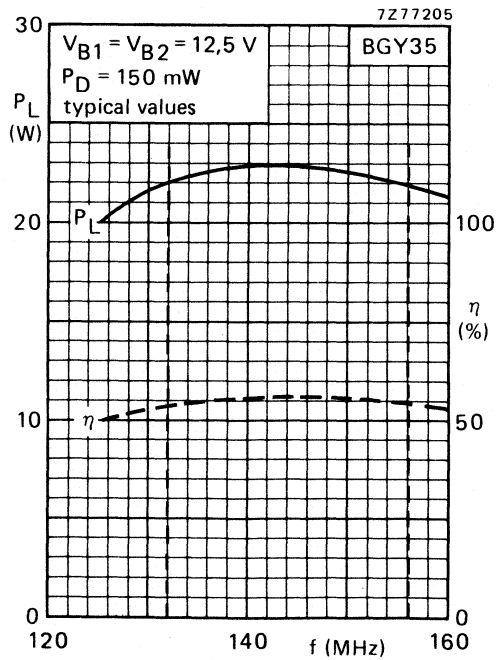
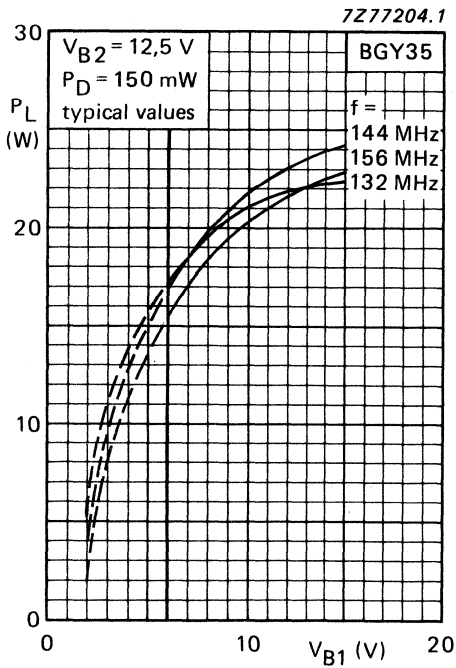
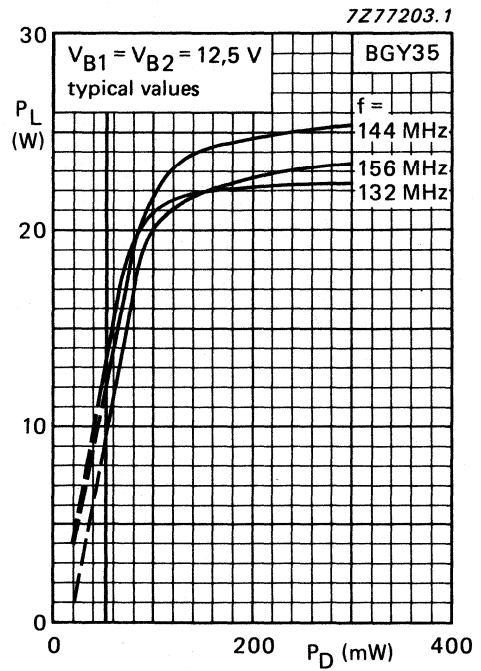
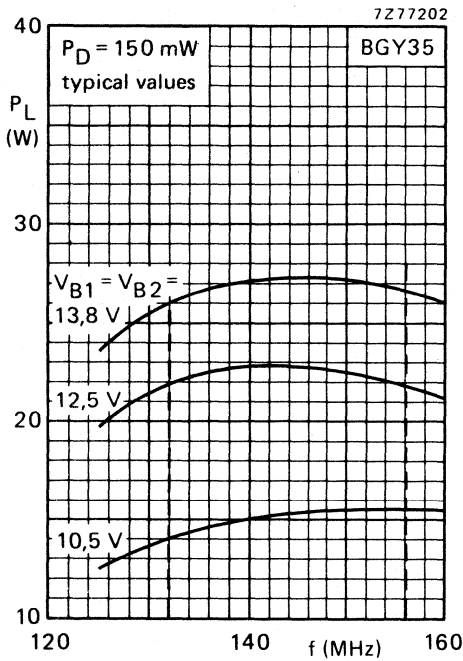


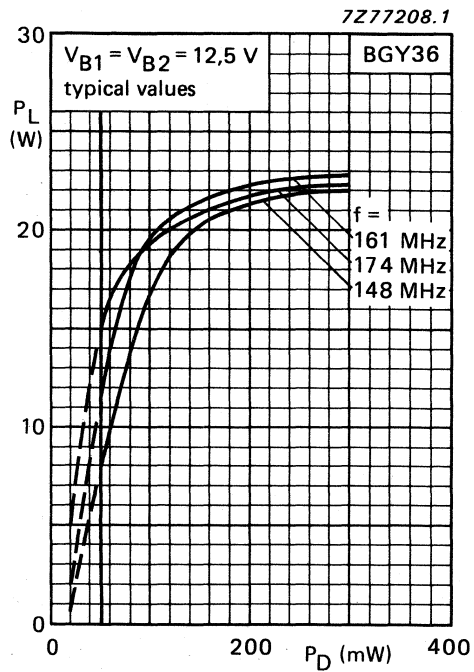
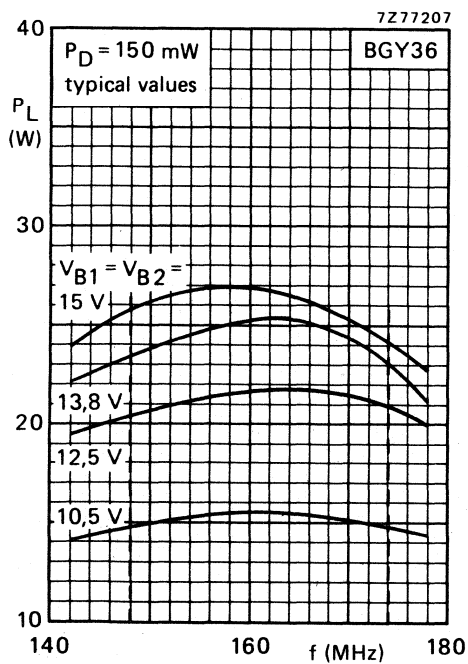
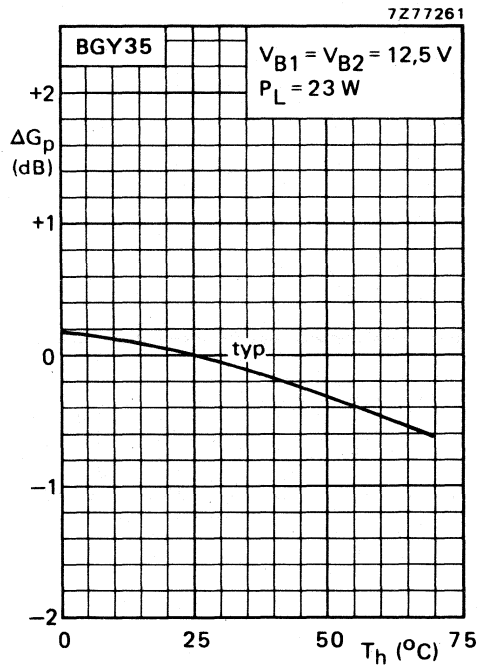
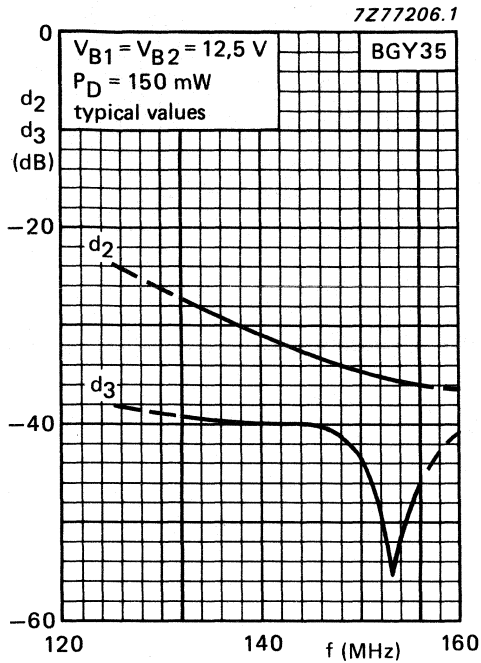
BGY32 BGY33  
BGY35 BGY36

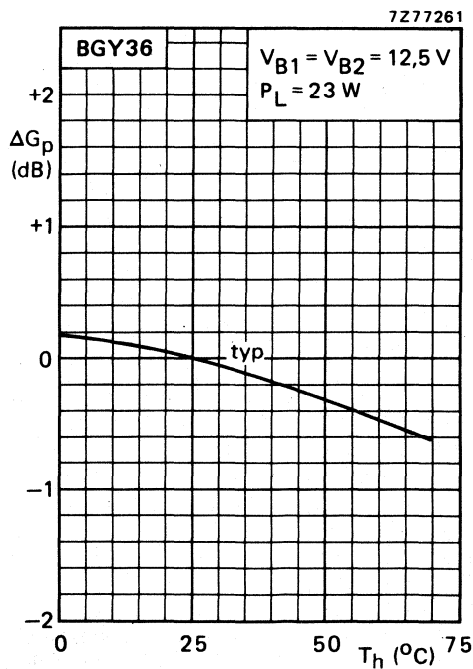
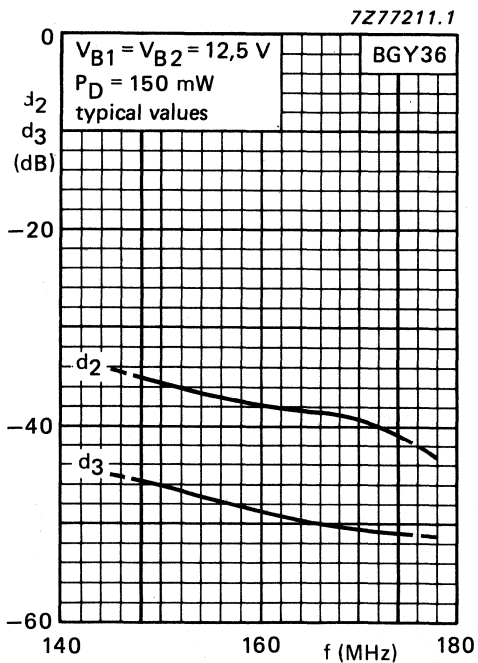
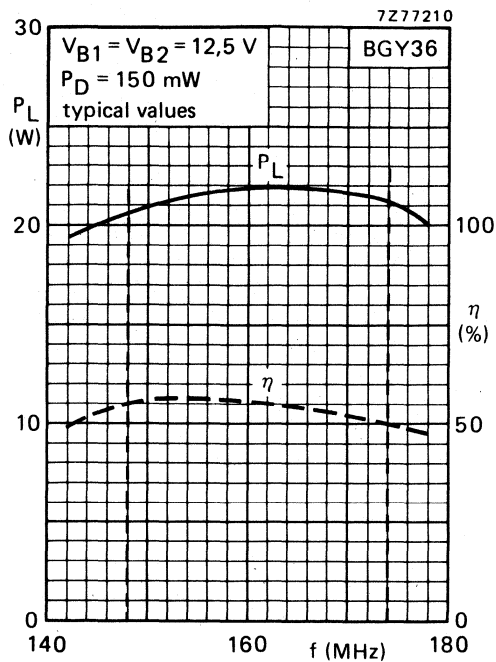
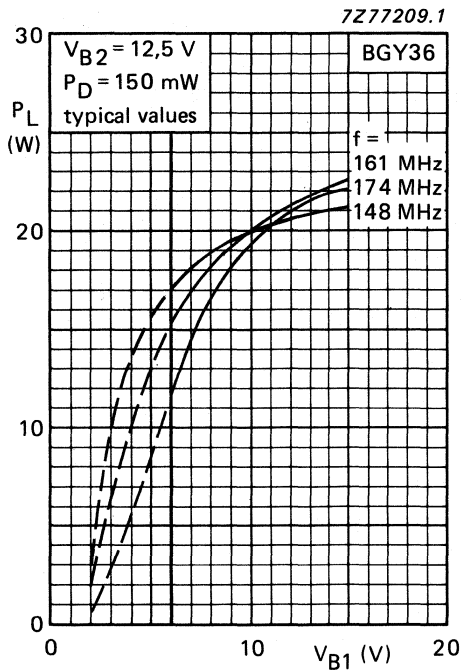












## VHF POWER AMPLIFIER MODULE

A broadband VHF amplifier module primarily designed for mobile communications equipment, operating directly from 12 V electrical systems. The module will produce a minimum output of 13 W into a 50 Ω load over the frequency range 148 to 174 MHz.

The module consists of a two stage RF amplifier using npn transistor chips with lumped-element matching components in a plastic stripline encapsulation. The negative supply is internally connected to the flange.

### QUICK REFERENCE DATA

Mode of operation			c.w.	
Frequency range	f		148 to 174	MHz
Drive power	$P_D$	max.	150	mW
	$P_D$	typ.	80	mW
Load power	$P_L$	>	13	W
Supply voltages	$V_{S1}$ and $V_{S2}$	nom.	12.5	V
Input impedance	$z_i$	nom.	50	Ω
Output load impedance	$Z_L$	nom.	50	Ω

### MECHANICAL DATA (see Fig. 10)

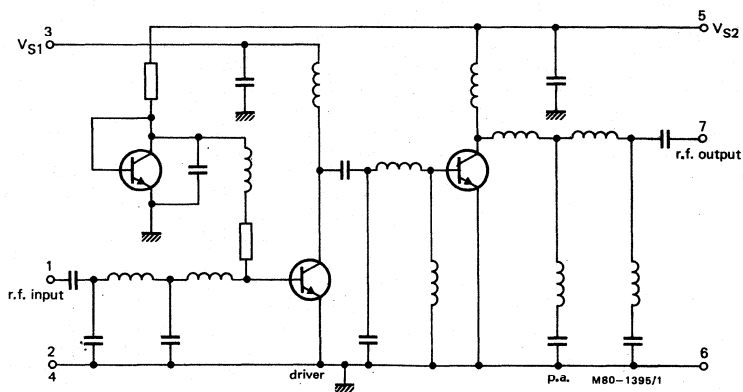


Fig. 1 Circuit of the VHF module.

**PRODUCT SAFETY** This device incorporates beryllium oxide, the dust of which is toxic. The device is entirely safe provided that the BeO disc is not damaged.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC134)

**Voltages** (with respect to flange)

DC supply terminals	$V_{S1}$ and $V_{S2}$	max.	16.5	V
RF input terminal	$\pm V_i$	max.	25	V
RF output terminal	$\pm V_o$	max.	25	V
Load power (see below)	$P_L$	max.	18	W
Input drive power	$P_D$	max.	300	mW
Storage temperature range	$T_{stg}$		-40 to +100	°C
Operating heatsink temperature	$T_h$	max.	90	°C

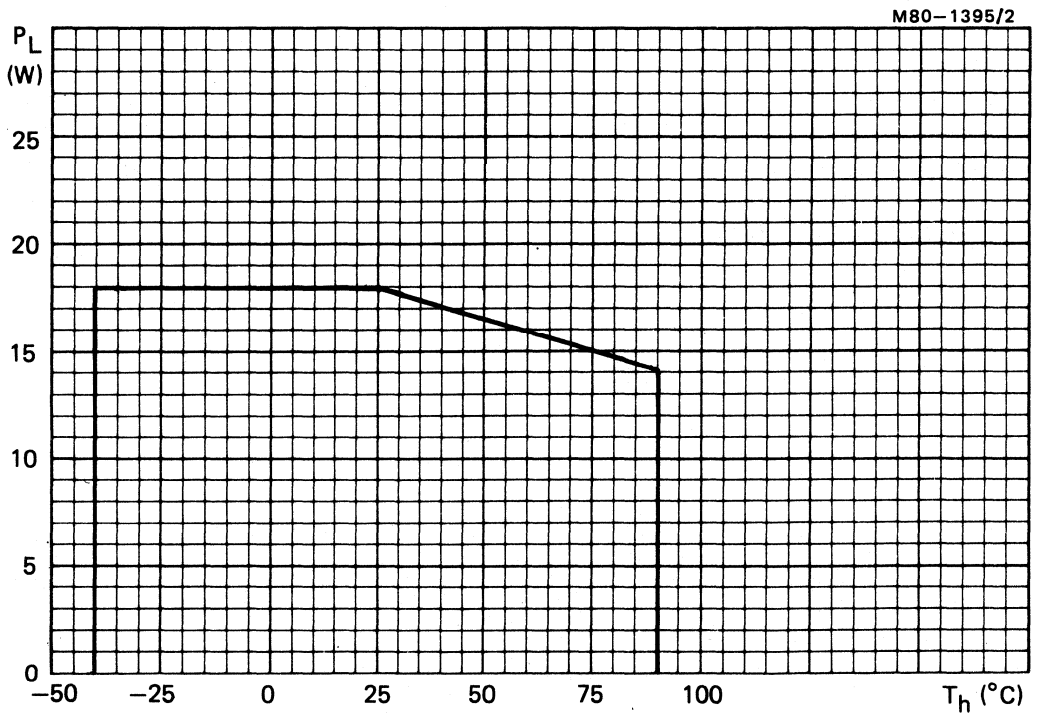


Fig.2 Load power derating; VSWR = 1

**CHARACTERISTICS**

$T_h = 25\text{ }^\circ\text{C}$  unless otherwise specified

$V_{S1} = V_{S2} = 12.5\text{ V}$ ;  $R_S = 50\ \Omega$ ; frequency range 148 to 174 MHz;  $R_L = 50\ \Omega$

**Quiescent currents**

$P_D = 0$	$I_{Q1}$	typ.	5	mA
	$I_{Q2}$	typ.	15	mA

**RF drive power**

$P_L = 13\text{ W}$	$P_D$	<	150	mW
	$P_D$	typ.	80	mW

**Efficiency**

$P_L = 13\text{ W}$	$\eta$	>	40	%
	$\eta$	typ.	48	%

**Harmonic output**

Any single harmonic will be at least 25 dB down from the carrier, with typical rejection of 34 dB.

**Input VSWR (with respect to 50  $\Omega$ )**

typ. 1.5

**Stability**

The module is stable with load VSWR up to 3 (all phases) when operated with:

$V_{S1} = V_{S2} = 10$  to 16.5 V;  $f = 148$  to 174 MHz;  $P_D = 30$  to 300 mW;  $P_L \leq 18\text{ W}$  (matched)

**Ruggedness**

The modules will withstand load VSWR of 50 for short period overload conditions, with  $P_D$ ,  $V_{S1}$  and  $V_{S2}$  at maximum values, providing the combination does not result in the matched RF output power rating being exceeded.

**Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface, with heat conducting compound between module and heatsink. If an isolation washer is used, heatsink compound should be applied to both sides of the washer. Burrs and thickening of the holes in the heatsink should be removed and 3 mm bolts tightened to a torque of 0.5 Nm.

Devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245  $^\circ\text{C}$  for not more than 10 seconds at a distance of at least 1 mm from the plastic.

**APPLICATION INFORMATION**

A technical publication (M80-0056) entitled 'Transmitter design using VHF broadband amplifier modules' is available on request.

**Power rating**

In general it is recommended that the output power from the module under nominal conditions should not exceed 16 W in order to provide adequate safety margin under fault conditions.

**Output power control**

The module is not designed to be operated over a large range of output power levels. The purpose of the output power control is to set the nominal output power level. The preferred method of output power control is by varying the drive power between 30 and 200 mW. The next option is by varying  $V_{S1}$  between 6 and 12.5 V.

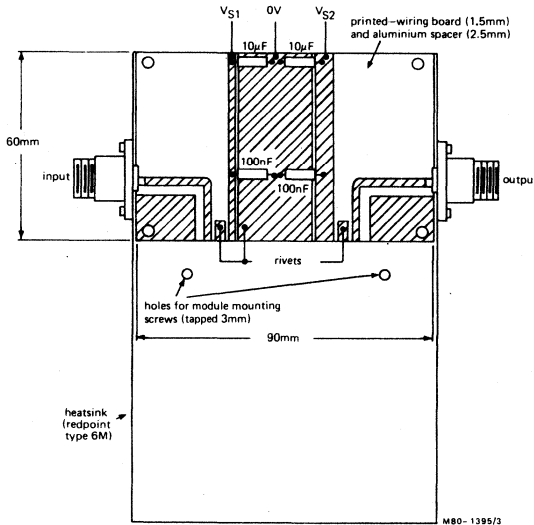


Fig.3 Test jig for VHF modules

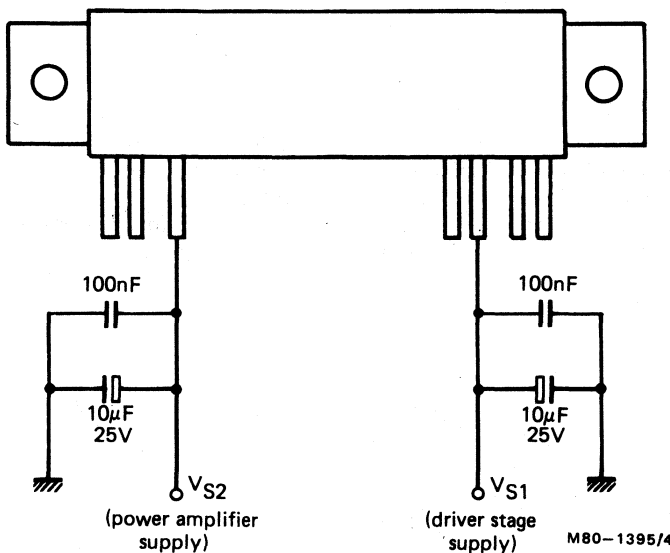


Fig.4 Recommended decoupling arrangement



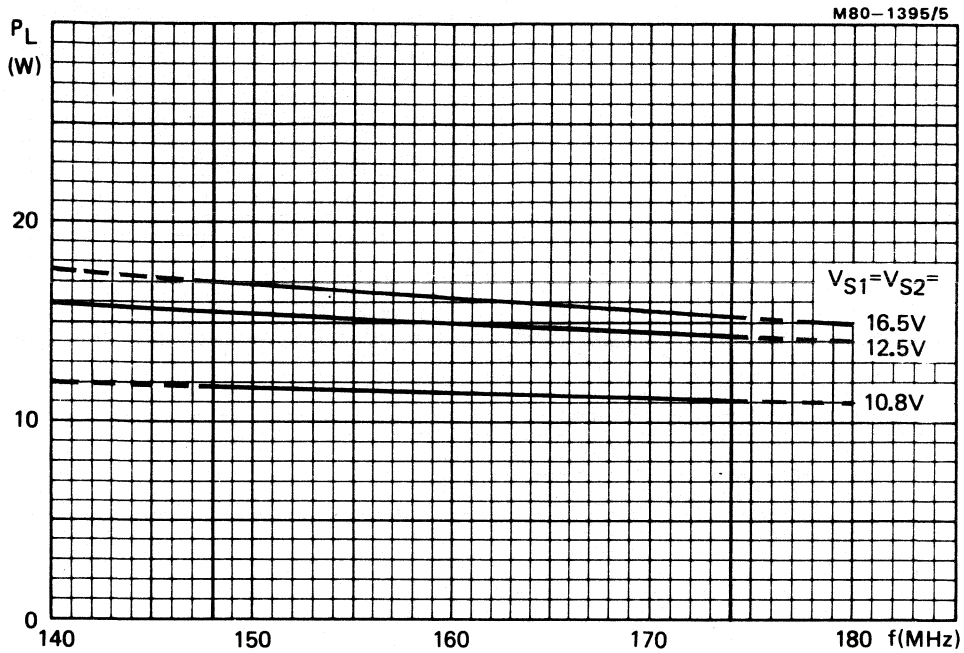


Fig.5 Typical values;  $P_D = 150$  mW

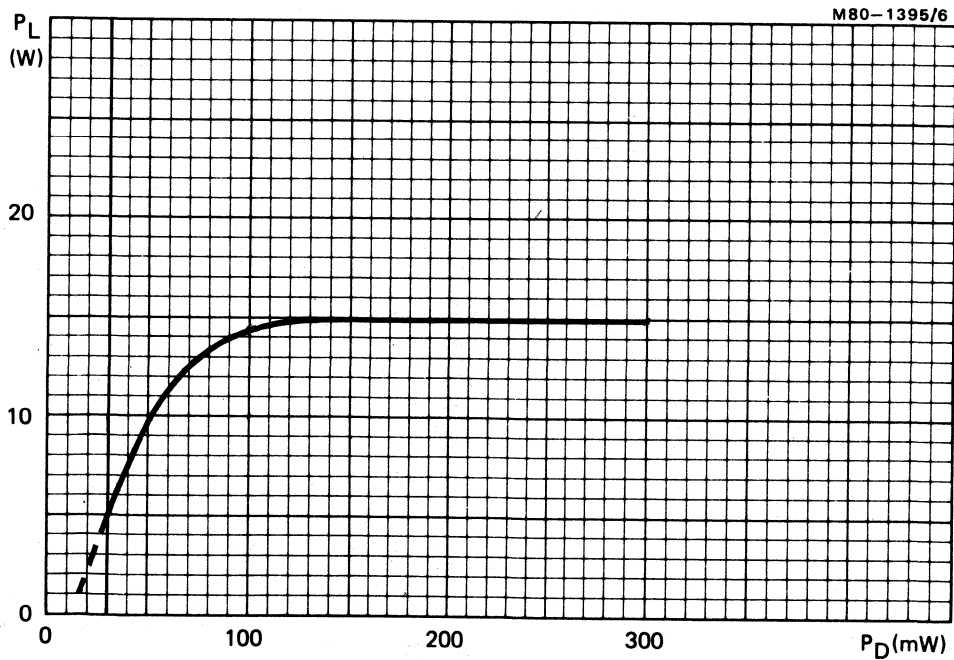


Fig.6 Typical values;  $V_{S1} = V_{S2} = 12.5$  V;  $f = 160$  MHz

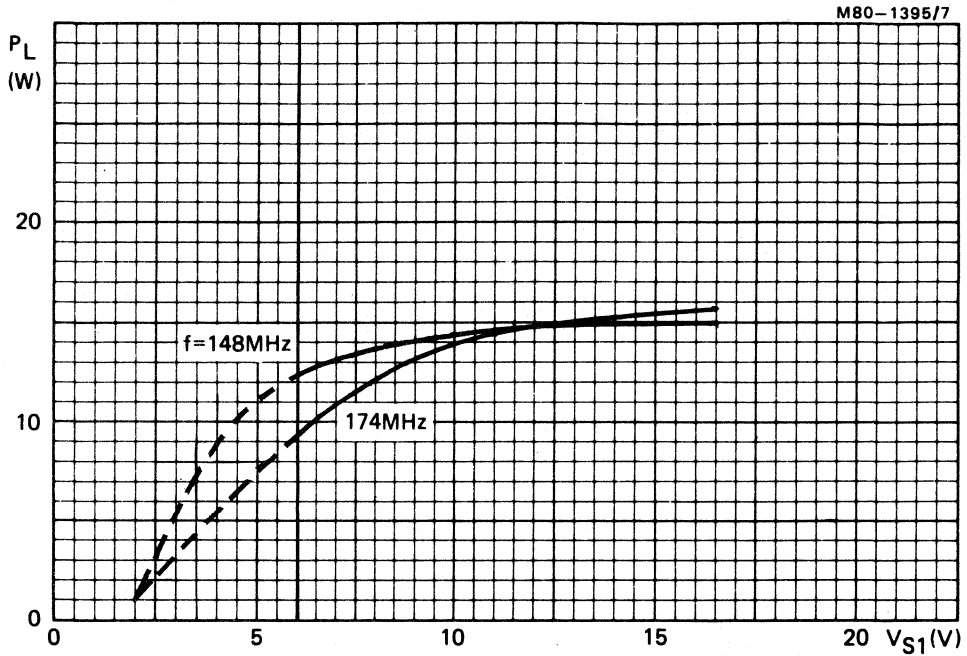


Fig.7 Typical values;  $V_{S2} = 12.5$  V;  $P_D = 150$  mW

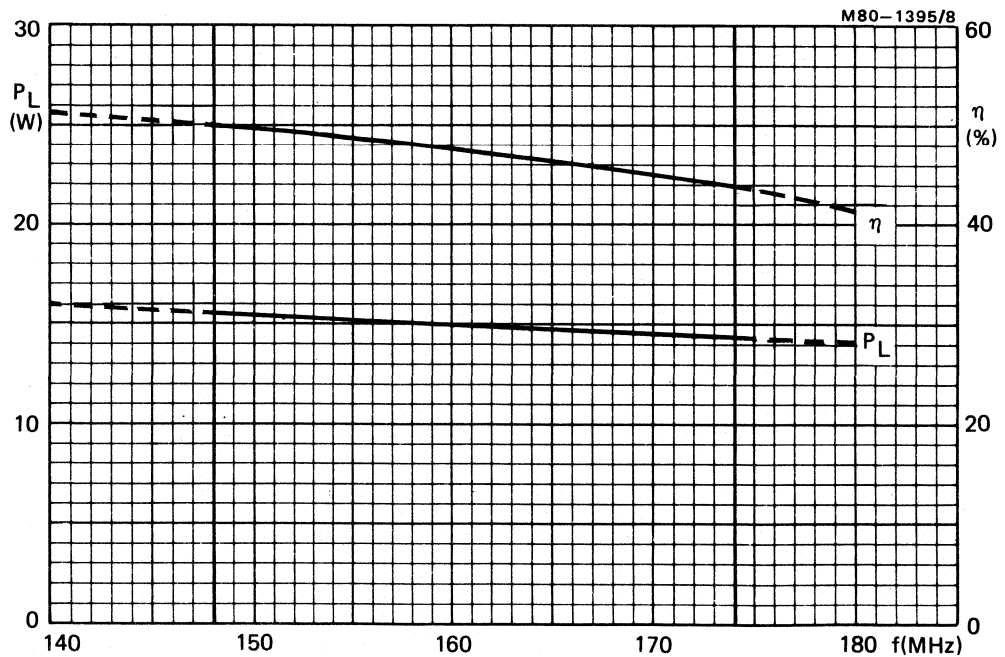


Fig.8 Typical values;  $V_{S1} = V_{S2} = 12.5$  V;  $P_D = 150$  mW

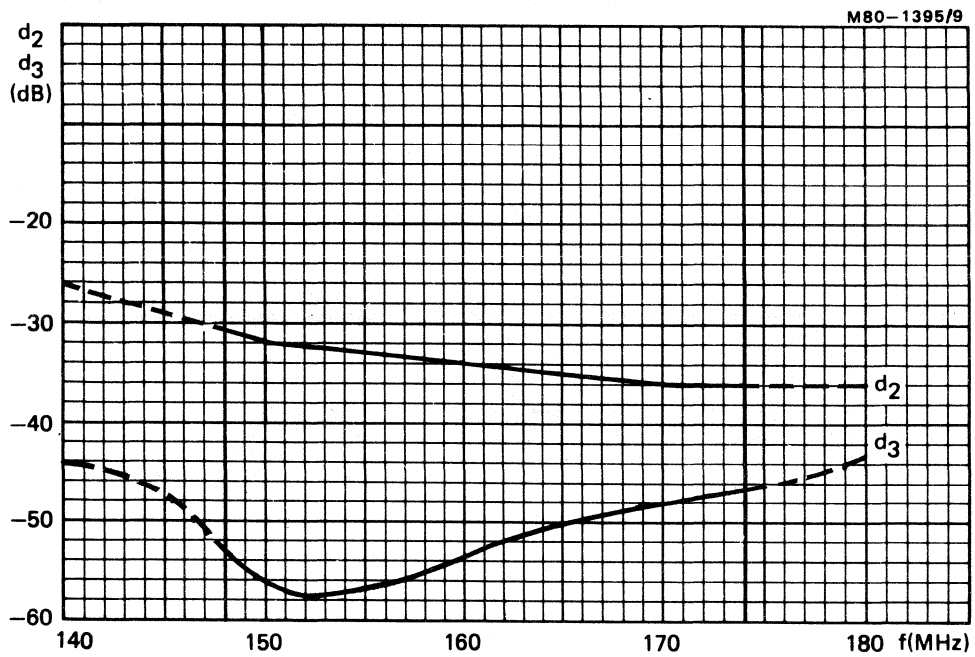
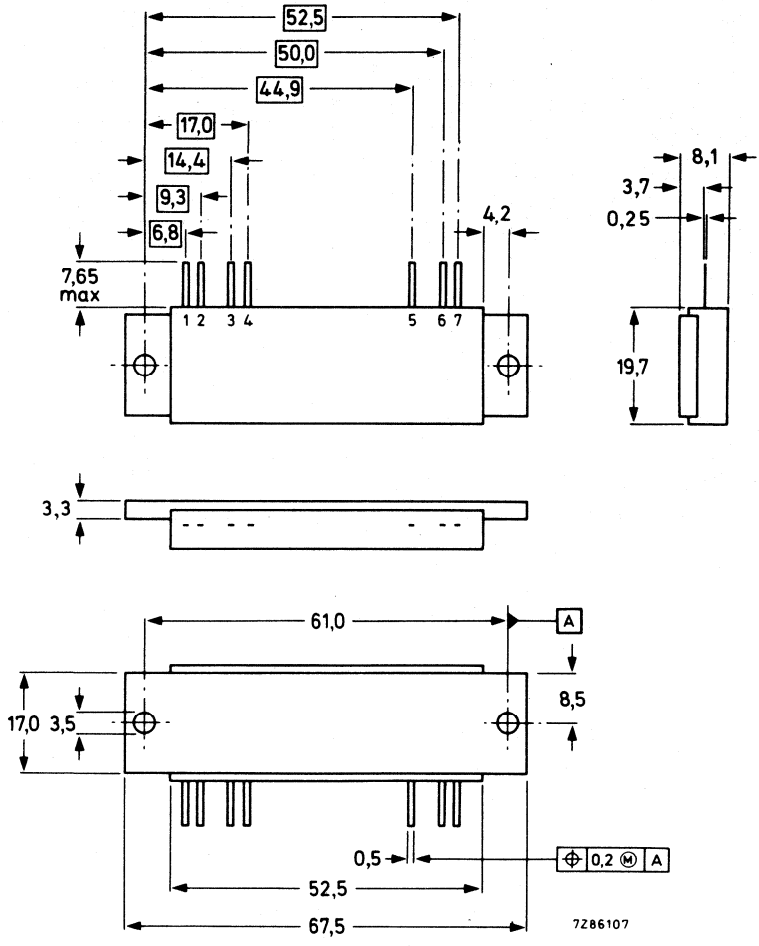


Fig.9 Typical values;  $V_{S1} = V_{S2} = 12.5$  V;  $P_D = 150$  mW

MECHANICAL DATA

Fig. 10 SOT-132B.

Dimensions in mm



Lead reference

- 1 = Input
- 2 = Earth
- 3 = VS1
- 4 = Earth
- 5 = VS2
- 6 = Earth
- 7 = Output

## UHF POWER AMPLIFIER MODULE

UHF broadband amplifier module designed for use in mobile communication equipment operating directly from a 9.6 V electrical supply. The module will produce a minimum of 1.4 W into a 50 Ω load over the frequency range 400 to 440 MHz.

The module consists of a two-stage RF amplifier using npn transistor chips with lumped element matching components in a SOT-181 plastic encapsulation. The negative supply is internally connected to the flange.

### QUICK REFERENCE DATA

Mode of operation	continuous wave		
Frequency range	400 to 440 MHz		
DC supply voltage (terminal 3)	VS1	nom.	7.5 V
DC supply voltage (terminal 4)	VS2	nom.	9.6 V
RF drive power	PD	<	45 mW
RF load power	PL	min.	1.4 W
Efficiency	η	typ.	42 %

### MECHANICAL DATA

Dimensions in mm

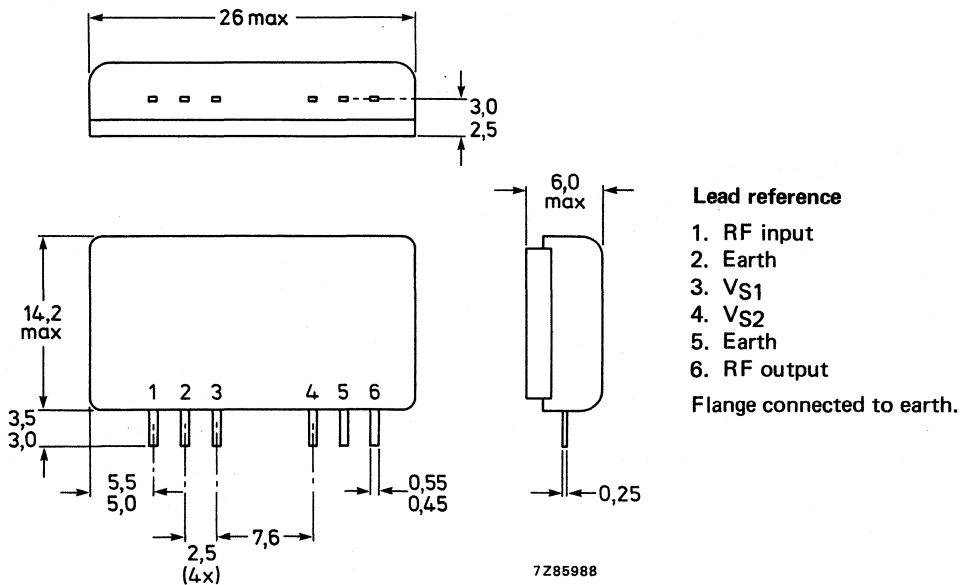


Fig. 1 SOT-181.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}, V_{S2}$	max.	12 V*
RF input terminal voltage*	$\pm V_i$	max.	25 V*
RF output terminal voltage*	$\pm V_o$	max.	25 V*
Load power (see Fig. 2)	$P_L$	max.	2.5 W
Drive power	$P_D$	max.	90 mW
Storage temperature range	$T_{stg}$		-40 to 100 °C
Operating heatsink temperature range	$T_h$		-30 to 90 °C

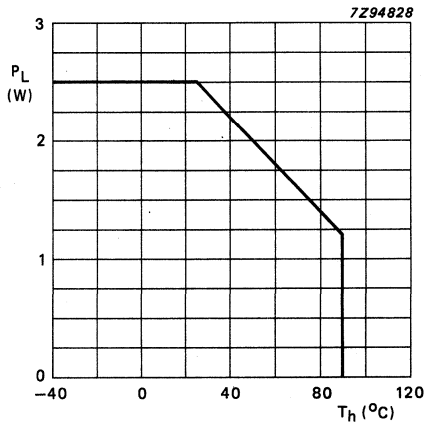


Fig. 2 Load power derating.

**CHARACTERISTICS**

$V_{S1} = 7.5 \text{ V}; V_{S2} = 9.6 \text{ V}; R_S = R_L = 50 \Omega; f = 400 \text{ to } 440 \text{ MHz}; T_h = 25 \text{ °C}$

Quiescent currents			
$P_D = 0$	$I_{Q1}$	<	7.0 mA
	$I_{Q2}$	<	0.1 mA
RF drive power			
$P_L = 1.4 \text{ W}$	$P_D$	<	45 mW
Efficiency			
$P_L = 1.4 \text{ W}$	$\eta$	>	40 %
		typ.	42 %
Harmonic output			
	any harmonic	min.	30 dB
		typ.	40 dB
Input VSWR with respect to 50 $\Omega$		<	2 : 1

\* With respect to earth pins.

**Stability**

The module is stable with a load VSWR up to 5 : 1 (all phases) when operated within the following conditions:

$V_{S1} = V_{S2} = 5.0 \text{ V to } 11.2 \text{ V}$ ;  $P_D = 17 \text{ to } 90 \text{ mW}$ ;  $f = 400 \text{ to } 440 \text{ MHz}$ ;  $P_L < 2.5 \text{ W}$  (matched).

**Ruggedness**

The module will withstand a load mismatch VSWR of 50 : 1 (all phases) for short period overload conditions, with  $P_D \leq 90 \text{ mW}$ ,  $V_{S1} \leq V_{S2} \leq 12 \text{ V}$ ,  $P_L < 2.5 \text{ W}$  (matched),  $T_h \leq 90 \text{ }^\circ\text{C}$ .

**APPLICATION INFORMATION****Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface with heat-conducting compound applied between module and heatsink. The module is designed to be pressed against the heatsink by a sheet spring applying up to 50 N to the top surface of the module encapsulation. The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245 °C for not more than 10 seconds at a distance of at least 1 mm from the plastic.

**Power rating**

In general, it is recommended that the output power from the module under nominal conditions should not exceed 1.5 W in order to provide an adequate safety margin under fault conditions.

**Output power control**

The module is designed to be operated at a constant output power of 1.4 W. The module is adjusted to produce nominal output by reducing the first stage supply voltage  $V_{S1}$ . If the module is to be used over a range of output power levels below 1.4 W, the first stage supply voltage should not be reduced below 5 V. If further reductions in power are needed, this may be achieved by varying the drive power  $P_D$ . For stable operation however, care must be taken to avoid operating the module outside the published stability conditions.

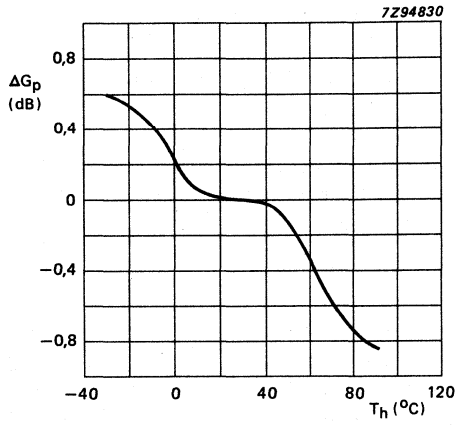


Fig. 3 Power gain as a function of temperature;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

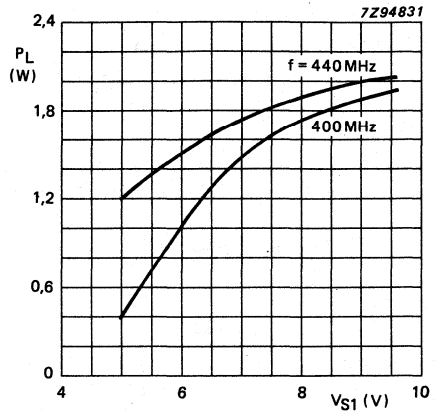


Fig. 4 Load power as a function of supply voltage  $V_{S1}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

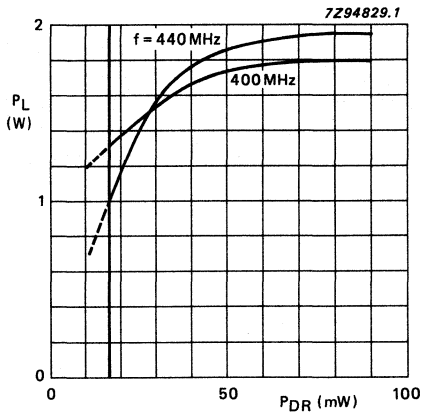


Fig. 5 Load power as a function of drive power;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ; typical values.



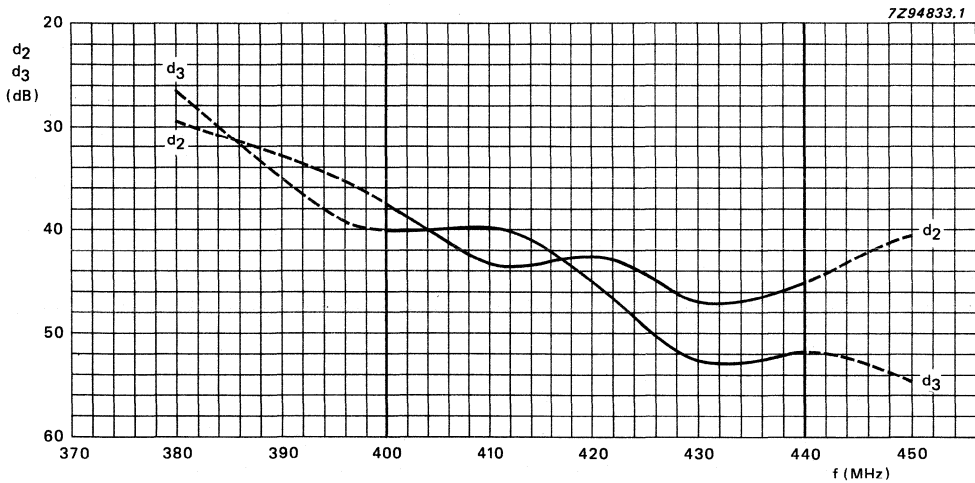


Fig. 6 Second and third harmonic distortions as a function of frequency;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

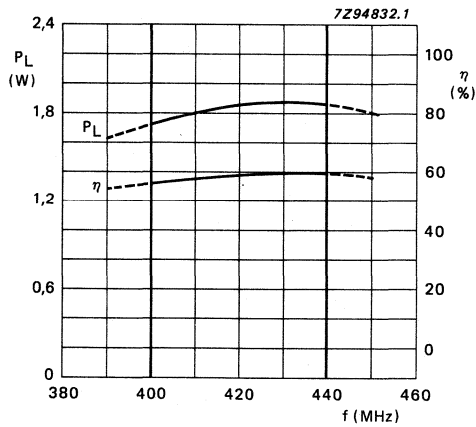


Fig. 7 Load power and efficiency as functions of frequency;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.



## UHF POWER AMPLIFIER MODULE

UHF broadband amplifier module designed for use in mobile communication equipment operating directly from a 9.6 V electrical supply. The module will produce a minimum of 1.4 W into a 50 Ω load over the frequency range of 430 to 470 MHz.

The module consists of a two-stage RF amplifier using npn transistor chips with lumped element matching components in a SOT-181 plastic encapsulation. The negative supply is internally connected to the flange.

### QUICK REFERENCE DATA

Mode of operation	continuous wave	
Frequency range	430 to 470 MHz	
DC supply voltage (terminal 3)	V <sub>S1</sub>	nom. 7.5 V
DC supply voltage (terminal 4)	V <sub>S2</sub>	nom. 9.6 V
RF drive power	P <sub>D</sub>	< 45 mW
RF load power	P <sub>L</sub>	min. 1.4 W
Efficiency	η	typ. 45 %

### MECHANICAL DATA

Dimensions in mm

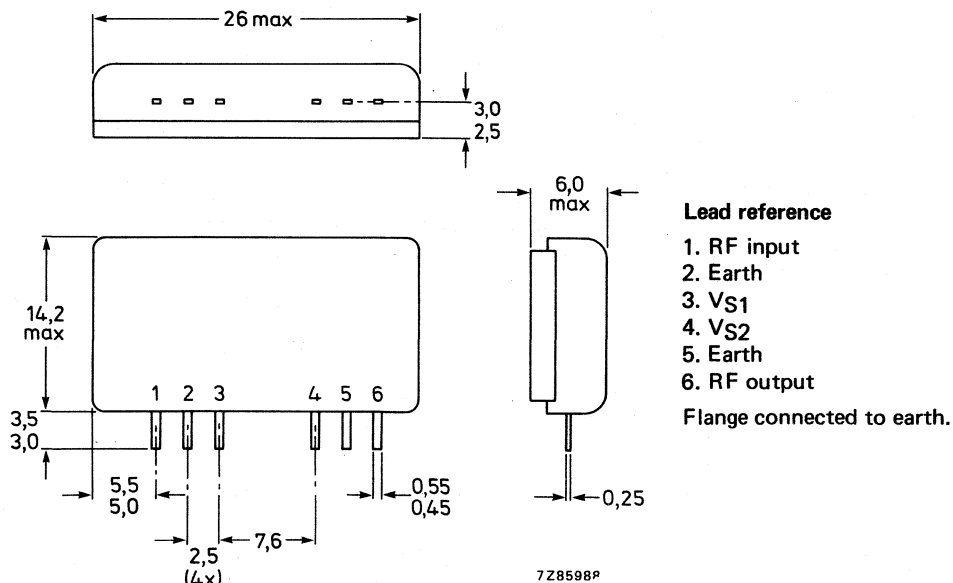


Fig. 1 SOT-181.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}, V_{S2}$	max.	12 V*
RF input terminal voltage*	$\pm V_i$	max.	25 V*
RF output terminal voltage*	$\pm V_o$	max.	25 V*
Load power (see Fig. 2)	$P_L$	max.	2.5 W
Drive power	$P_D$	max.	90 mW
Storage temperature range	$T_{stg}$		-40 to +100 °C
Operating heatsink temperature	$T_h$	max.	90 °C

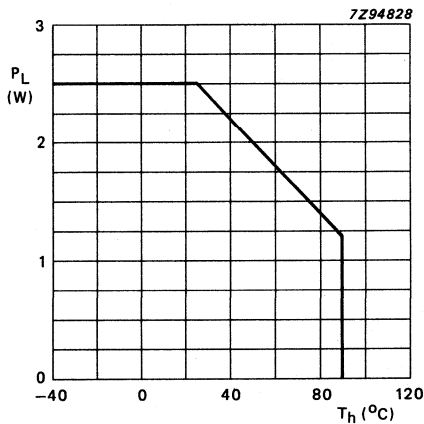


Fig. 2 Load power derating; VSWR = 1 : 1.

**CHARACTERISTICS**

$V_{S1} = 7.5$  V;  $V_{S2} = 9.6$  V;  $R_S = R_L = 50 \Omega$ ;  $f = 430$  to  $470$  MHz;  $T_h = 25$  °C

Quiescent currents			
$P_D = 0$	$I_{Q1}$	<	7.0 mA
	$I_{Q2}$	<	0.1 mA
RF drive power			
$P_L = 1.4$ W	$P_D$	<	45 mW
Efficiency			
$P_L = 1.4$ W	$\eta$	>	40 %
		typ.	45 %
Harmonic output	any harmonic	min.	30 dB
		typ.	40 dB
Input VSWR			
with respect to $50 \Omega$		<	2 : 1

\* With respect to the earth pins.

**Stability**

The module is stable with a load VSWR up to 5 : 1 (all phases) when operated within the following conditions:

$$V_{S1} \leq V_{S2} = 5.0 \text{ V to } 11.2 \text{ V}; P_D = 17 \text{ to } 90 \text{ mW}; f = 430 \text{ to } 470 \text{ MHz}; P_L < 2.5 \text{ W (matched)}.$$

**Ruggedness**

The module will withstand a load mismatch VSWR of 50 : 1 (all phases) for short period overload conditions, with  $P_D \leq 90 \text{ mW}$ ,  $V_{S1} \leq V_{S2} \leq 12 \text{ V}$ ,  $P_L < 2.5 \text{ W (matched)}$ ,  $T_h < 90 \text{ }^\circ\text{C}$ .

**APPLICATION INFORMATION****Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface with heat-conducting compound applied between module and heatsink. The module is designed to be pressed against the heatsink by a sheet spring applying up to 50 N to the top surface of the module encapsulation. The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245 °C for not more than 10 seconds at a distance of at least 1 mm from the plastic.

**Power rating**

In general, it is recommended that the output power from the module under nominal conditions should not exceed 1.5 W in order to provide an adequate safety margin under fault conditions.

**Output power control**

The module is designed to be operated at a constant output power of 1.4 W. The module is adjusted to produce nominal output by reducing the first stage supply voltage  $V_{S1}$ . If the module is to be used over a range of output power levels below 1.4 W, the first stage supply voltage should not be reduced below 5 V. If further reductions in power are needed, this may be achieved by varying the drive power  $P_D$ . For stable operation however, care must be taken to avoid operating the module outside the published stability conditions.

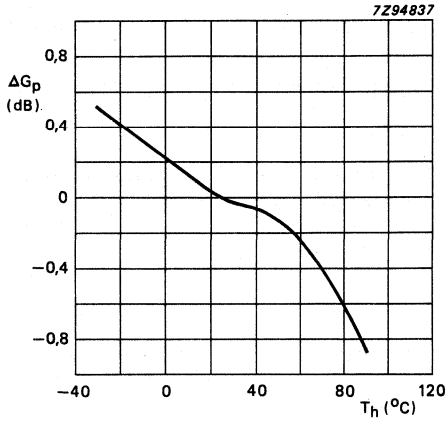


Fig. 3 Power gain as a function of temperature;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

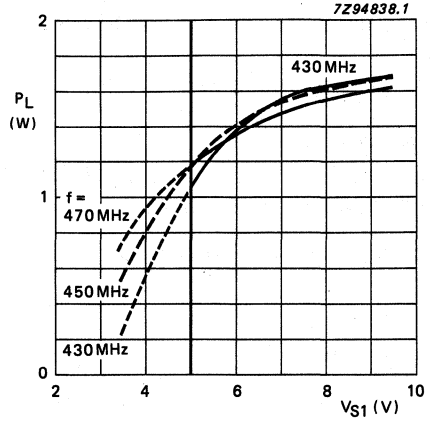


Fig. 4 Load power as a function of supply voltage  $V_{S1}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

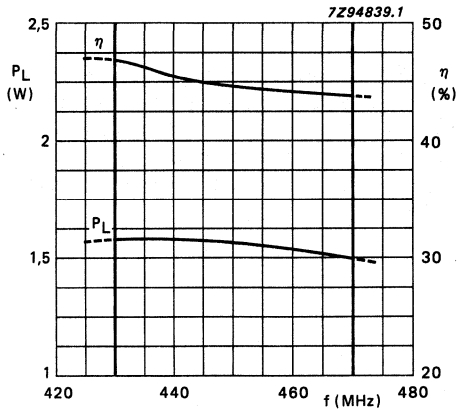


Fig. 5 Load power and efficiency as functions of frequency;  $V_{S1} = 7.5 \text{ V}$ ;  $V_{S2} = 9.6 \text{ V}$ ;  $P_D = 45 \text{ mW}$ ; typical values.

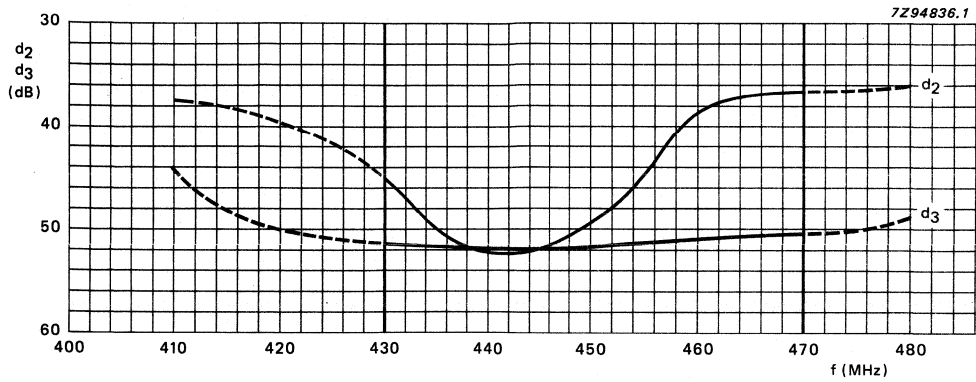


Fig. 6 Second and third harmonic distortions as a function of frequency;  $V_{S1} = 7.5$  V;  $V_{S2} = 9.6$  V;  $P_D = 45$  mW; typical values.

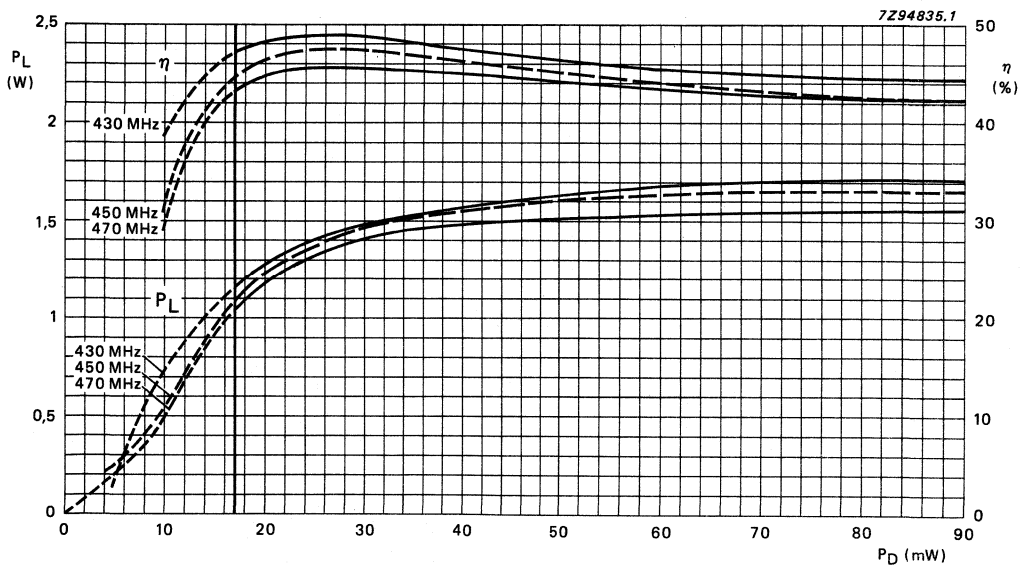


Fig. 7 Load power and efficiency as functions of drive power;  $V_{S1} = 7.5$  V;  $V_{S2} = 9.6$  V; typical values.





## UHF POWER AMPLIFIER MODULE

A broadband UHF amplifier module primarily designed for mobile communications equipment, operating directly from 7.5 V or 9.6 V electrical systems. The module will produce a minimum output of 2.0 W or 3.2 W into a 50 Ω load over the frequency range 400 to 470 MHz.

The module consists of a two-stage RF amplifier, using npn transistor chips with lumped-element matching components in a plastic stripline encapsulation (SOT181). The negative supply is internally connected to the flange.

### QUICK REFERENCE DATA

Mode of operation			CW
Frequency range			400 to 470 MHz
DC supply voltage (terminal 3)	V <sub>S1</sub>		7.5 or 9.6 V
DC supply voltage (terminal 4)	V <sub>S2</sub>		7.5 or 9.6 V
RF drive power	P <sub>D</sub>	max.	50 mW
RF load power	P <sub>L</sub>	min.	2.0 or 3.2 W
Efficiency	η	typ.	44 %

### MECHANICAL DATA

Dimensions in mm

#### Lead reference

- 1 = RF input
- 2 = Earth
- 3 = V<sub>S1</sub>
- 4 = V<sub>S2</sub>
- 5 = Earth
- 6 = RF output
- Flange = earth

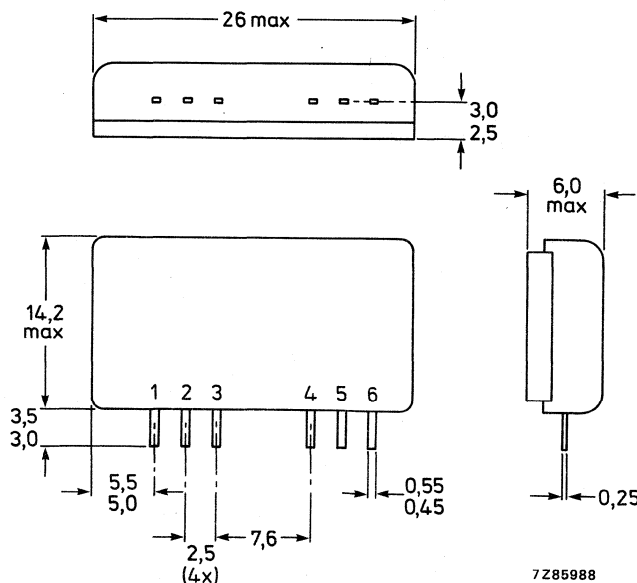


Fig.1 SOT181.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}, V_{S2}$	max.	12 V
RF input terminal voltage*	$\pm V_i$	max.	25 V
RF output terminal voltage*	$\pm V_o$	max.	25 V
Load power	$P_L$	max.	5.0 W
Drive power	$P_D$	max.	90 mW
Storage temperature range	$T_{stg}$		-40 to 100 °C
Operating heatsink temperature	$T_h$	max.	90 °C

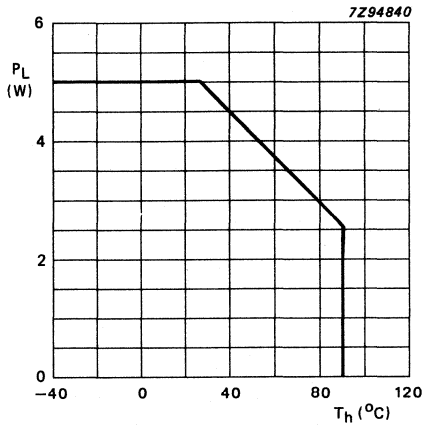


Fig.2 Load power derating; VSWR = 1 : 1.

\* With respect to the earth pins.

**CHARACTERISTICS**

$Z_S = Z_L = 50 \Omega$ ; frequency range = 400 to 470 MHz;  $T_h = 25 \text{ }^\circ\text{C}$  unless otherwise specified.

**Quiescent currents**

$V_{S1} = V_{S2} = 7.5 \text{ V}$  or  $9.6 \text{ V}$ ;

$P_D = 0$

$I_{Q1}$  max. 7.0 mA

$I_{Q2}$  max. 0.1 mA

**Efficiency**

$P_L = 2.0 \text{ W}$  or  $P_L = 3.2 \text{ W}$

$\eta$  min. 40 %

$\eta$  typ. 44 %

**RF drive power**

$P_L = 2.0 \text{ W}$ ;  $V_{S1} = V_{S2} = 7.5 \text{ V}$

$P_L = 3.2 \text{ W}$ ;  $V_{S1} = V_{S2} = 9.6 \text{ V}$

$P_D$  max. 50 mW

$P_D$  max. 50 mW

**Harmonic output**

any harmonic min. -30 dB

typ. -40 dB

**Input VSWR**

with respect to  $50 \Omega$

VSWR max. 2:1

**Stability**

The module is stable with a load VSWR up to 5:1 (all phases) when operated within the following conditions:

$V_{S1} \leq V_{S2} = 5.0 \text{ V}$  to  $11.2 \text{ V}$ ;  $P_D = 25$  to  $90 \text{ mW}$ ;  $f = 400$  to  $470 \text{ MHz}$ ;  $P_L < 5.0 \text{ W}$  (matched)

**Ruggedness**

The module will withstand a load mismatch VSWR of 50:1 (all phases) for short period overload conditions, with  $P_D$ ,  $V_{S1}$  and  $V_{S2}$  at maximum values, providing the combination does not cause the matched RF output power rating to be exceeded.

**Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface with heat-conducting compound applied between module and heatsink. The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of  $245 \text{ }^\circ\text{C}$  for not more than 10 seconds at a distance of a least 1 mm from the plastic.

**Power rating**

In general it is recommended that the output power from the module under nominal conditions should not exceed 4 W in order to provide an adequate safety margin under fault conditions.

**Output power control**

The module is not designed to be operated over a large range of output power levels. The aim of the output power control is to set the nominal output power level. The preferred method of output power control is by varying the drive power between 25 and 50 mW. The next option is by varying  $V_{S1}$  between 5.0 and 9.6 V.

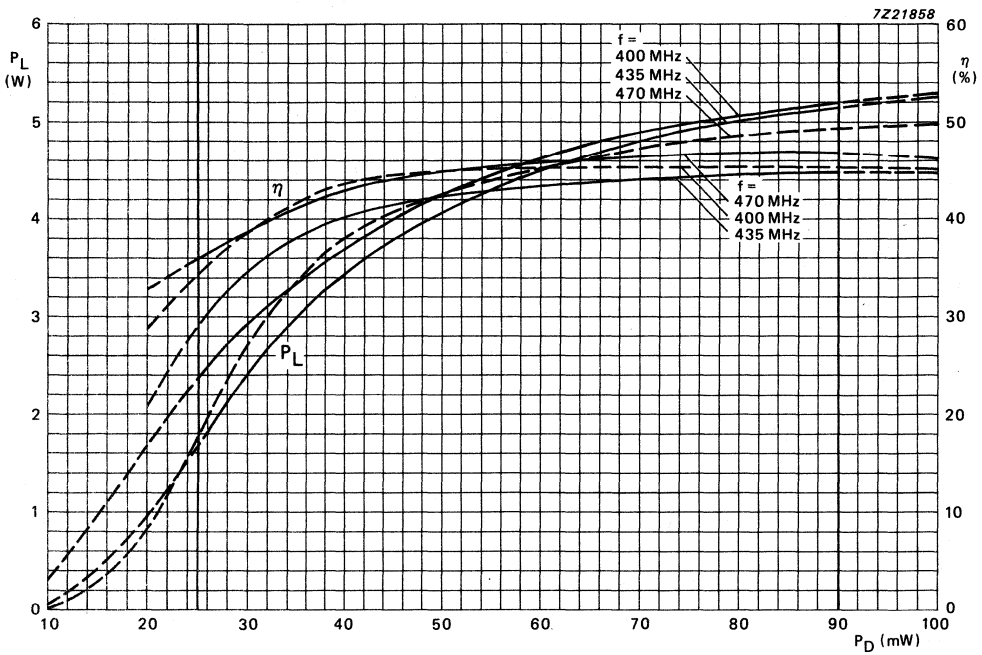


Fig.3 Load power and efficiency as functions of drive power;  $V_{S1} = V_{S2} = 9.6$  V; typical values.

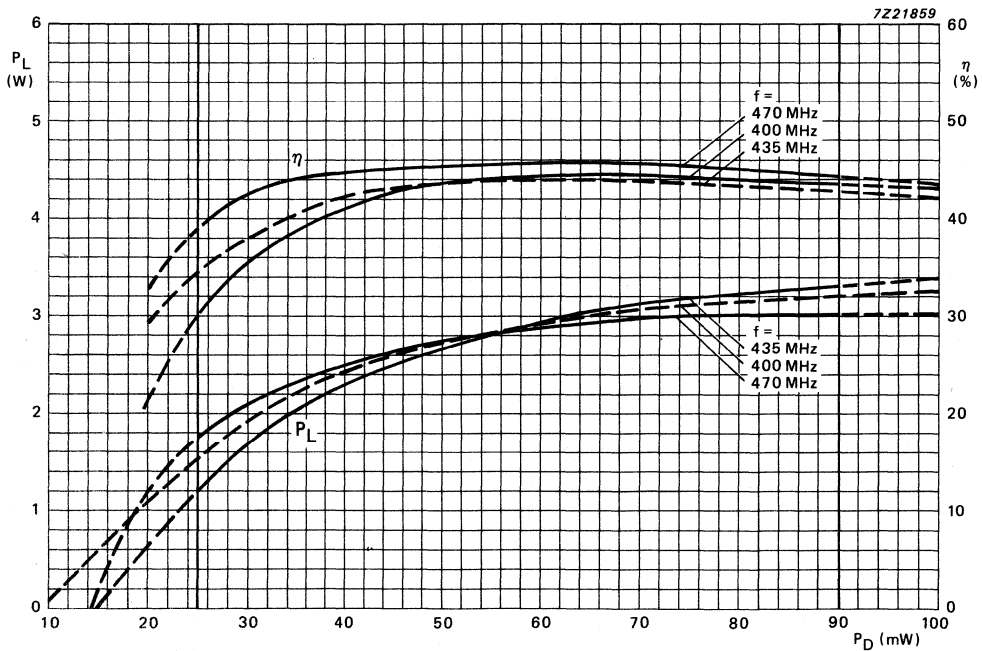


Fig.4 Load power and efficiency as functions of drive power;  $V_{S1} = V_{S2} = 7.5$  V; typical values.

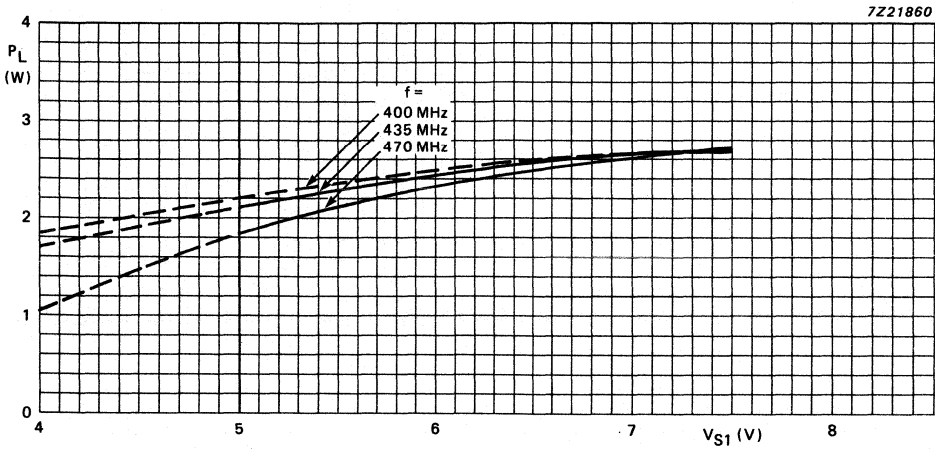


Fig.5 Load power as a function of  $V_{S1}$ ;  $V_{S2} = 7.5$  V;  $P_D = 50$  mW; typical values.

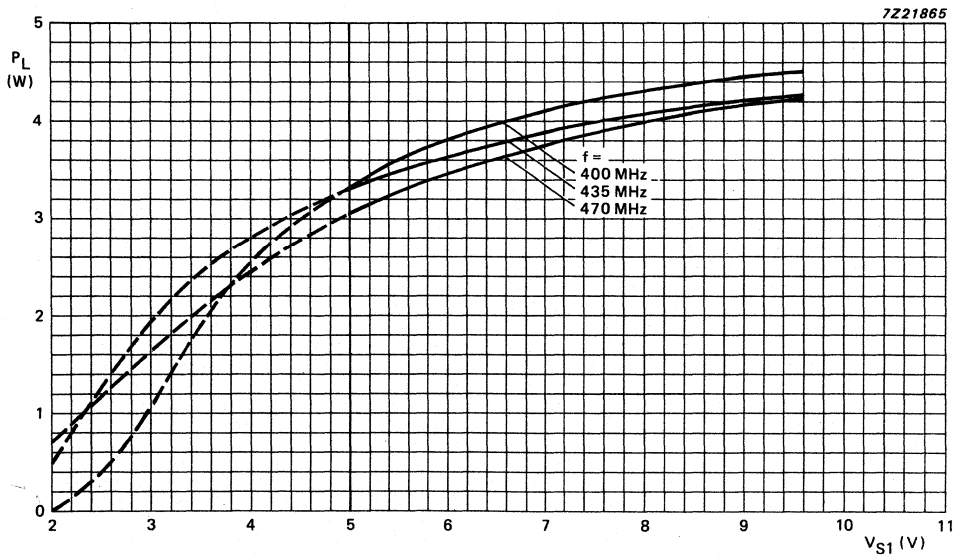


Fig.6 Load power as a function of  $V_{S1}$ ;  $V_{S2} = 9.6$  V;  $P_D = 50$  mW; typical values.

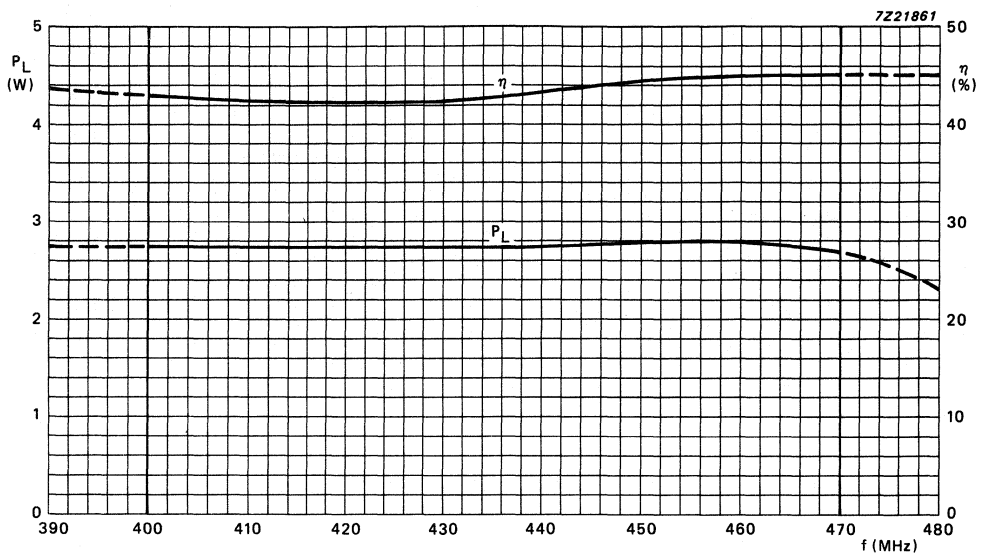


Fig.7 Load power and efficiency as functions of frequency;  $V_{S1} = V_{S2} = 7.5$  V;  $P_D = 50$  mW; typical values.

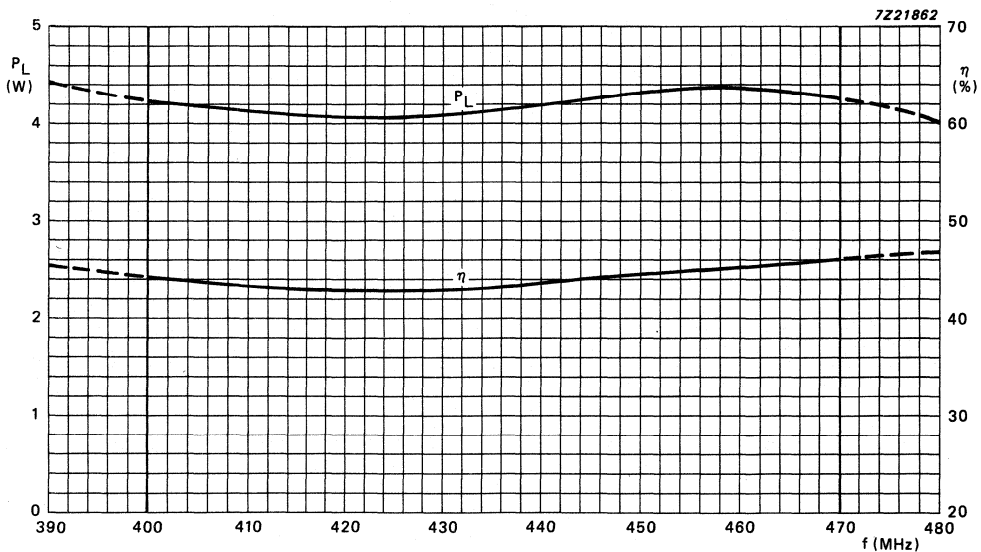


Fig.8 Load power and efficiency as functions of frequency;  $V_{S1} = V_{S2} = 9.6$  V;  $P_D = 50$  mW; typical values.

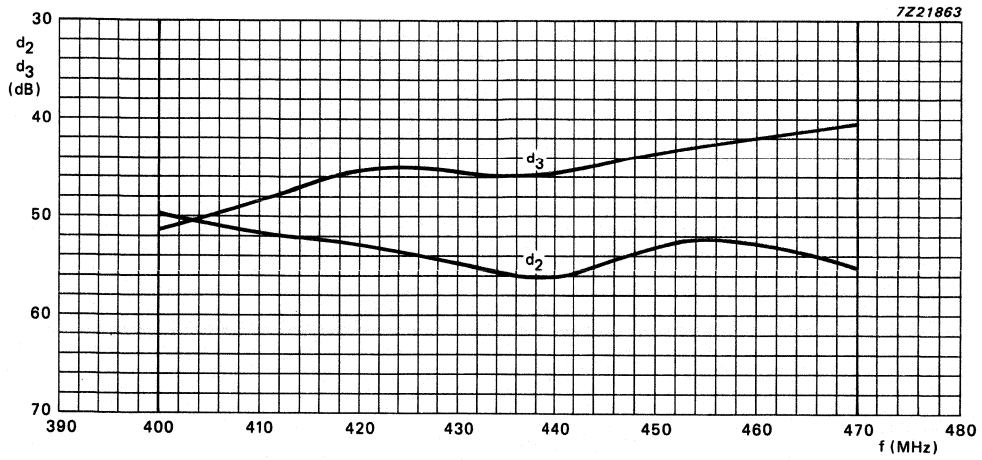


Fig.9 Second and third harmonic distortions as functions of frequency;  $V_{S1} = V_{S2} = 7.5 \text{ V}$ ;  $P_D = 50 \text{ mW}$ ; typical values.

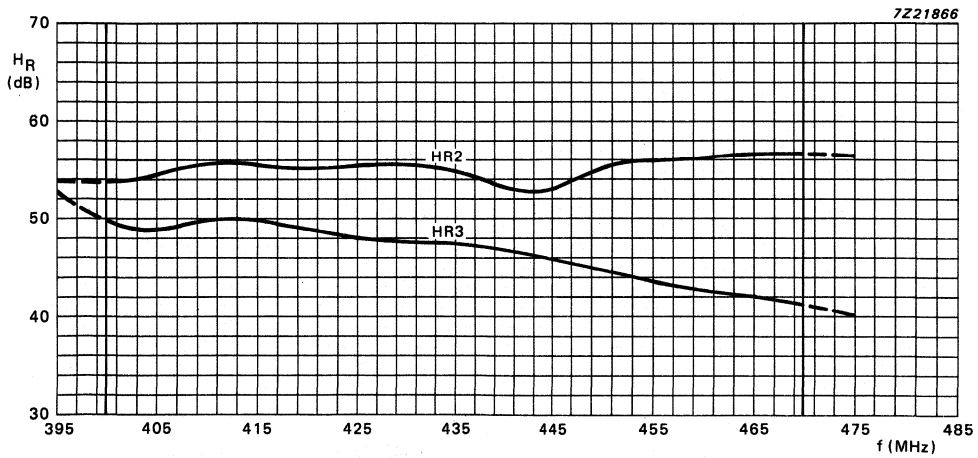


Fig.10 Second and third harmonic distortions as functions of frequency;  $V_{S1} = V_{S2} = 9.6 \text{ V}$ ;  $P_D = 50 \text{ mW}$ ; typical values.

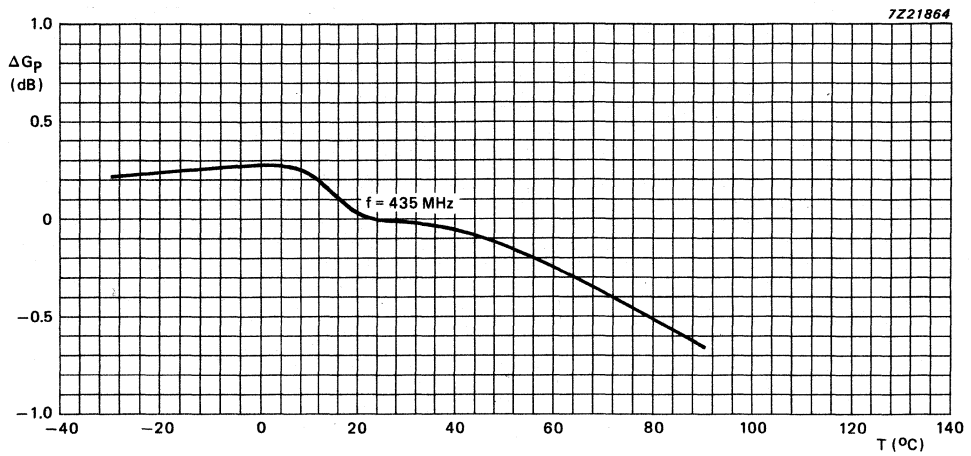


Fig.11 Power gain as a function of temperature;  $P_D = 50$  mW;  $V_{S1} = V_{S2} = 7.5$  V; typical values.

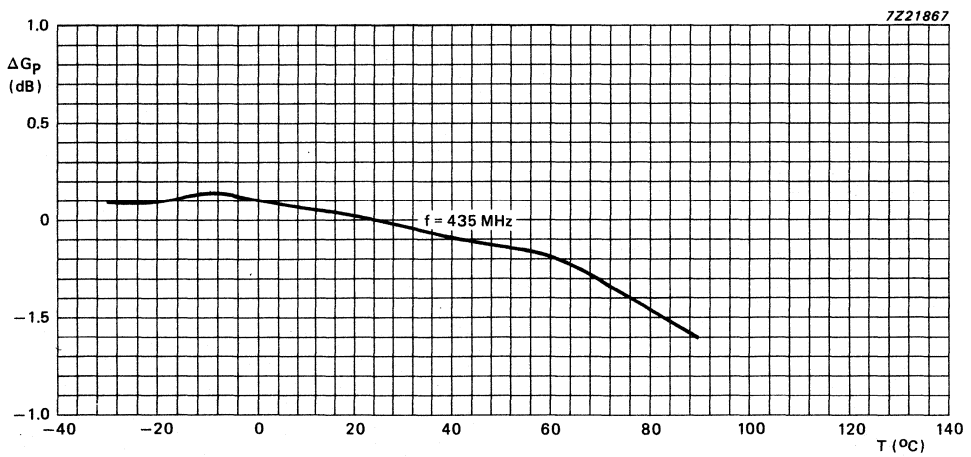


Fig.12 Power gain as a function of temperature;  $P_D = 50$  mW;  $V_{S1} = V_{S2} = 9.6$  V; typical values.



## UHF AMPLIFIER MODULE

The BGY95 is a three-stage UHF amplifier module designed primarily for mobile transmitting equipment operating from a nominal 7.5 V power supply.

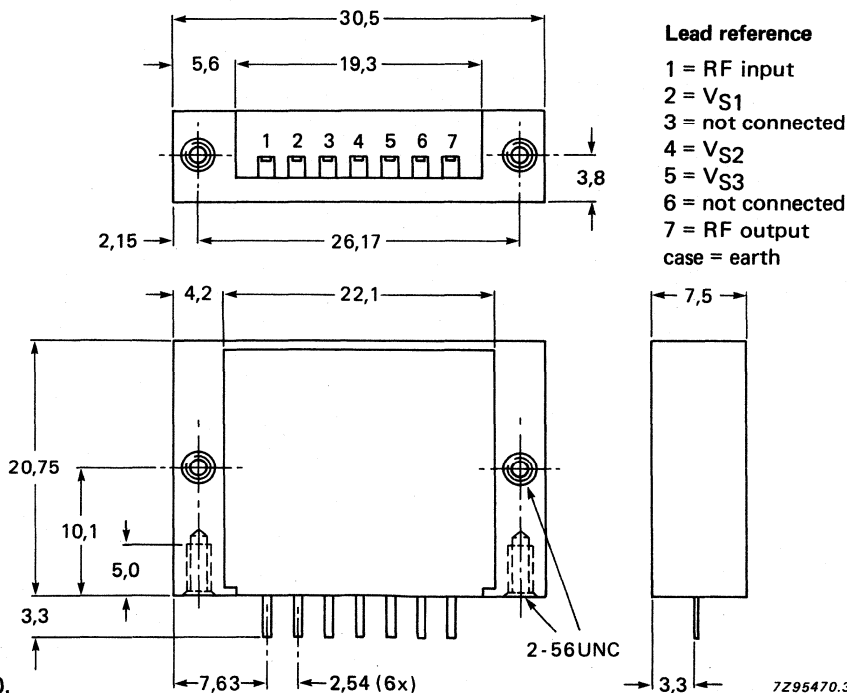
The module consists of three npn silicon planar transistors mounted on a metallized ceramic substrate, together with matching and bias circuitry. The BGY95A and BGY95B produce an output power of 2.2 W into a 50 Ω load over the frequency band of 824-851 MHz and 890-915 MHz respectively. The output power can be controlled by means of a DC voltage ( $V_{S1}$ ).

### QUICK REFERENCE DATA

Mode of operation			CW
Frequency range	BGY95A	f	824 to 851 MHz
	BGY95B	f	890 to 915 MHz
RF load power			
$V_{S1} = 6\text{ V}; V_{S2} = V_{S3} = 7.5\text{ V}; P_D = 20\text{ mW}$		$P_L$	min. 2.2 W
RF drive power			
$V_{S1} = 6\text{ V}; V_{S2} = V_{S3} = 7.5\text{ V}; P_L = 2.2\text{ W}$		$P_D$	≤ 20 mW
Output load impedance		$Z_L$	nom. 50 Ω

### MECHANICAL DATA

Dimensions in mm



**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

RF input terminal voltage*	$V_{in}$	max.	$\pm 25$ V
RF output terminal voltage*	$V_{out}$	max.	$\pm 25$ V
DC supply terminal voltages*	$V_{S1}$	max.	8.0 V
	$V_{S2}, V_{S3}$	max.	9.0 V
RF load power (see Fig.2)	$P_L$	max.	3.5 W
RF drive power	$P_D$	max.	40 mW
Storage temperature range	$T_{stg}$		-40 to + 100 °C
Operating heatsink temperature range	$T_h$		-30 to + 90 °C

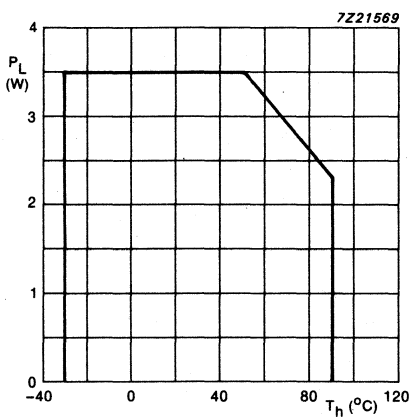


Fig.2 Load power derating; VSWR = 1:1.

\* With respect to case.

**CHARACTERISTICS**

$V_{S2} = V_{S3} = 7.5 \text{ V}$ ;  $P_D = 20 \text{ mW}$ ;  $T_h = 25 \text{ }^\circ\text{C}$ ;  $R_S = R_L = 50 \text{ } \Omega$ ; unless otherwise specified

Frequency range	BGY95A	f		824 to 851 MHz
	BGY95B	f		890 to 915 MHz
RF output power $V_{S1} = 6 \text{ V}$		$P_L$	min.	2.2 W
Efficiency $P_L = 2.2 \text{ W}$		$\eta$	min.	35 %
Harmonic rejection $P_L = 2.2 \text{ W}$		$H_{R2}$	min.	30 dB
		$H_{R3}$	min.	40 dB
Input VSWR with respect to $50 \text{ } \Omega$		VSWR	max.	2 : 1
Noise power 25 kHz. Bandwidth 45 MHz above $f_o$ . $P_{out} = 2.2 \text{ W}$		Noise	max.	-88 dBm

**Stability**

The module will produce no spurious signals  $> -60 \text{ dB}$  below the carrier signal when operated with a load mismatch  $VSWR < 3 : 1$  (all phases) and  $V_{S1} = 0.5 \text{ to } 6.0 \text{ V}$ ,  $V_{S2} = V_{S3} = 6 \text{ to } 9 \text{ V}$ .  
 $P_D = 10 \text{ to } 40 \text{ mW}$  and  $T_h \leq 90 \text{ }^\circ\text{C}$ , provided maximum ratings are not exceeded.  $V_{S1} \leq V_{S2}$  and  $V_{S3}$ .

**Ruggedness**

The module will withstand a load mismatch of  $50 : 1$  (all phases) for short periods when operated with  $V_{S1} < 8 \text{ V}$ ,  $V_{S2} = V_{S3} \leq 9 \text{ V}$ ,  $P_D \leq 40 \text{ mW}$  and  $T_h \leq 90 \text{ }^\circ\text{C}$ , provided maximum ratings are not exceeded.

**Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface with heat-conducting compound applied between module and the heatsink. The leads may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245 °C for not more than 10 seconds at a distance of at least 1 mm from the plastic.

**Power rating**

In general, it is recommended that the output power from the module under nominal conditions should not exceed 3.0 W in order to provide an adequate safety margin under fault conditions.

**Gain control**

The module is designed to be operated at a nominal output power of 2.2 W. The module is adjusted to produce nominal output power by reducing the first stage supply voltage  $V_{S1}$ . The output power may be varied from 6 mW to 2.2 W by varying  $V_{S1}$  from 0.5 V to 6 V.

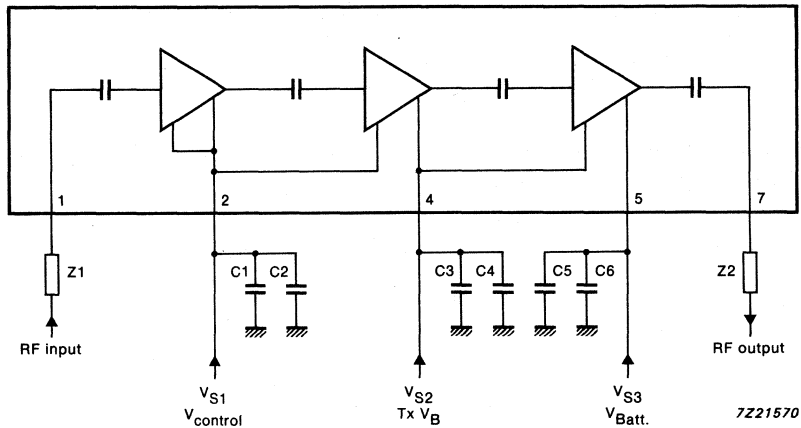
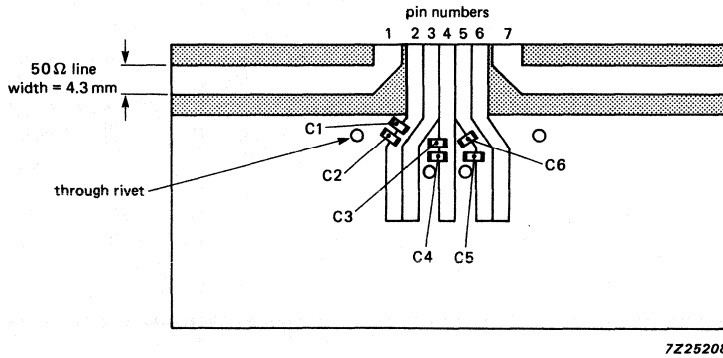


Fig. 3 Internal diagram.

- Z1 = Z2 = 50 Ω stripline
- C1 = C3 = C6 = 0.01 μF ceramic chip capacitor
- C2 = C4 = C5 = 1.0 μF tantalum capacitor



Teflon glass board 1/16";  $\epsilon_r = 2.55$ . Decouple DC supplies with 0.01  $\mu\text{F}$  chip and 1  $\mu\text{F}$  tantalum capacitors.

Fig.4 Printed circuit board layout.

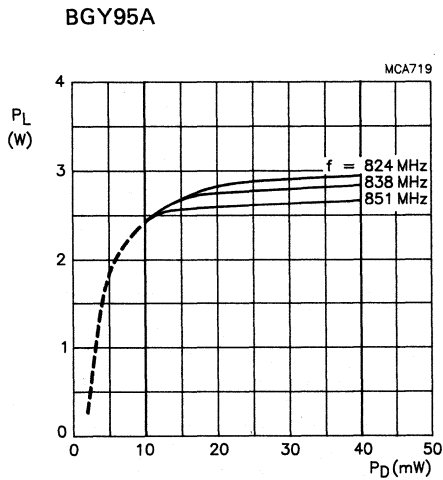


Fig.5 Load power as a function of drive power;  $V_{S1} = 6 \text{ V}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ .

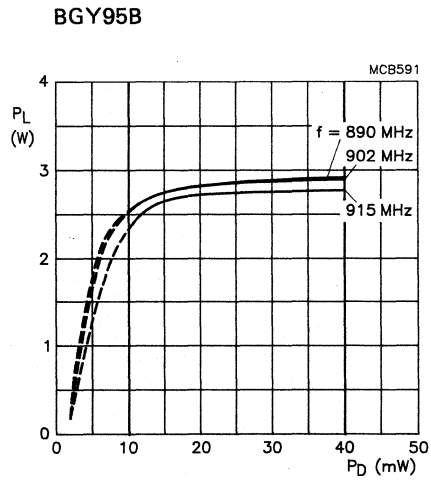


Fig.6 Load power as a function of drive power;  $V_{S1} = 6 \text{ V}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ .

BGY95A

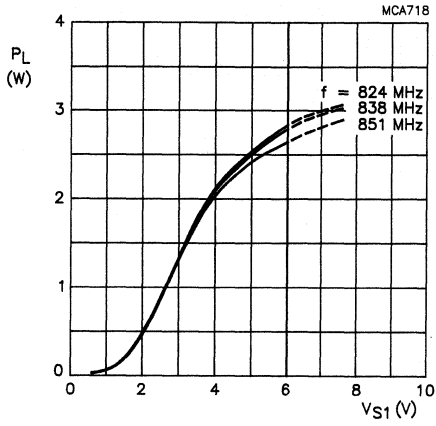


Fig. 7 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95B

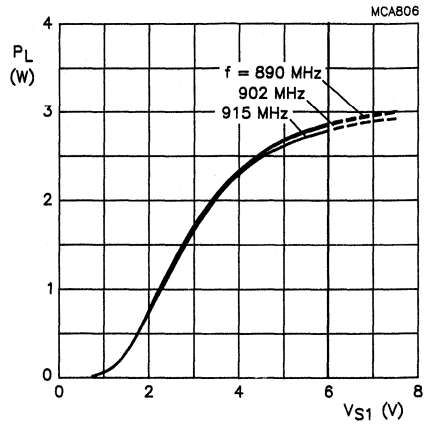


Fig. 8 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95A

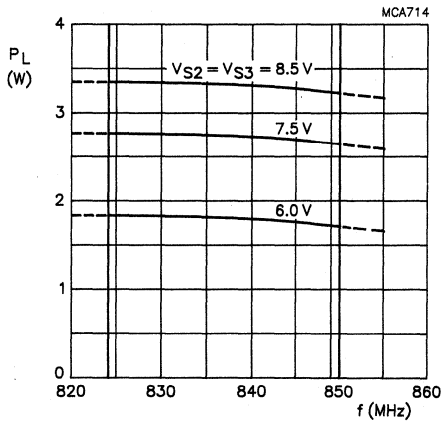


Fig. 9 Load power as a function of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V.

BGY95B

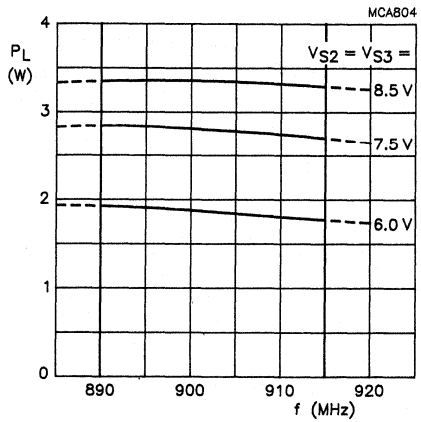


Fig. 10 Load power as a function of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V.

BGY95A

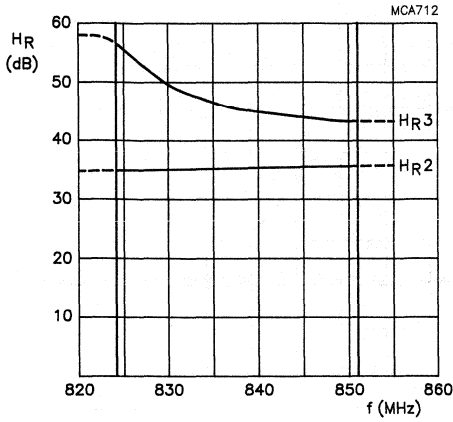


Fig.11 Second and third harmonic rejections as functions of frequency;  $P_D = 20 \text{ mW}$ ;  $V_{S1} = 6 \text{ V}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ .

BGY95B

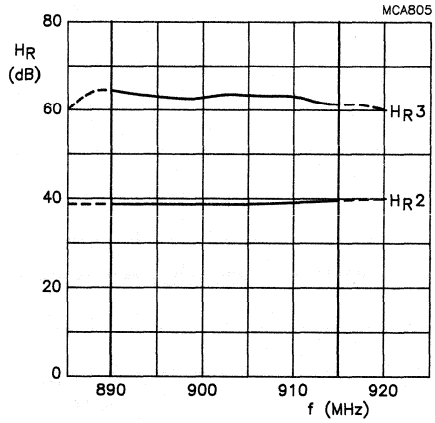


Fig.12 Second and third harmonic rejections as functions of frequency;  $P_D = 20 \text{ mW}$ ;  $V_{S1} = 6 \text{ V}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ .

BGY95A

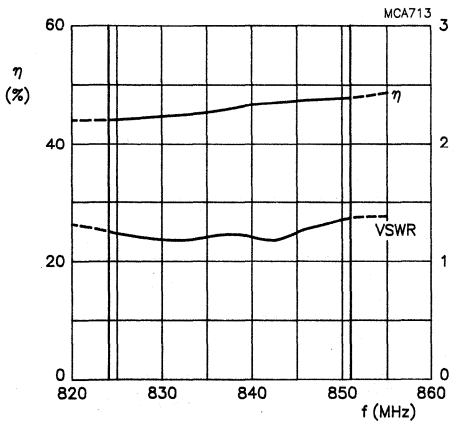


Fig.13 Efficiency and VSWR as functions of frequency;  $P_D = 20 \text{ mW}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ ;  $P_L = 2.2 \text{ W}$ .

BGY95B

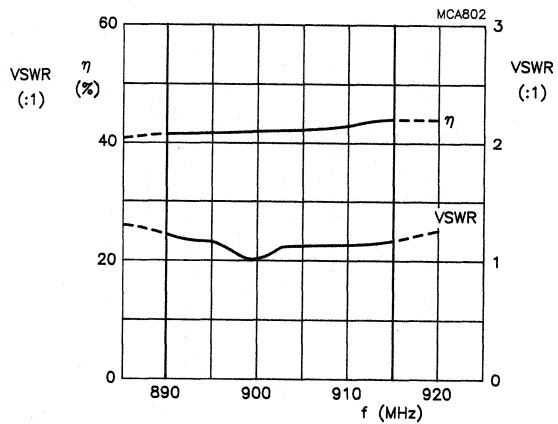


Fig.14 Efficiency and VSWR as functions of frequency;  $P_D = 20 \text{ mW}$ ;  $V_{S2} = V_{S3} = 7.5 \text{ V}$ ;  $P_L = 2.2 \text{ W}$ .

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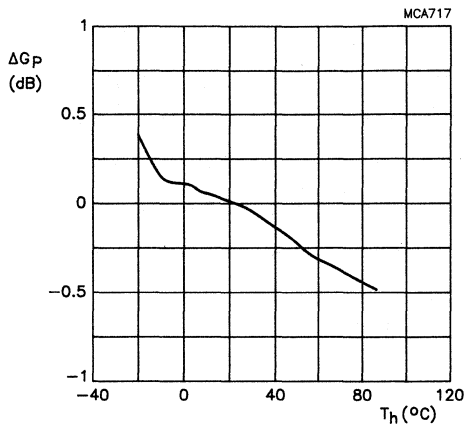


Fig. 15 Change in power gain as a function of heatsink temperature;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 7.5$  V;  $f = 838$  MHz.

BGY95B

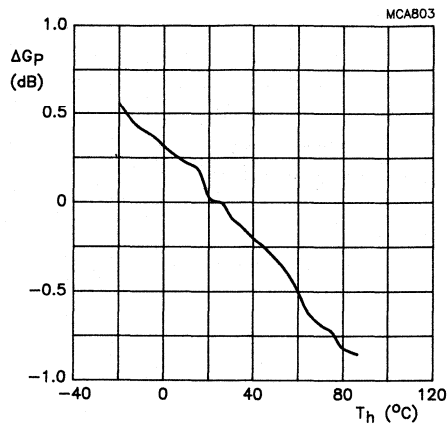


Fig. 16 Change in power gain as a function of heatsink temperature;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 7.5$  V;  $f = 902$  MHz.

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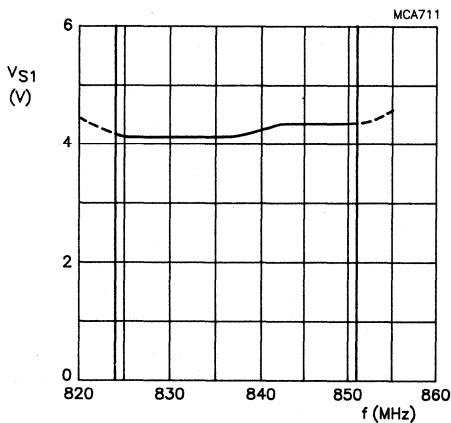


Fig. 17 Supply voltage  $V_{S1}$  as a function of frequency;  $P_D = 20$  mW;  $P_L = 2.2$  W;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95B

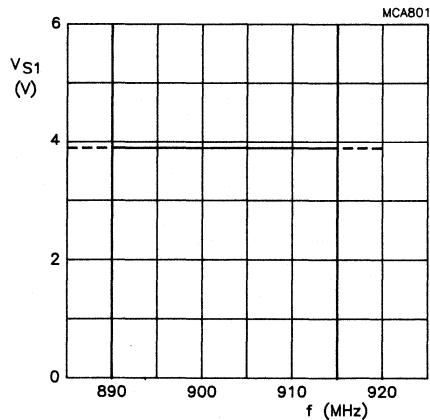


Fig. 18 Supply voltage  $V_{S1}$  as a function of frequency;  $P_D = 20$  mW;  $P_L = 2.2$  W;  $V_{S2} = V_{S3} = 7.5$  V.



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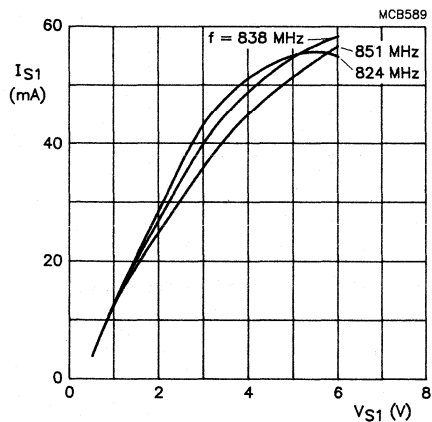


Fig.19 Supply current  $I_{S1}$  as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95B

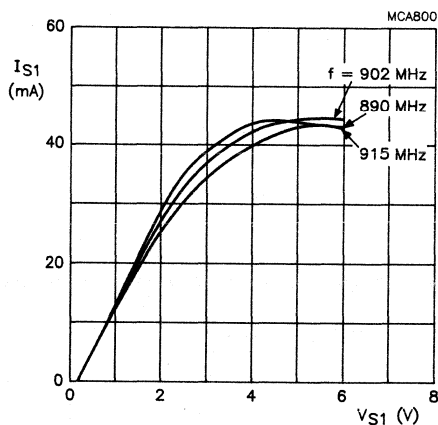


Fig.20 Supply current  $I_{S1}$  as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95A

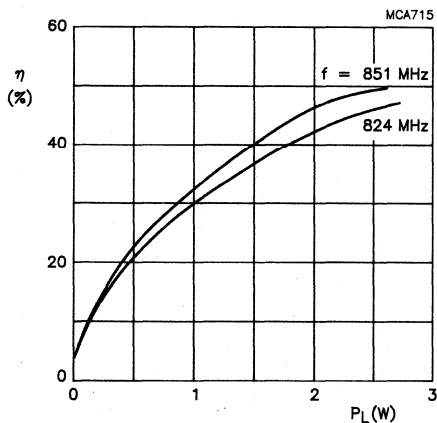


Fig.21 Efficiency as a function of load power;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.

BGY95B

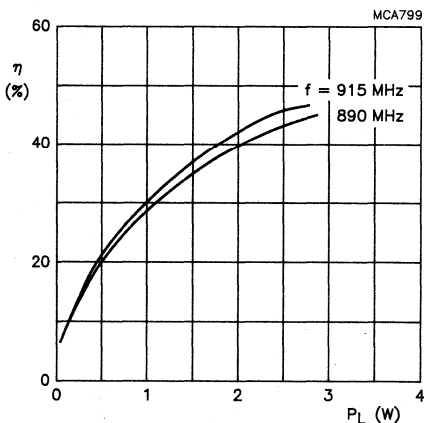


Fig.22 Efficiency as a function of load power;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 7.5$  V.



## UHF AMPLIFIER MODULE

The BGY96 is a three-stage UHF amplifier module designed primarily for mobile transmitting equipment operating from a nominal 9.6 V power supply.

The module consists of three npn silicon planar transistors mounted on a metallized ceramic substrate, together with matching and bias circuitry. The BGY96A and BGY96B produce an output power of 2.5 W into a 50 Ω load over the frequency band of 824-851 MHz and 890-915 MHz respectively. The output power can be controlled by means of a DC voltage ( $V_{S1}$ ).

### QUICK REFERENCE DATA

Mode of operation				CW
Frequency range	BGY96A BGY96B	f f		824 to 851 MHz 890 to 915 MHz
RF power output				
$V_{S1} = 6\text{ V}; V_{S2} = V_{S3} = 9.6\text{ V}; P_D = 20\text{ mW}$		$P_L$	min.	2.5 W
RF input drive power				
$P_L = 2.5\text{ W}$		$P_D$	≤	20 mW
Output load impedance		$Z_L$	nom.	50 Ω

### MECHANICAL DATA

#### Lead reference

- 1 = RF input
- 2 =  $V_{S1}$
- 3 = not connected
- 4 =  $V_{S2}$
- 5 =  $V_{S3}$
- 6 = not connected
- 7 = RF output
- case = earth

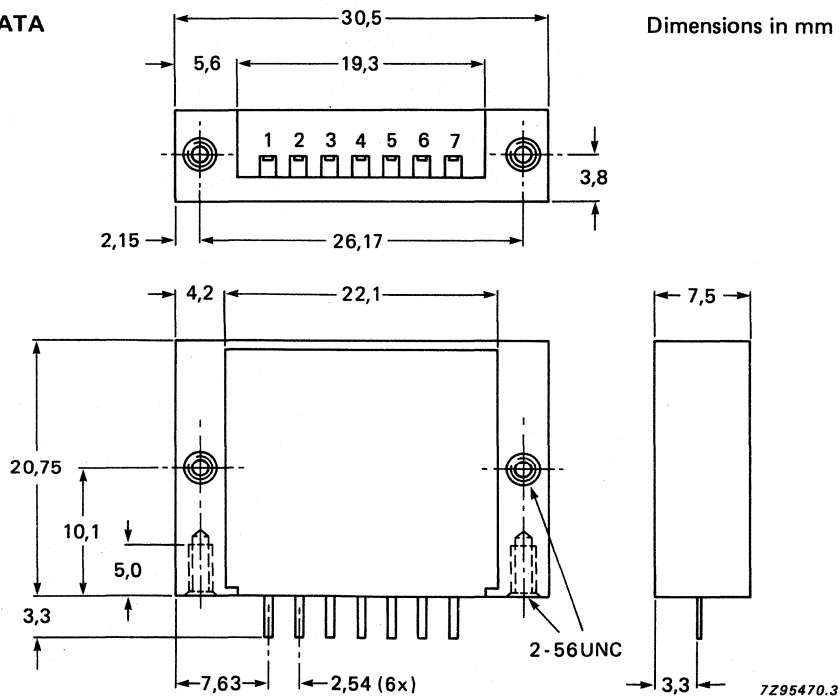


Fig. 1 SOT-200.

7Z96470.3

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}$	max.	8.0 V
	$V_{S2}, V_{S3}$	max.	13 V
RF input terminal voltage*	$V_{in}$	max.	$\pm 25$ V
RF output terminal voltage*	$V_{out}$	max.	$\pm 25$ V
RF load power (see Fig. 2)	$P_L$	max.	3.5 W
RF drive power	$P_D$	max.	50 mW
Storage temperature range	$T_{stg}$		-40 to + 100 °C
Operating heatsink temperature range	$T_h$	max.	-30 to + 90 °C

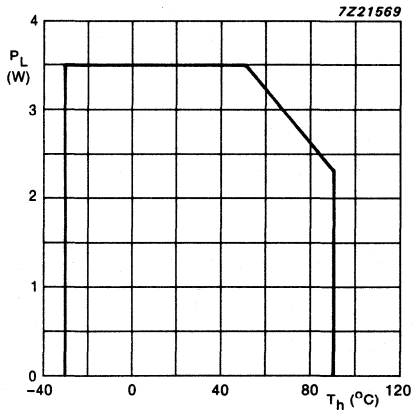


Fig. 2 Load power derating; VSWR = 1 : 1.

\* With respect to case.

**CHARACTERISTICS**

$V_{S2} = V_{S3} = 9.6 \text{ V}$ ;  $P_D = 20 \text{ mW}$ ;  $T_h = 25 \text{ }^\circ\text{C}$ ;  $R_S = R_L = 50 \text{ } \Omega$ ; unless otherwise specified

Frequency range	BGY96A BGY96B	f f		824 to 851 MHz 890 to 915 MHz
RF output power $V_{S1} = 6 \text{ V}$		$P_L$	min.	2.5 W
Efficiency $P_L = 2.5 \text{ W}$		$\eta$	min.	35 %
Harmonic rejection $P_L = 2.5 \text{ W}$		d2 d3	min. min.	30 dB 40 dB
Input VSWR with respect to $50 \text{ } \Omega$		VSWR	max.	2 : 1
Noise power 25 kHz, bandwidth 45 MHz above $f_0$ ; $P_{out} = 2.5 \text{ W}$ by adjustment of $V_{control}$		Noise power max.		-88 dBm

**Stability**

The module will produce no spurious signals  $> -60 \text{ dB}$  below the carrier signal when operated with a load mismatch  $VSWR < 3 : 1$  (all phases) and  $V_{S1} = 0.5$  to  $6.0 \text{ V}$ ,  $V_{S2} = V_{S3} = 7.9$  to  $12 \text{ V}$ .  $P_D = 10$  to  $40 \text{ mW}$  and  $T_h \leq 90 \text{ }^\circ\text{C}$ , provided maximum ratings are not exceeded.  $V_{S1} \leq V_{S2}$  and  $V_{S3}$ .

**Ruggedness**

The module will withstand a load mismatch of  $50 : 1$  (all phases) for short periods when operated with  $V_{S1} < 8 \text{ V}$ ,  $V_{S2} = V_{S3} \leq 13 \text{ V}$ ,  $P_D \leq 50 \text{ mW}$  and  $T_h \leq 90 \text{ }^\circ\text{C}$ , provided maximum ratings are not exceeded.

**Mounting**

To ensure good thermal transfer the module should be mounted onto a heatsink with a flat surface with heat-conducting compound applied between module and the heatsink. The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of  $245 \text{ }^\circ\text{C}$  for not more than 10 seconds at a distance of at least  $1 \text{ mm}$  from the plastic.

**Power rating**

In general, it is recommended that the output power from the module under nominal conditions should not exceed  $3.0 \text{ W}$  in order to provide an adequate safety margin under fault conditions.

**Gain control**

The module is designed to be operated at a nominal output power of  $2.5 \text{ W}$ . The module is adjusted to produced nominal output power by reducing the first stage supply voltage  $V_{S1}$ . The output power may be varied from  $6 \text{ mW}$  to  $2.5 \text{ W}$  by varying  $V_{S1}$  from  $0.5 \text{ V}$  to  $6 \text{ V}$ .

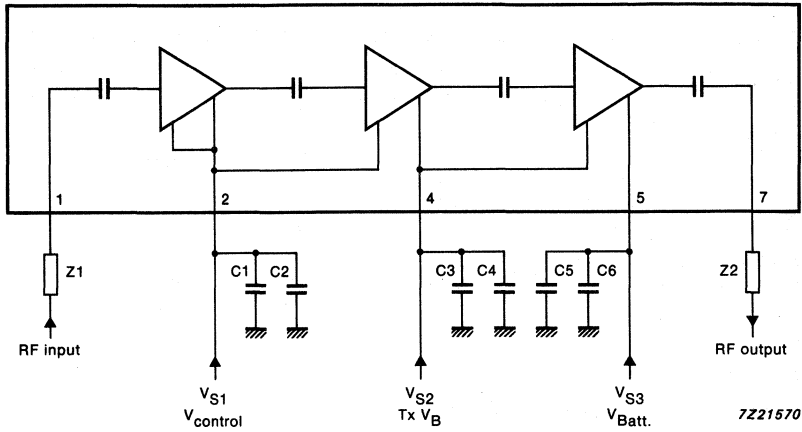
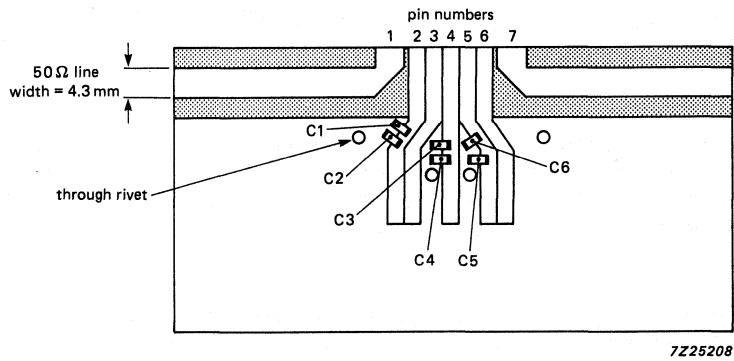


Fig.3 Internal diagram.

- Z1 = Z2 = 50  $\Omega$  stripline
- C1 = C3 = C6 = 0.01  $\mu$ F ceramic chip capacitor
- C2 = C4 = C5 = 1.0  $\mu$ F tantalum capacitor



Teflon glass board 1/16";  $\epsilon_r = 2.55$ .

Fig.4 Printed-circuit board layout.

BGY96A

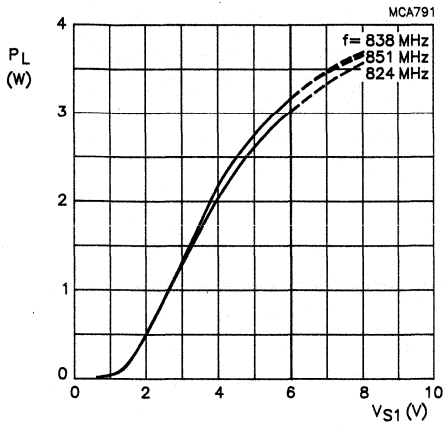


Fig.5 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 9.6$  V.

BGY96B

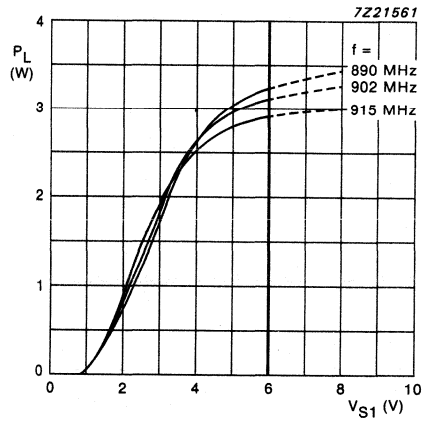


Fig.6 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 9.6$  V.

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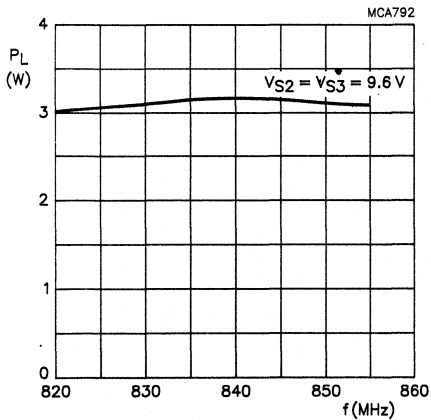


Fig.7 Load power as a function of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

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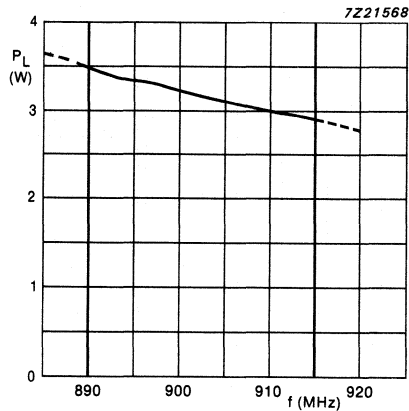


Fig.8 Load power as a function of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

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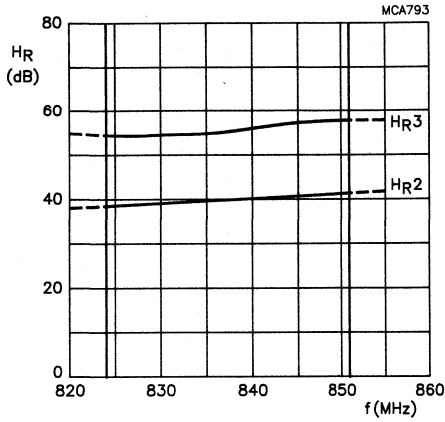


Fig.9 Second and third harmonic rejections as functions of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

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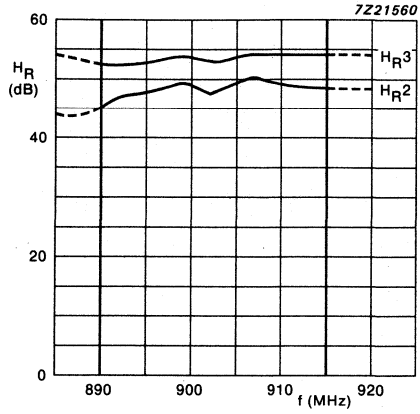


Fig.10 Second and third harmonic rejections as functions of frequency;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

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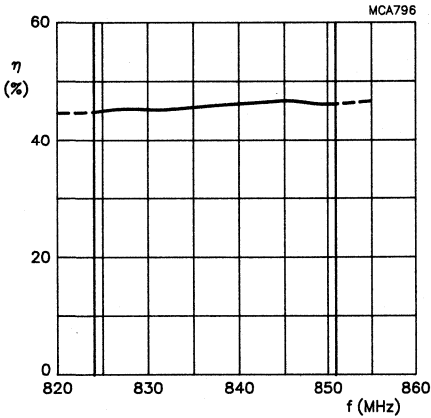


Fig.11 Efficiency as a function of frequency;  $P_D = 20$  mW;  $P_L = 2.5$  W;  $V_{S2} = V_{S3} = 9.6$  V.

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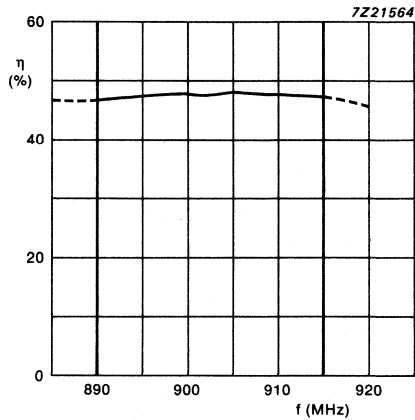


Fig.12 Efficiency as a function of frequency;  $P_D = 20$  mW;  $P_L = 2.5$  W;  $V_{S2} = V_{S3} = 9.6$  V.



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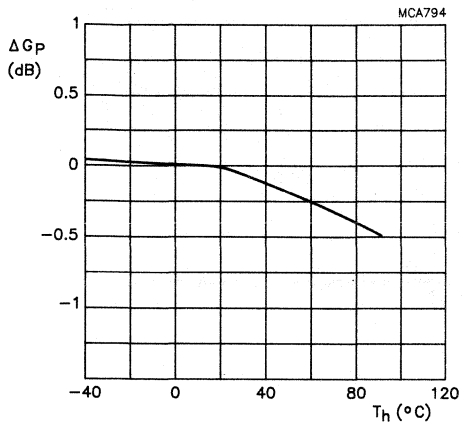


Fig. 13 Change in power gain as a function of heatsink temperature;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V;  $f = 838$  MHz.

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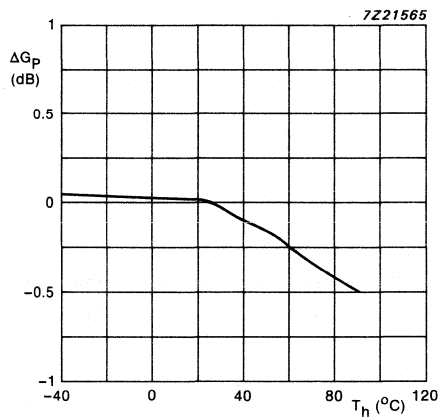


Fig. 14 Change in power gain as a function of heatsink temperature;  $P_D = 20$  mW;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V;  $f = 915$  MHz.

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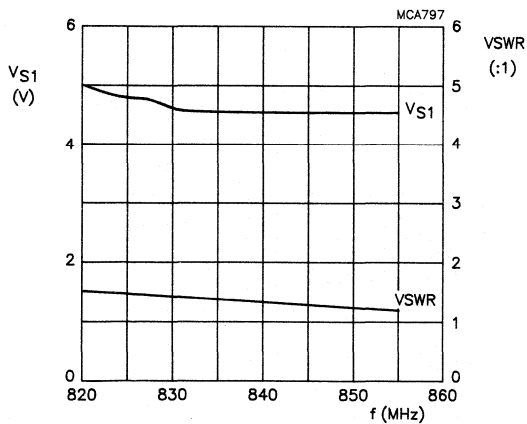


Fig. 15 Supply voltage  $V_{S1}$  and VSWR as functions of frequency;  $P_D = 20$  mW;  $P_L = 2.5$  W;  $V_{S2} = V_{S3} = 9.6$  V.

BGY96B

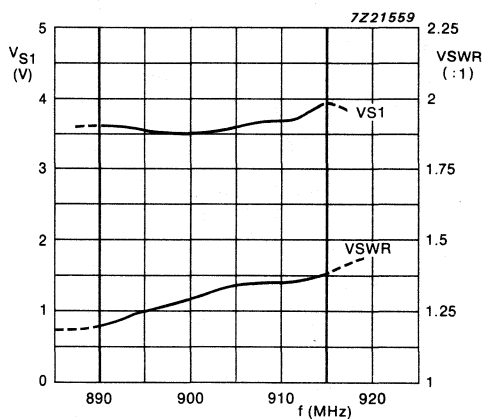


Fig. 16 Supply voltage  $V_{S1}$  and VSWR as functions of frequency;  $P_D = 20$  mW;  $P_L = 2.5$  W;  $V_{S2} = V_{S3} = 9.6$  V.

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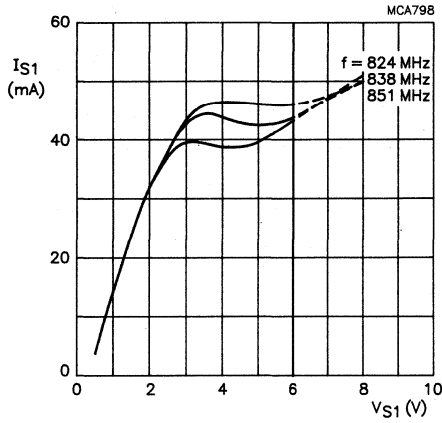


Fig.17 Supply current  $I_{S1}$  as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 9.6$  V.

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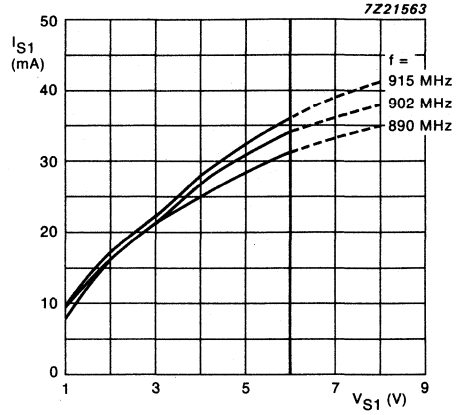


Fig.18 Supply current  $I_{S1}$  as a function of supply voltage  $V_{S1}$ ;  $P_D = 20$  mW;  $V_{S2} = V_{S3} = 9.6$  V.

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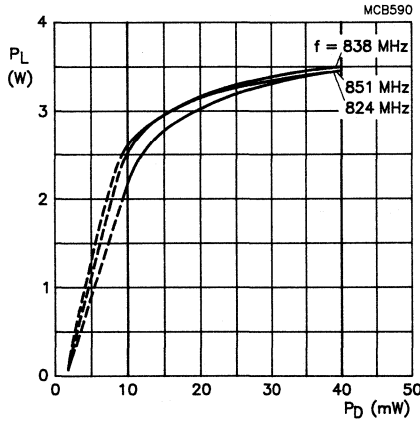


Fig.19 Load power as a function of drive power;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

BGY96B

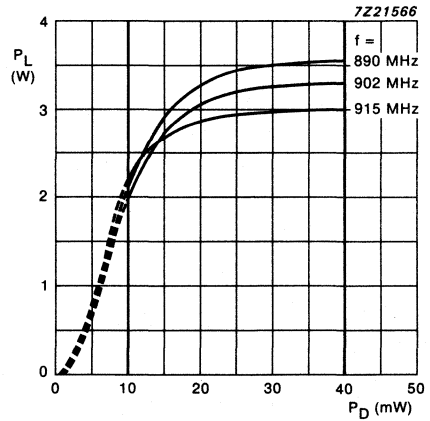


Fig.20 Load power as a function of drive power;  $V_{S1} = 6$  V;  $V_{S2} = V_{S3} = 9.6$  V.

# DEVELOPMENT DATA

This data sheet contains advance information and specifications are subject to change without notice.

BGY110A

## UHF AMPLIFIER MODULE

The BGY110A is a four-stage UHF amplifier module designed primarily for hand-held transmitting equipment, operating from a nominal 6 V power supply.

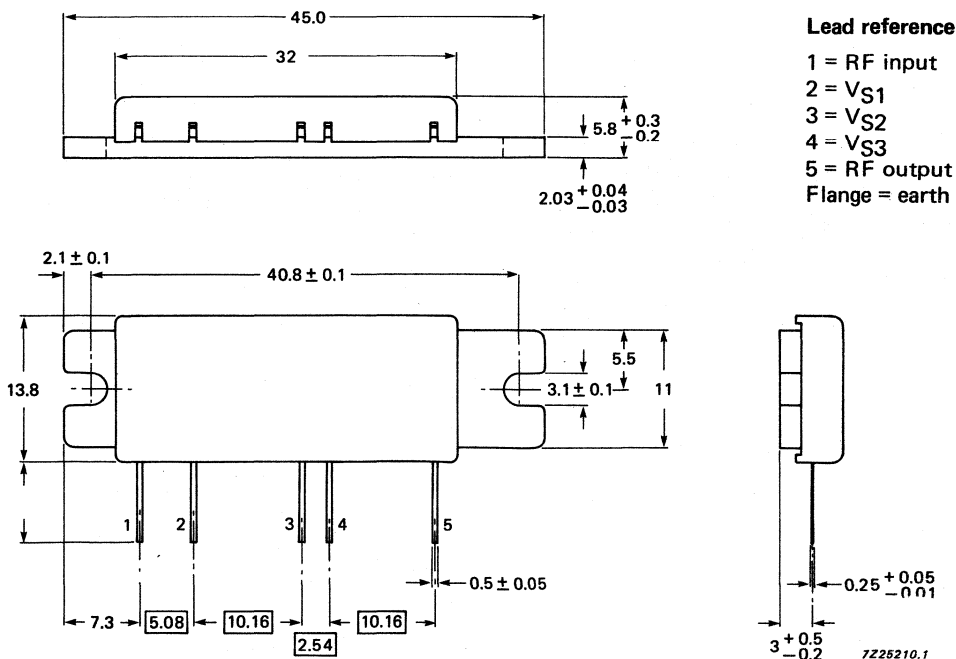
The module consists of four npn silicon planar transistor chips mounted on a metallized ceramic substrate, together with matching and bias circuitry. The module produces an output power of 1.2 W into a  $50 \Omega$  load over the frequency band of 824 - 849 MHz. The output power can be controlled by means of a DC voltage ( $V_{S2}$ ).

### QUICK REFERENCE DATA

Mode of operation	CW
Frequency range	f 824 to 849 MHz
Supply voltage	$V_S$ 6.0 V
Load power	$P_L$ min. 1.2 W
Gain	G min. 30.8 dB
Load impedance	$Z_L$ nom. $50 \Omega$

### MECHANICAL DATA

Dimensions in mm



**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}, V_{S2}, V_{S3}$	max.	8.0 V
RF input terminal voltage*	$+V_{in}$	max.	25 V
RF output terminal voltage*	$+V_{out}$	max.	25 V
RF load power	$P_L$	max.	1.6 W
RF drive power	$P_D$	max.	2.0 mW
Storage temperature range	$T_{stg}$		-40 to + 100 °C
Operating heatsink temperature	$T_h$	max.	90 °C

**CHARACTERISTICS**

$V_{S1} = V_{S2} = V_{S3} = 6 \text{ V}$ ;  $T_h = 25 \text{ °C}$ ;  $f = 824 - 849 \text{ MHz}$ ;  $R_S = R_L = 50 \text{ } \Omega$  unless otherwise specified

Load power			
$P_D = 1 \text{ mW}$	$P_L$	min.	1.2 W
Efficiency			
$P_L = 1.2 \text{ W}$	$\eta$	min.	40 %
Harmonic rejection			
$P_L = 1.2 \text{ W}$	d2	min.	40 dB
	d3	min.	45 dB
Input VSWR			
$P_L = 1.2 \text{ W}$	VSWR	max.	2 : 1
Gain control			
$P_D = 1 \text{ mW}$	$\Delta G_p$	min.	30 dB
Power switching			
$V_{S1} = 0 \text{ V}$ ; $P_D = 1 \text{ mW}$	$P_L$	max.	-20 dBm

**Stability**

All spurious signals will be at least 60 dB below the desired output signal level with a load mismatch  $VSWR < 3 : 1$  when operated with  $V_{S1}, V_{S3} = 4 \text{ to } 8 \text{ V}$  and  $V_{S2} = 0 \text{ to } 8 \text{ V}$ ;  $P_D = 0.5 \text{ to } 2 \text{ mW}$ , providing maximum ratings are not exceeded.

**Ruggedness**

The module will withstand a load mismatch of 50 : 1 under the following conditions:  $P_D = 1 \text{ mW}$ ;  $V_{S1}, V_{S3} = 8 \text{ V}$ ;  $P_L = 1.6 \text{ W}$  (matched).

# DEVELOPMENT DATA

This data sheet contains advance information and specifications are subject to change without notice.

BGY110B

## UHF AMPLIFIER MODULE

The BGY110B is a four-stage UHF amplifier module designed primarily for hand-held transmitting equipment, operating from a nominal 6 V power supply.

The module consists of four npn silicon planar transistor chips mounted on a metallized ceramic substrate, together with matching and bias circuitry. The module produces an output power of 1.2 W into a  $50 \Omega$  load over the frequency band of 872 - 905 MHz. The output power can be controlled by means of a DC voltage ( $V_{S2}$ ).

### QUICK REFERENCE DATA

	CW
Mode of operation	f
Frequency range	872 to 905 MHz
Supply voltage	$V_S$ 6.0 V
Load power	$P_L$ min. 1.2 W
Gain	G min. 30.8 dB
Load impedance	$Z_L$ nom. $50 \Omega$

### MECHANICAL DATA

Dimensions in mm

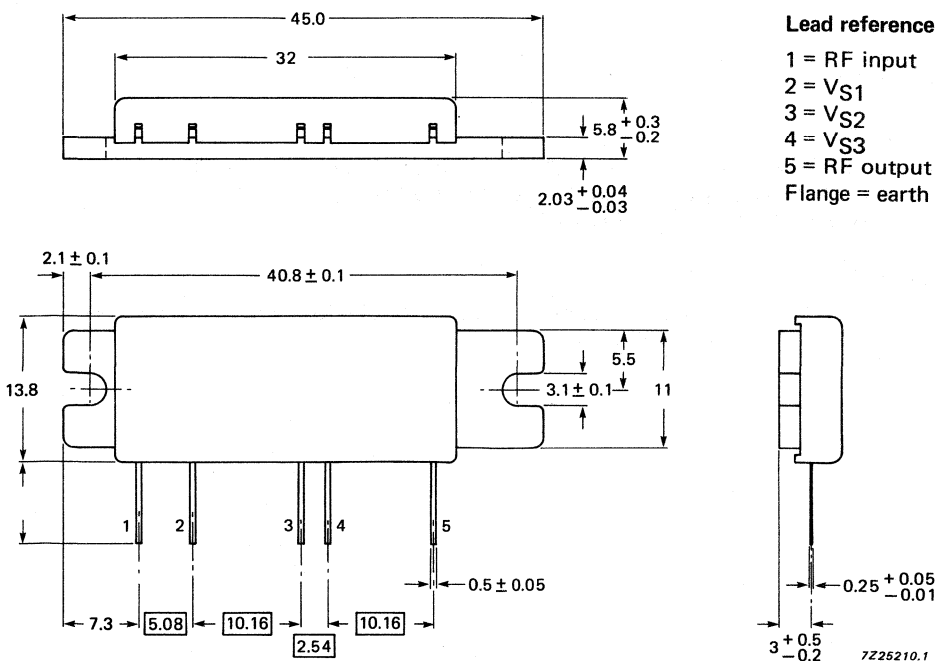


Fig. 1 SOT-246.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

DC supply terminal voltages*	$V_{S1}, V_{S2}, V_{S3}$	max.	8.0 V
RF input terminal voltage*	$+V_{in}$	max.	25 V
RF output terminal voltage*	$+V_{out}$	max.	25 V
RF load power	$P_L$	max.	1.6 W
RF drive power	$P_D$	max.	2.0 mW
Storage temperature range	$T_{stg}$		-40 to + 100 °C
Operating heatsink temperature	$T_h$	max.	90 °C

**CHARACTERISTICS**

$V_{S1} = V_{S2} = V_{S3} = 6 \text{ V}$ ;  $T_h = 25 \text{ °C}$ ;  $f = 872 - 905 \text{ MHz}$ ;  $R_S = R_L = 50 \text{ } \Omega$  unless otherwise specified

Load power			
$P_D = 1 \text{ mW}$	$P_L$	min.	1.2 W
Efficiency			
$P_L = 1.2 \text{ W}$	$\eta$	min.	40 %
Harmonic rejection			
$P_L = 1.2 \text{ W}$	d2	min.	40 dB
	d3	min.	45 dB
Input VSWR			
$P_L = 1.2 \text{ W}$	VSWR	max.	2 : 1
Gain control			
$P_D = 1 \text{ mW}$	$\Delta G_p$	min.	30 dB
Power switching			
$V_{S1} = 0 \text{ V}$ ; $P_D = 1 \text{ mW}$	$P_L$	max.	-20 dBm

**Stability**

All spurious signals will be at least 60 dB below the desired output signal level with a load mismatch  $VSWR < 3 : 1$  when operated with  $V_{S1}, V_{S3} = 4 \text{ to } 8 \text{ V}$  and  $V_{S2} = 0 \text{ to } 8 \text{ V}$ ;  $P_D = 0.5 \text{ to } 2 \text{ mW}$ , providing maximum ratings are not exceeded.

**Ruggedness**

The module will withstand a load mismatch of 50 : 1 under the following conditions:  $P_D = 1 \text{ mW}$ ;  $V_{S1}, V_{S3} = 8 \text{ V}$ ;  $P_L = 1.6 \text{ W}$  (matched).

Data sheet	
status	Product specification
date of issue	May 1991

# BGY110D/BGY110E/BGY110F

## UHF amplifier modules

### DESCRIPTION

The BGY110 is a four-stage UHF amplifier module, primarily designed for hand-held transmitting equipment operating from a nominal 7.2 V power supply.

The module consists of four npn silicon planar transistor chips, mounted on a metallized ceramic substrate, together with matching and bias circuitry. The BGY110D, 110E and 110F produce an output power of 1.7 W into a 50 Ω load over the frequency band 824 to 849 MHz, 872 to 905 MHz and 890 to 915 MHz respectively. The output power can be controlled by means of a DC voltage ( $V_C$ ).

### MECHANICAL DATA

SOT246 - see Fig.1.

### QUICK REFERENCE DATA

RF performance at  $T_{mb} = 25\text{ }^\circ\text{C}$ .

TYPE NUMBER	MODE OF OPERATION	f (MHz)	$V_S$ (V)	$V_C$ (V)	$P_L$ (W)	$G_P$ (dB)	$\eta$ (%)	$Z_i/Z_L$ ( $\Omega$ )
BGY110D	c.w.	824 - 849	7.2	4.5	1.7	> 32.3	> 39	50
BGY110E	c.w.	872 - 905	7.2	4.5	1.7	> 32.3	> 39	50
BGY110F	c.w.	890 - 915	7.2	4.5	1.7	> 32.3	> 39	50

## UHF amplifier modules

## BGY110D/BGY110E/BGY110F

## MECHANICAL DATA

Dimensions in mm

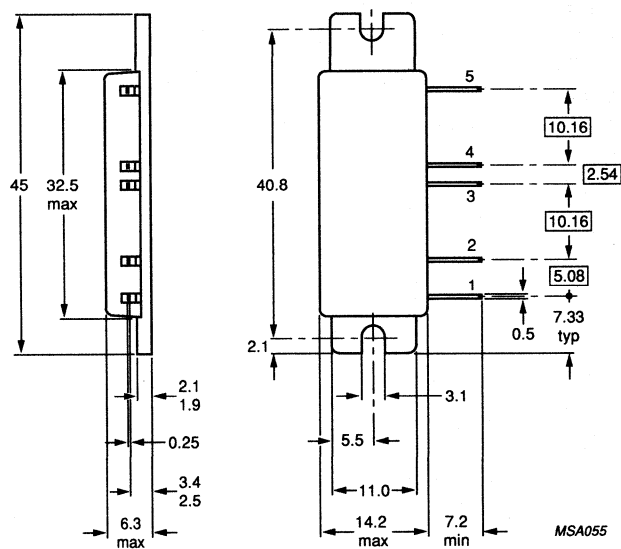


Fig.1 SOT246.

## PINNING

PIN	DESCRIPTION
1	RF input/ $V_C$
2	$V_{S1}$
3	$V_{S2}$
4	$V_{S3}$
5	RF output
flange	earth



## UHF amplifier modules

## BGY110D/BGY110E/BGY110F

## LIMITING VALUES

Limiting values in accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_{S1}; V_{S2}; V_{S3}$	DC supply voltage	-	10	V
$V_C$	DC control voltage	-	4.5	V
$+V_O$	RF output terminal	-	25	V
$P_L$	load power	-	2.25	W
$P_D$	input drive power	-	3	mW
$T_{stg}$	storage temperature range	-40	100	°C
$T_{mb}$	operating mounting base temperature	-	90	°C

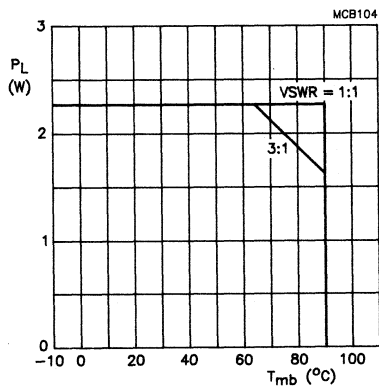


Fig. 2 Load power derating;  
 $V_{S1}; V_{S2}; V_{S3} = \text{max. } 9 \text{ V.}$

## UHF amplifier modules

## BGY110D/BGY110E/BGY110F

## CHARACTERISTICS

$T_{mb} = 25\text{ }^{\circ}\text{C}$ ,  $Z_i = Z_L = 50\text{ }\Omega$ ,  $V_{S1} = V_{S2} = V_{S3} = 7.2\text{ V}$ ,  $V_C = 4.5\text{ V}$ , unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range BGY110D		824	-	849	MHz
f	frequency range BGY110E		872	-	905	MHz
f	frequency range BGY110F		890	-	915	MHz
$I_{C2} + I_{C3}$	leakage current	$V_{S1} = V_C = 0$	-	-	200	$\mu\text{A}$
$P_L$	load power	$P_D = 1\text{ mW}$	1.7	-	-	W
$\eta$	efficiency	$P_L = 1.7\text{ W}$	39	-	-	%
$H_2$	second harmonic rejection	$P_L = 1.7\text{ W}$	40	-	-	dB
$H_3$	third harmonic rejection	$P_L = 1.7\text{ W}$	45	-	-	dB
	input VSWR	$P_L = 1.7\text{ W}$	-	-	2:1	
$\Delta G_p$	gain control	$V_C = 0 - 4.5\text{ V}$ $P_D = 1.0\text{ mW}$	30	-	-	dB
$P_L$	output power switching	$V_{S1} = V_C = 0$ $P_D = 1\text{ mW}$	-	-	-20	dBm
	noise power	30 kHz bandwidth $P_L = 1.7\text{ W}$ 45 MHz above $f_0$	-	-84	-80	dBm

## STABILITY

All non-harmonically related outputs shall be at least 60 dB down when the module is operated with a load mismatch up to  $VSWR = 6:1$  under the conditions  $V_{S1-2-3} = 6\text{ to }9\text{ V}$ ,  $V_C = 0\text{ to }4.5\text{ V}$ ,  $P_D = 0.5\text{ to }2\text{ mW}$  and  $P_L < 2\text{ W}$ .

## Ruggedness

The BGY110 is capable of withstanding a load mismatch corresponding to  $VSWR = 10:1$  through all phases, under the following conditions:  $P_D = 1\text{ mW}$ ,  $V_{S1-2-3} = 9\text{ V}$  and  $P_L = 1.8\text{ W}$ .

## UHF amplifier modules

## BGY110D/BGY110E/BGY110F

## APPLICATION INFORMATION

Conditions:  $T_{mb} = 25\text{ }^{\circ}\text{C}$ ,  $P_D = 1\text{ mW}$ ,  $P_L = 1.7\text{ W}$ ,  
 $V_{S1} = V_{S2} = V_{S3} = 7.2\text{ V}$ , unless otherwise specified; typical values.

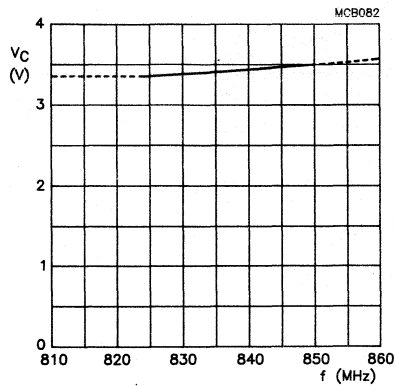


Fig.3 Control voltage as a function of frequency, BGY110D.

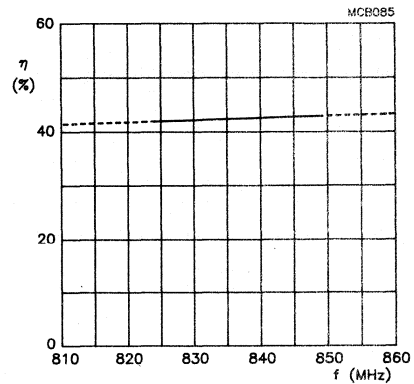


Fig.4 Efficiency as a function of frequency, BGY110D.

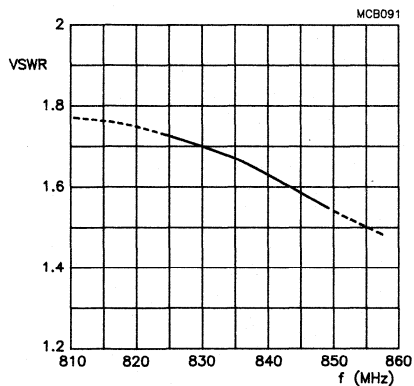


Fig.5 VSWR input as a function of frequency, BGY110D.

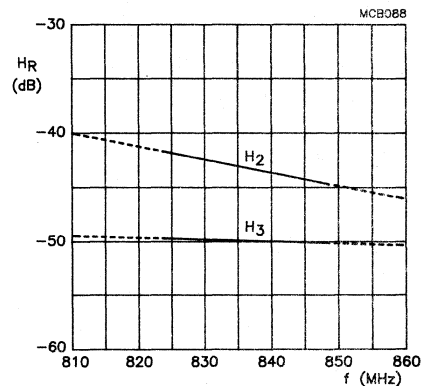


Fig.6 Harmonics as a function of frequency, BGY110D.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**

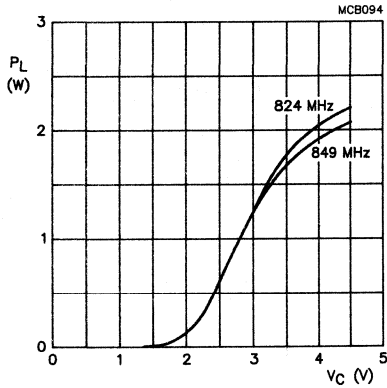


Fig.7 Load power as a function of control voltage, BGY110D.

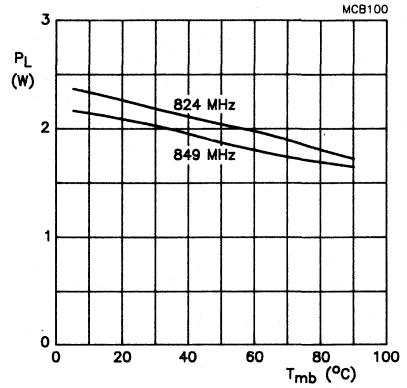


Fig.8 Load power as a function of temperature,  $V_C = 4.5$  V; BGY110D.

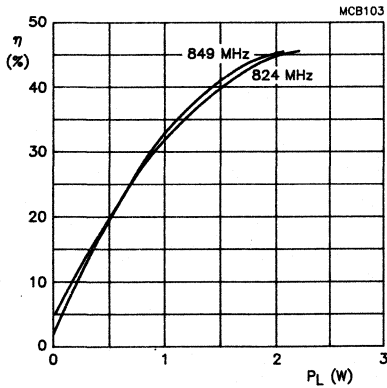


Fig.9 Efficiency as a function of load power, BGY110D.

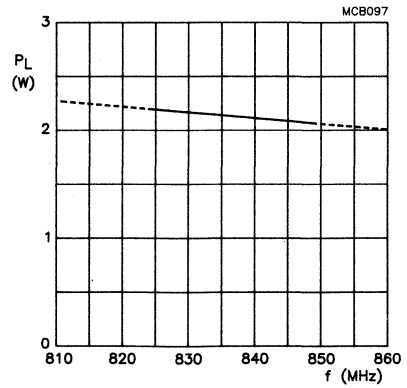


Fig.10 Load power as a function of frequency,  $V_C = 4.5$  V; BGY110D.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**

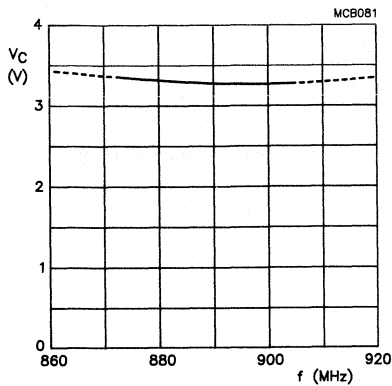


Fig.11 Control voltage as a function of frequency, BGY110E.

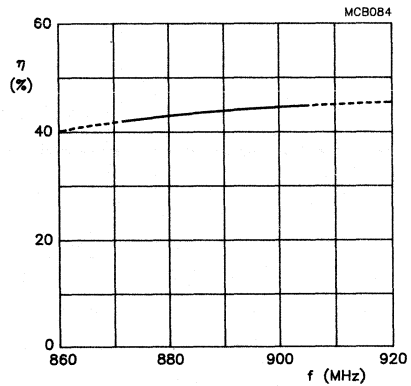


Fig.12 Efficiency as a function of frequency, BGY110E.

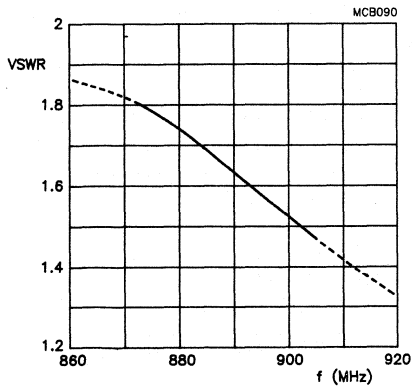


Fig.13 VSWR input as a function of frequency, BGY110E.

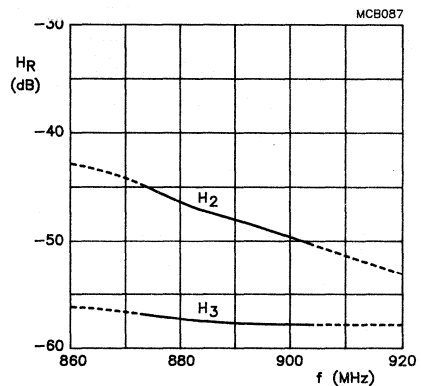


Fig.14 Harmonics as a function of frequency, BGY110E.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**

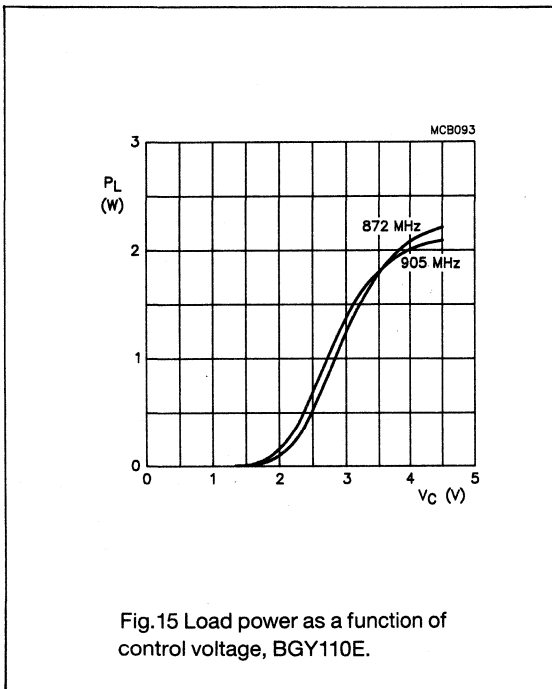


Fig.15 Load power as a function of control voltage, BGY110E.

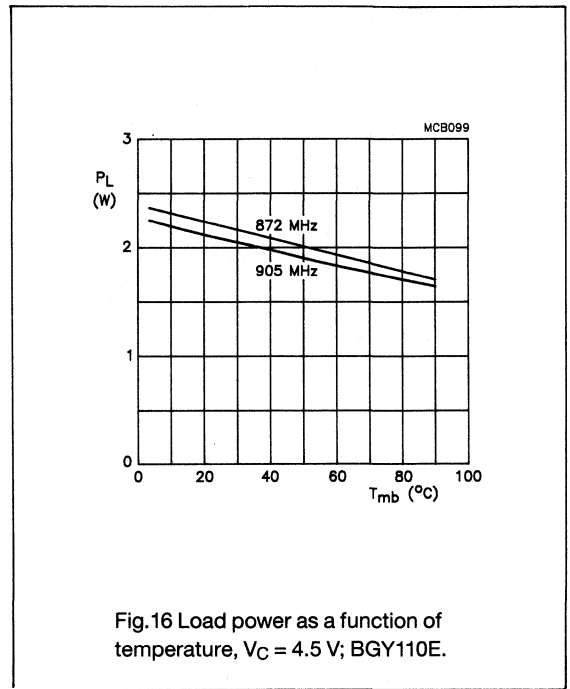


Fig.16 Load power as a function of temperature, V<sub>C</sub> = 4.5 V; BGY110E.

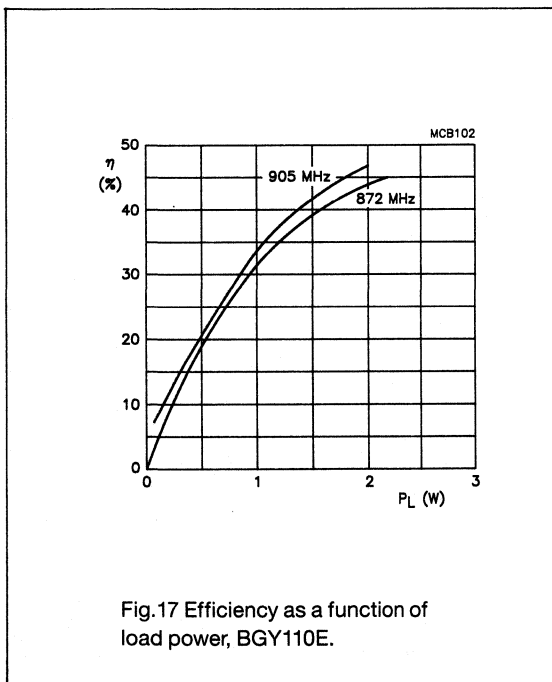


Fig.17 Efficiency as a function of load power, BGY110E.

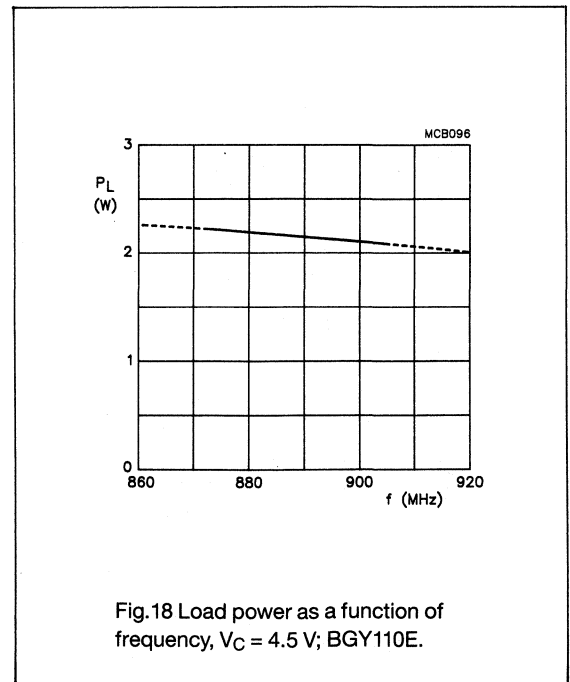


Fig.18 Load power as a function of frequency, V<sub>C</sub> = 4.5 V; BGY110E.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**

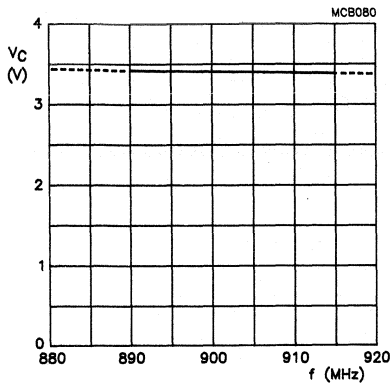


Fig.19 Control voltage as a function of frequency, BGY110F.

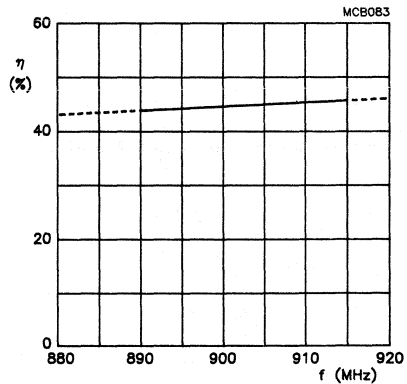


Fig.20 Efficiency as a function of frequency, BGY110F.

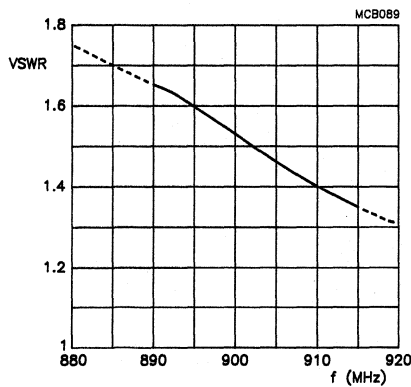


Fig.21 VSWR input as a function of frequency, BGY110F.

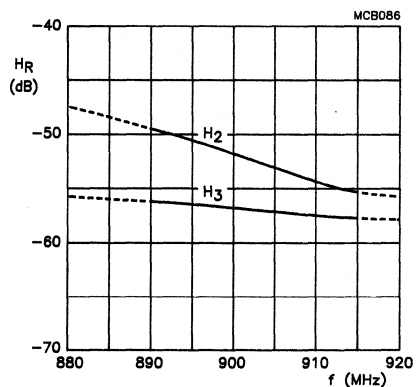
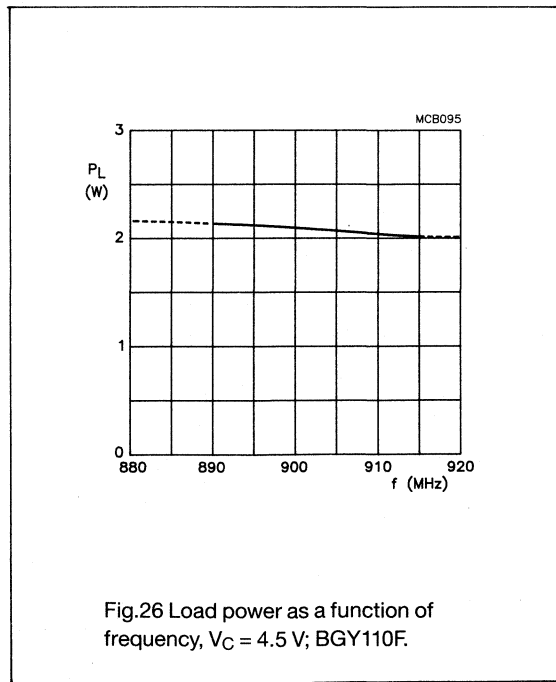
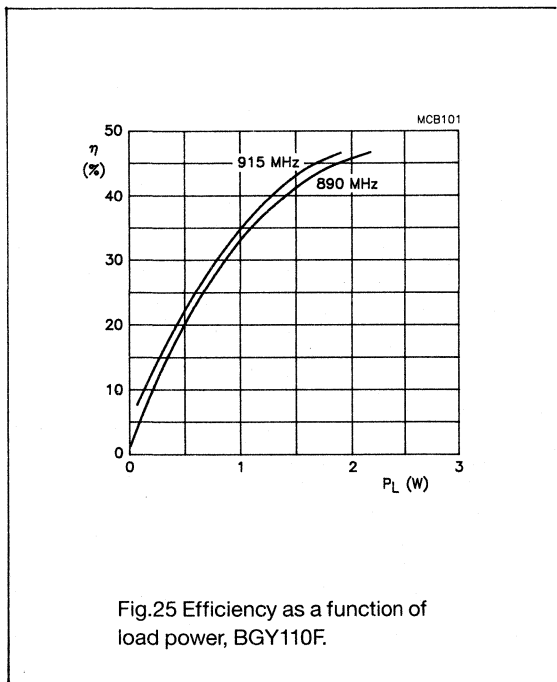
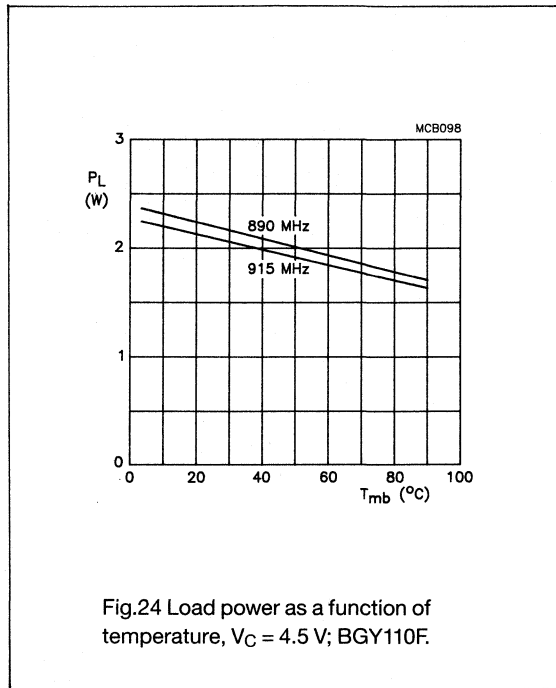
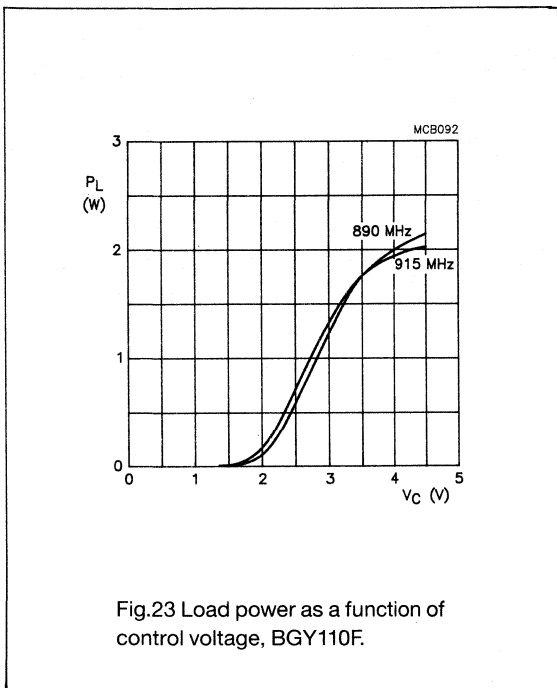


Fig.22 Harmonics as a function of frequency, BGY110F.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**





# UHF amplifier modules

# BGY110D/BGY110E/BGY110F

### List of components (Fig.27)

DESIGNATION	DESCRIPTION	VALUE	DIMENSIONS	CATALOGUE NO.
C1, C4, C7	multilayer chip capacitor	100 nF		
C2, C5, C8	tantalum capacitor	2.2 $\mu$ F		
C3, C6, C9	multilayer chip capacitor	33 pF		
C10, C11	multilayer chip capacitor	1 nF		
C12	tantalum capacitor	1 $\mu$ F		
L1, L2, L3	RF choke, 1 turn copper wire on grade 3B core	2.2 $\mu$ H	0.4 mm	4330 030 32221
L4	Ferroxcube coil	5 $\mu$ H		3122 108 20153
Z1, Z2	stripline note 1	50 $\Omega$		

### Notes

- Z1 and Z2 striplines are on a double copper-clad printed-circuit board with PTFE ( $\epsilon_r = 2.2$ ), thickness 1/16 inch.

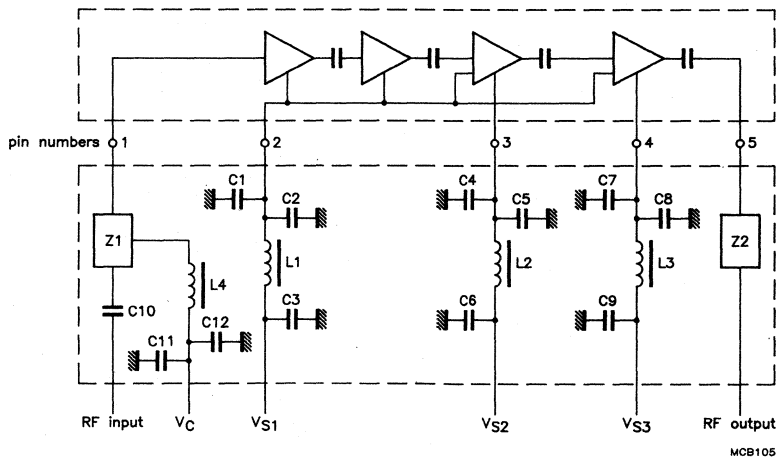


Fig.27 Test circuit BGY110D, BGY110E, BGY110F.

**UHF amplifier modules**

**BGY110D/BGY110E/BGY110F**

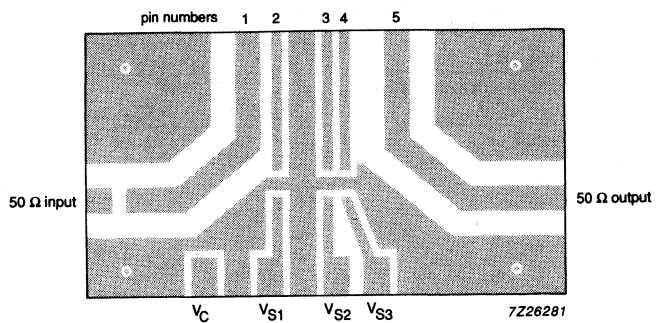


Fig.28 Printed-circuit board layout.

Data sheet	
status	Preliminary specification
date of issue	May 1991

# BGY112A/112B/112C

## VHF amplifier modules

### DESCRIPTION

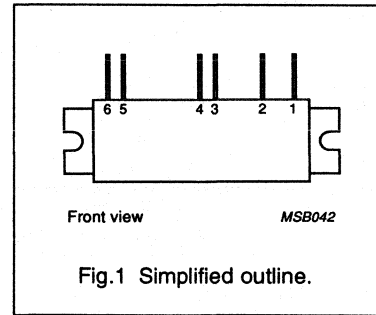
A range of RF power amplifier modules designed for use in portable communications equipment with nominal 7.5 V electrical battery supplies.

The devices are four stage RF amplifiers, consisting of npn bipolar transistors mounted on a single ceramic thick film metallized substrate, together with lumped elements that make up the matching and biasing circuits.

The module will produce a minimum output of 7 W into a 50 Ω load with a minimum power gain of 38.5 dB.

### PINNING - SOT288C

PIN	DESCRIPTION
1	RF input
2	V <sub>S1</sub>
3	V <sub>control</sub>
4	V <sub>S2</sub>
5	V <sub>S3</sub>
6	RF output flange



### QUICK REFERENCE DATA

Mode of operation: continuous wave.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range BGY112A BGY112B BGY112C		68 132 146	– – –	88 156 174	MHz MHz MHz
P <sub>L</sub>	RF output power	P <sub>D</sub> = 1 mW	7	–	–	W
G <sub>p</sub>	RF power gain	P <sub>L</sub> = 7 W	38.5	–	–	dB
η	efficiency	P <sub>L</sub> = 7 W	40	–	–	%
V <sub>s</sub>	DC supply voltage		–	7.5	–	V
Z <sub>i</sub>	input impedance		–	50	–	Ω
Z <sub>L</sub>	output load impedance		–	50	–	Ω

## VHF amplifier modules

## BGY112A/112B/112C

## LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_S$	DC supply voltage	–	9	V
$\pm V_i$	RF input terminal voltage	–	25	V
$\pm V_o$	RF output terminal voltage	–	25	V
$P_D$	RF input power	–	2	mW
$P_L$	RF output power	–	9	W
$T_{stg}$	storage temperature range	–40	100	°C
$T_h$	heatsink operating temperature	–	90	°C

## CHARACTERISTICS

$T_h = 25\text{ °C}$ ;  $V_S = 7.5\text{ V}$ ;  $R_S = R_L = 50\ \Omega$ ; frequency ranges as stated in 'Quick Reference Data'.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{\text{Q3}}$	quiescent current	$V_{S1} = V_{S2} = V_{\text{control}} = 0$ $V_{S3} = 7.5\text{ V}$	–	–	0.1	mA
$P_D$	RF input power	$P_L = 7\text{ W}$	–	–	1	mW
$G_p$	RF power gain	$P_L = 7\text{ W}$	38.5	–	–	dB
$\eta$	efficiency	$P_L = 7\text{ W}$	40	45	–	%
$H_{R2}, H_{R3}$	harmonic output	$P_L = 7\text{ W}$	–	–	–40	dBc
	input VSWR with respect to $50\ \Omega$	$P_L = 7\text{ W}$	–	–	2:1	

## STABILITY

The module is stable when operated into a load of 6:1 at all phases, providing the operating conditions are as follows:

$P_D = 0$  to  $2\text{ mW}$ ;  $P_L < 9\text{ W}$ ;  
 $V_{S1} = V_{S2} = V_{S3} = 5$  to  $9\text{ V}$ ;  $V_{\text{control}}$   
 adjusted for required  $P_L$ ; source  
 impedance VSWR max 3:1.

## OUTPUT POWER CONTROL

The module output should be limited to  $7\text{ W}$ . The preferred method of output power control is to fix  $V_{S1} = V_{S2} = V_{S3} = 7.5\text{ V}$ ,  $P_D$  at  $1\text{ mW}$  and vary  $V_{\text{control}}$ .

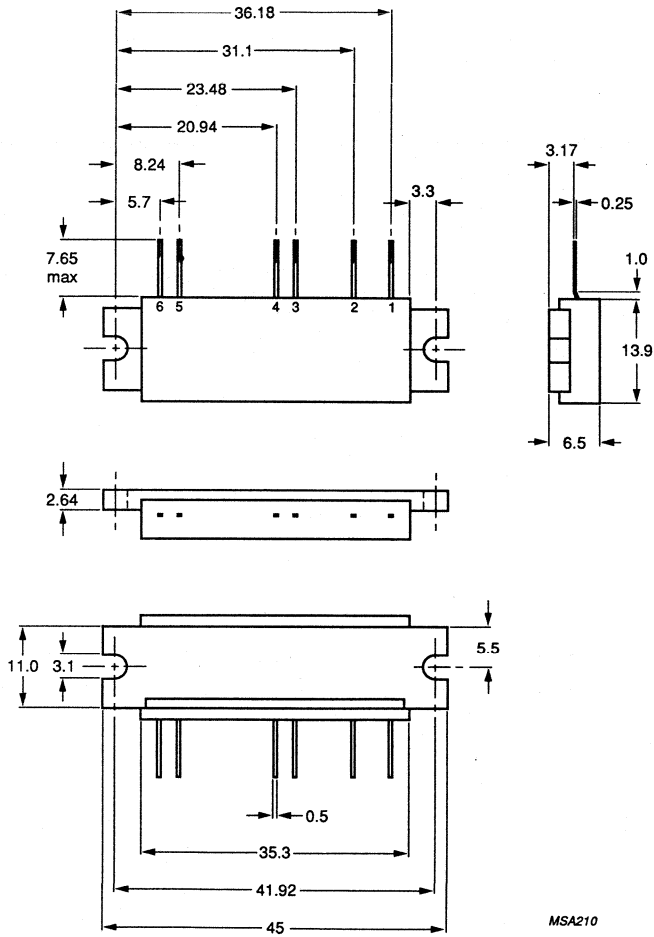
## RUGGEDNESS

The module will withstand a load of 50:1 for short period overload conditions, with  $P_D$ ,  $V_{S1}$  and  $V_{S2}$  at maximum values.

# VHF amplifier modules

# BGY112A/112B/112C

## PACKAGE OUTLINE



MSA210

Dimensions in mm.

Fig.2 SOT288C.



Data sheet	
status	Preliminary specification
date of issue	May 1991

# BGY113A/113B

## UHF amplifier modules

### DESCRIPTION

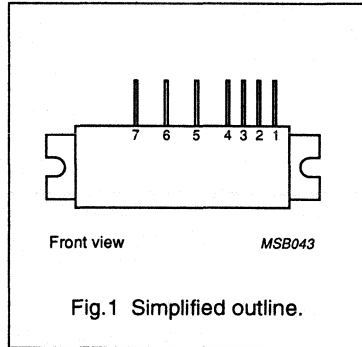
A range of RF power amplifier modules designed for use in portable communications equipment with nominal 7.5 V electrical battery supplies.

The devices are four stage RF amplifiers, consisting of npn bipolar transistors mounted on a single ceramic thick film metallized substrate, together with lumped elements that make up the matching and biasing circuits.

The module will produce a minimum output of 7 W into a 50 Ω load with a minimum power gain of 38.5 dB.

### PINNING - SOT288D

PIN	DESCRIPTION
1	RF input
2	V <sub>S1</sub>
3	V <sub>control</sub>
4	V <sub>S2</sub>
5	V <sub>S3</sub>
6	V <sub>S4</sub>
7	RF output
flange	ground



### QUICK REFERENCE DATA

Mode of operation: continuous wave.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range BGY113A BGY113B		400 430	– –	440 470	MHz MHz
P <sub>L</sub>	RF output power	P <sub>D</sub> = 1 mW	7	–	–	W
G <sub>p</sub>	RF power gain	P <sub>L</sub> = 7 W	38.5	–	–	dB
η	efficiency	P <sub>L</sub> = 7 W	40	–	–	%
V <sub>s</sub>	DC supply voltage		–	7.5	–	V
Z <sub>i</sub>	input impedance		–	50	–	Ω
Z <sub>L</sub>	output load impedance		–	50	–	Ω

## UHF amplifier modules

## BGY113A/113B

## LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_S$	DC supply voltage	–	9	V
$\pm V_i$	RF input terminal voltage	–	25	V
$\pm V_o$	RF output terminal voltage	–	25	V
$P_D$	RF input power	–	2	mW
$P_L$	RF output power	–	9	W
$T_{stg}$	storage temperature range	–40	100	°C
$T_h$	heatsink operating temperature	–	90	°C

## CHARACTERISTICS

$T_h = 25\text{ °C}$ ;  $V_S = 7.5\text{ V}$ ;  $R_S = R_L = 50\ \Omega$ ; frequency ranges as stated in 'Quick Reference Data'.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{O3}, I_{O4}$	quiescent current	$V_{S1} = V_{S2} = V_{control} = 0$ $V_{S3} = V_{S4} = 7.5\text{ V}$	–	–	0.1	mA
$P_D$	RF output power	$P_D = 1\text{ mW}$	7	–	–	W
$G_p$	RF power gain	$P_L = 7\text{ W}$	38.5	–	–	dB
$\eta$	efficiency	$P_L = 7\text{ W}$	40	45	–	%
$H_{R2}, H_{R3}$	harmonic output	$P_L = 7\text{ W}$	–	–	–40	dBc
	input VSWR with respect to $50\ \Omega$	$P_L = 7\text{ W}$	–	–	2:1	

## STABILITY

The module is stable when operated into a load of 6:1 at all phases, providing the operating conditions are as follows:

$P_D = 0$  to  $2\text{ mW}$ ;  $P_L < 9\text{ W}$ ;  
 $V_{S1} = V_{S2} = V_{S3} = V_{S4} = 5$  to  $9\text{ V}$ ;  
 $V_{control}$  adjusted for required  $P_L$ ;  
 source impedance VSWR max 3:1.

## OUTPUT POWER CONTROL

The module output should be limited to  $7\text{ W}$ . The preferred method of output power control is to fix  $V_{S1} = V_{S2} = V_{S3} = V_{S4} = 7.5\text{ V}$ ,  $P_D$  at  $1\text{ mW}$  and vary  $V_{control}$ .

## RUGGEDNESS

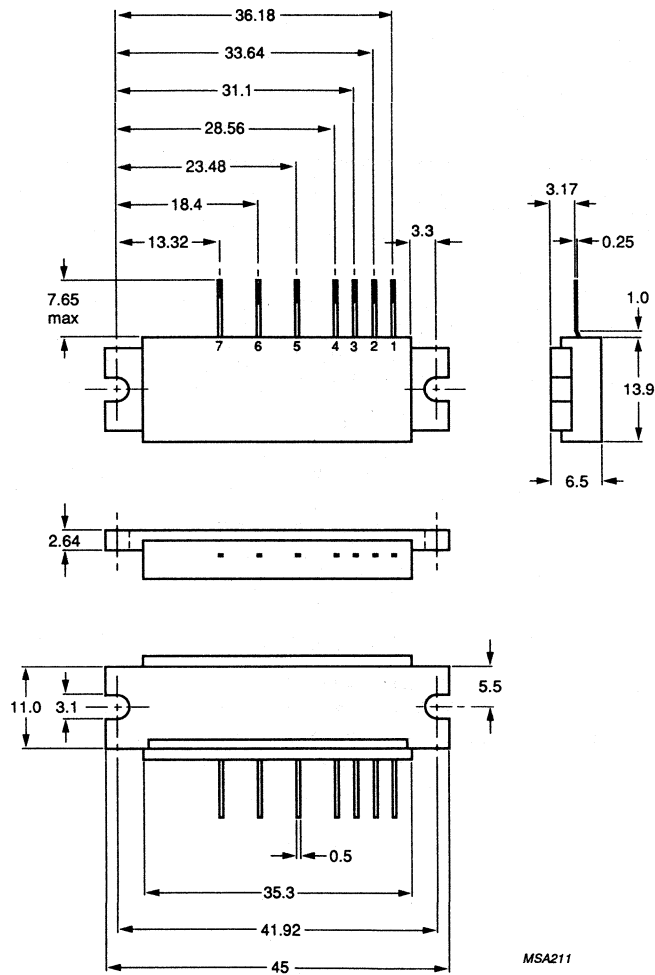
The module will withstand a load of 50:1 for short period overload conditions, with  $P_D$ ,  $V_{S1}$  and  $V_{S2}$  at maximum values.



**UHF amplifier modules**

**BGY113A/113B**

**PACKAGE OUTLINE**



MSA211

Dimensions in mm.

Fig.2 SOT288D.



## VHF amplifier module

BGY145A

## DESCRIPTION

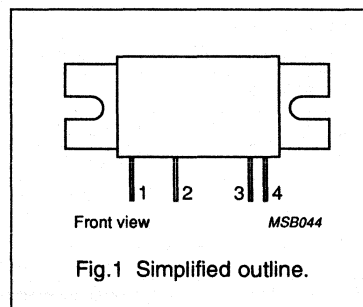
The BGY145A is a RF amplifier module, designed for use in transmitters of mobile communications equipment powered by vehicles with 12.5 V battery supplies.

The module is a two-stage transistor amplifier and consists of two RF npn transistors mounted on a ceramic substrate, together with surface mounted components that make up the matching and bias circuits.

The module will provide 29 W RF power into a 50  $\Omega$  load, when operated at nominal conditions within the frequency range of 68 to 88 MHz.

## PINNING - SOT183A

PIN	DESCRIPTION
1	output
2	$V_{S2}$
3	$V_{S1}$
4	input
flange	ground



## QUICK REFERENCE DATA

Mode of operation: continuous wave.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range		68	–	88	MHz
$P_D$	RF output power	$P_D = 150$ mW	29	–	–	W
$G_p$	RF power gain	$P_L = 29$ W	22.9	–	–	dB
$\eta$	efficiency	$P_L = 29$ W	37	–	–	%
$V_{S1}, V_{S2}$	DC supply voltage		–	12.5	–	V
$Z_i$	input impedance		–	50	–	$\Omega$
$Z_L$	output load impedance		–	50	–	$\Omega$

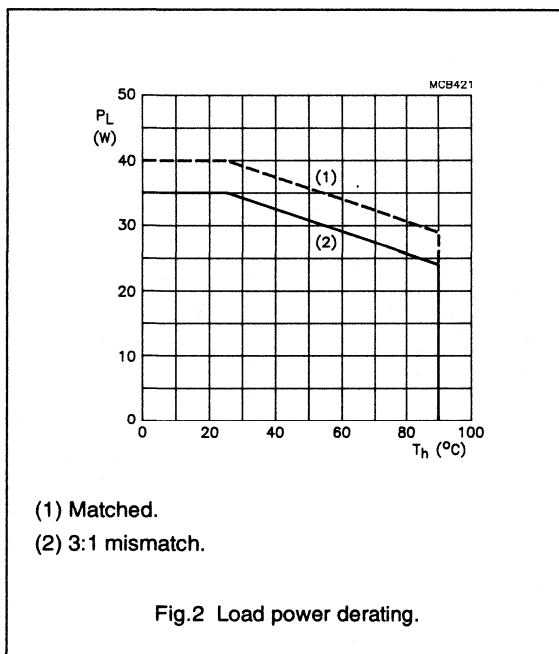
## VHF amplifier module

BGY145A

## LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_{S1}, V_{S2}$	DC supply voltage	–	15	V
$\pm V_i$	RF input terminal voltage	–	25	V
$\pm V_o$	RF output terminal voltage	–	25	V
$P_D$	RF input power	–	300	mW
$P_L$	RF output power (see Fig.2)	–	40	W
$T_{stg}$	storage temperature range	–30	100	°C
$T_h$	heatsink operating temperature	–	90	°C



## CHARACTERISTICS

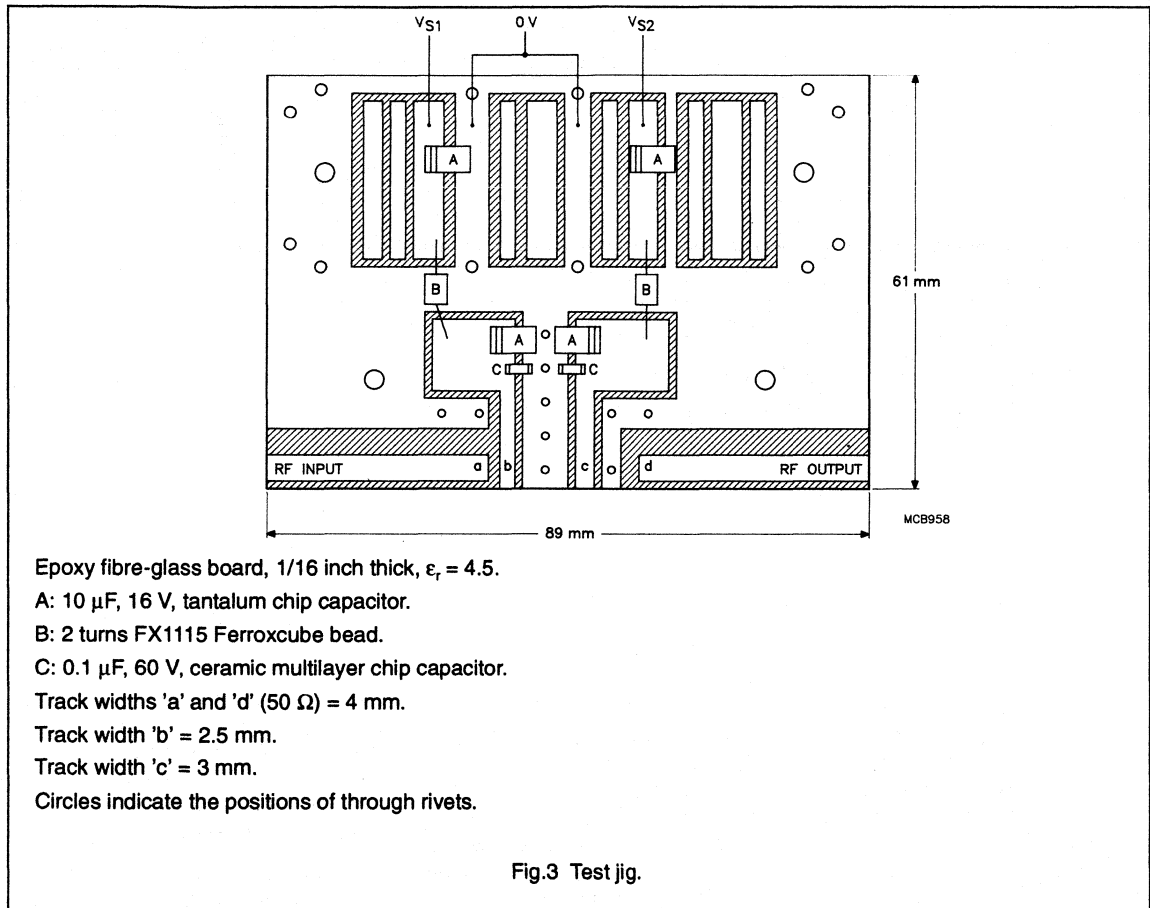
 $T_h = 25\text{ °C}$ ;  $V_{S1} = V_{S2} = 12.5\text{ V}$ ;  $R_S = R_L = 50\ \Omega$ ; frequency range = 68 to 88 MHz.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{O1}$	quiescent current	$P_D = 0$	–	10	25	mA
$I_{O2}$	quiescent current	$P_D = 0$	–	–	35	mA
$P_L$	RF output power	$P_D = 150\text{ mW}$	29	–	–	W
$G_p$	RF power gain	$P_L = 29\text{ W}$	22.9	–	–	dB
$\eta$	efficiency	$P_L = 29\text{ W}$	37	–	–	%
$H_{R2}$	2nd harmonic output	$P_L = 29\text{ W}$	–	–	–30	dBc
	input VSWR with respect to $50\ \Omega$	$P_L = 29\text{ W}$	–	–	2:1	

## VHF amplifier module

BGY145A

## APPLICATION INFORMATION



Epoxy fibre-glass board, 1/16 inch thick,  $\epsilon_r = 4.5$ .

A: 10  $\mu\text{F}$ , 16 V, tantalum chip capacitor.

B: 2 turns FX1115 Ferroxcube bead.

C: 0.1  $\mu\text{F}$ , 60 V, ceramic multilayer chip capacitor.

Track widths 'a' and 'd' ( $50 \Omega$ ) = 4 mm.

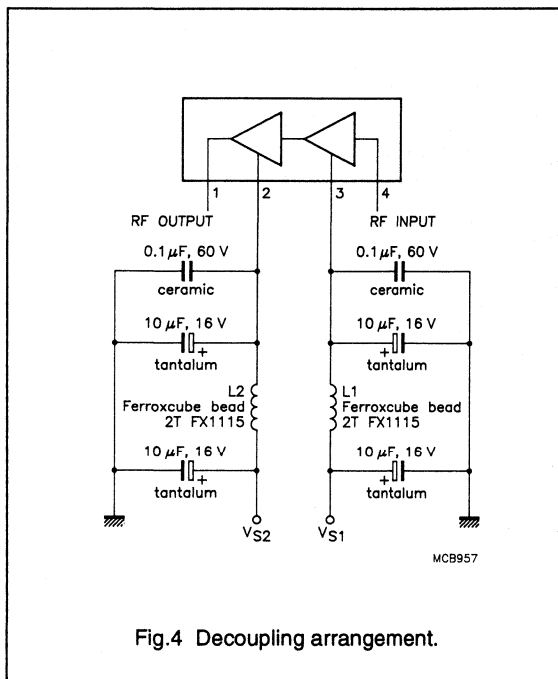
Track width 'b' = 2.5 mm.

Track width 'c' = 3 mm.

Circles indicate the positions of through rivets.

## VHF amplifier module

BGY145A

**STABILITY**

The module is stable when operated into a load of 3:1 at all phases, under the following conditions, providing maximum ratings are not exceeded:

$$P_D \text{ 30 to 300 mW; } P_L \leq 40 \text{ W;}$$

$$V_{S1} = 6 \text{ to 15 V; } V_{S2} = 10 \text{ to 15 V and}$$

$$V_{S1} < V_{S2}.$$

**RUGGEDNESS**

The output power of the module into a 50  $\Omega$  load will be unchanged after one minute of operation into a load mismatch of 20:1 (any phase), providing maximum ratings are not exceeded.

$$V_{S1}, V_{S2} \leq 15 \text{ V; } T_h \leq 90 \text{ }^\circ\text{C;}$$

$$P_L \leq 40 \text{ W; } P_D < 300 \text{ mW.}$$

**RF POWER CONTROL**

The module is not designed to be operated over a wide range of output levels. The aim of the output power control is to set the nominal output level. The preferred method of output power control is by varying the drive power between 30 and 200 mW. Another option is to vary  $V_{S1}$  between 6 and 12.5 V.

**CAUTIONS**

The main earth return path for this module is via the flange. Therefore, it is important that the heatsink is well earthed and that the return paths are kept as short as possible. Failure to do this may result in loss of output power or oscillation, which will have a detrimental effect upon the life of the module.

The RF output connection should be made to correctly designed 50  $\Omega$  terminals. Failure to do so will result in a mismatch being presented to the module, with a resultant reduction in module life.

The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245  $^\circ\text{C}$ , for not more than 10 seconds at a distance of at least 1 mm from the plastic.

Under no circumstances must the maximum specified operating or storage temperatures be exceeded, even for short periods.

VHF amplifier module

BGY145A

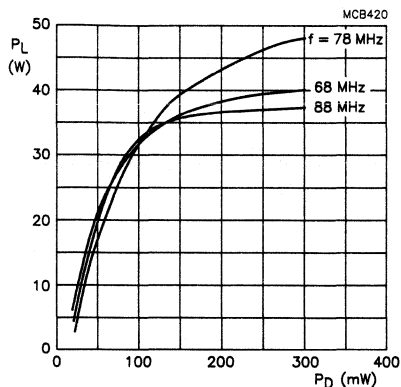


Fig.5 Load power as a function of drive power;  $V_{S1} = V_{S2} = 12.5$  V; typical values.

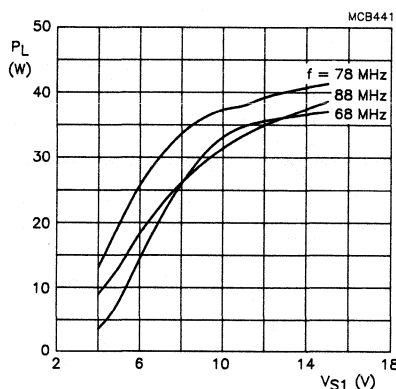


Fig.6 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 150$  mW; typical values.

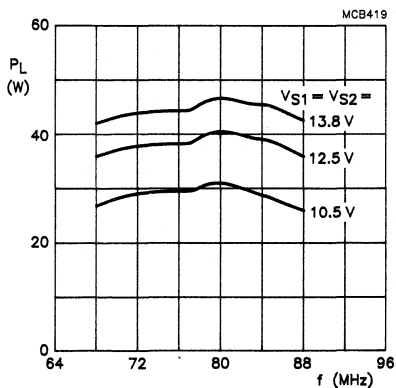


Fig.7 Load power as a function of frequency;  $P_D = 150$  mW; typical values.

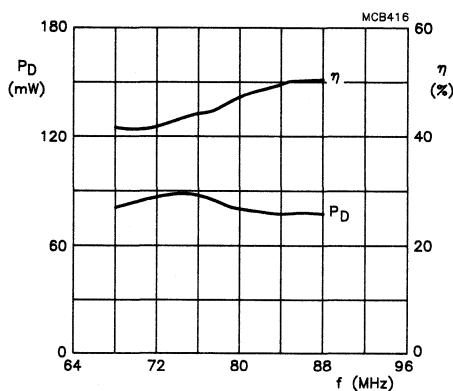
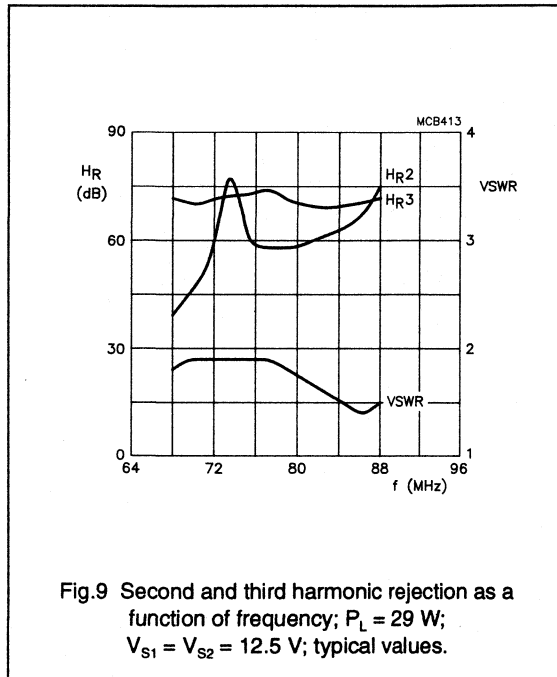


Fig.8 Efficiency and drive power as functions of frequency;  $P_L = 29$  W;  $V_{S1} = V_{S2} = 12.5$  V; typical values.

VHF amplifier module

BGY145A

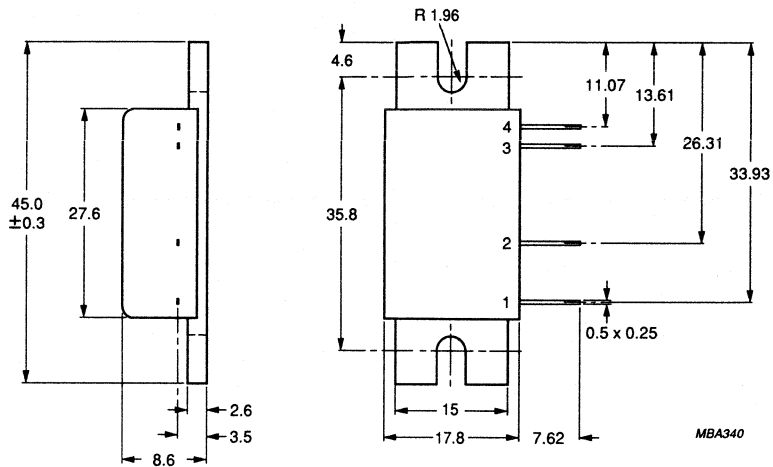




VHF amplifier module

BGY145A

PACKAGE OUTLINE



Dimensions in mm.

Fig.10 SOT183A.



## VHF amplifier module

## BGY145B

## DESCRIPTION

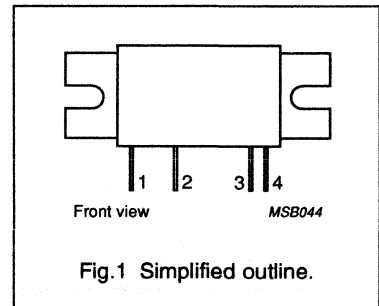
The BGY145B is a RF amplifier module, designed for use in transmitters of mobile communications equipment powered by vehicles with 12.5 V battery supplies.

The module is a two-stage transistor amplifier and consists of two RF npn transistors mounted on a ceramic substrate, together with surface mounted components that make up the matching and bias circuits.

The module will provide 28 W RF power into a 50  $\Omega$  load, when operated at nominal conditions within the frequency range of 146 to 174 MHz.

## PINNING - SOT183A

PIN	DESCRIPTION
1	output
2	$V_{S2}$
3	$V_{S1}$
4	input
flange	ground



## QUICK REFERENCE DATA

Mode of operation: continuous wave.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range		146	–	174	MHz
$P_D$	RF output power	$P_D = 300$ mW	28	–	–	W
$G_p$	RF power gain	$P_L = 28$ W	19.7	–	–	dB
$\eta$	efficiency	$P_L = 28$ W	40	–	–	%
$V_{S1}, V_{S2}$	DC supply voltage		–	12.5	–	V
$Z_i$	input impedance		–	50	–	$\Omega$
$Z_L$	output load impedance		–	50	–	$\Omega$

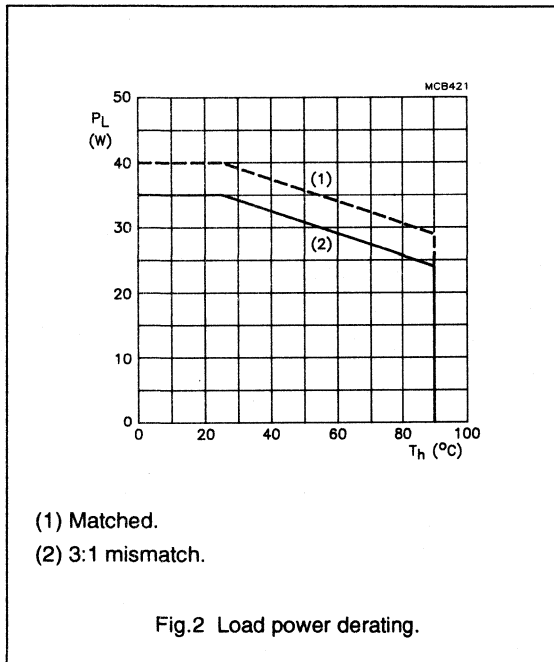
## VHF amplifier module

BGY145B

## LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_{S1}, V_{S2}$	DC supply voltage	–	15.5	V
$\pm V_i$	RF input terminal voltage	–	25	V
$\pm V_o$	RF output terminal voltage	–	25	V
$P_D$	RF input power	–	450	mW
$P_L$	RF output power (see Fig.2)	–	40	W
$T_{stg}$	storage temperature range	–30	100	°C
$T_h$	heatsink operating temperature	–	90	°C



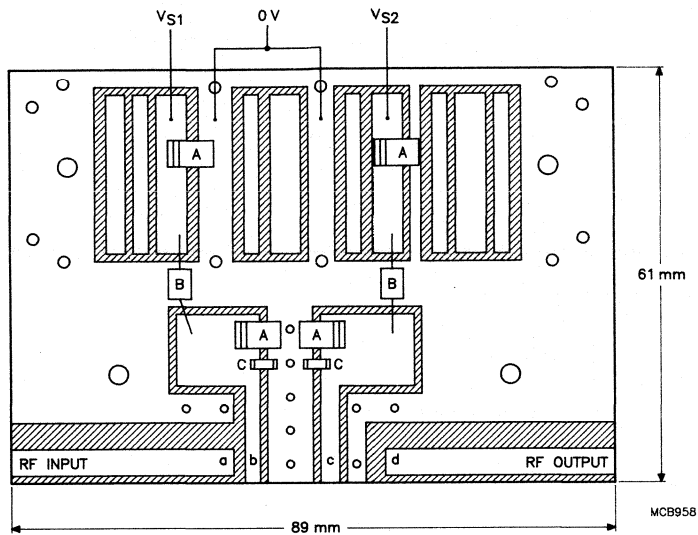
## CHARACTERISTICS

 $T_h = 25\text{ °C}$ ;  $V_{S1} = V_{S2} = 12.5\text{ V}$ ;  $R_S = R_L = 50\ \Omega$ ; frequency range = 146 to 174 MHz.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{Q1}$	quiescent current	$P_D = 0$	–	10	25	mA
$I_{Q2}$	quiescent current	$P_D = 0$	–	–	35	mA
$P_L$	RF output power	$P_D = 300\text{ mW}$	28	–	–	W
$G_p$	RF power gain	$P_L = 28\text{ W}$	19.7	–	–	dB
$\eta$	efficiency	$P_L = 28\text{ W}$	40	–	–	%
$H_{R2}, H_{R3}$	2nd & 3rd harmonic outputs	$P_L = 28\text{ W}$	–	–	–30	dBc
	input VSWR with respect to $50\ \Omega$	$P_L = 28\text{ W}$	–	–	2:1	

## VHF amplifier module

BGY145B



Epoxy fibre-glass board, 1/16 inch thick,  $\epsilon_r = 4.5$ .

A: 10  $\mu\text{F}$ , 16 V, tantalum chip capacitor.

B: 2 turns FX1115 Ferroxcube bead.

C: 0.1  $\mu\text{F}$ , 60 V, ceramic multilayer chip capacitor.

Track widths 'a' and 'd' ( $50 \Omega$ ) = 4 mm.

Track width 'b' = 2.5 mm.

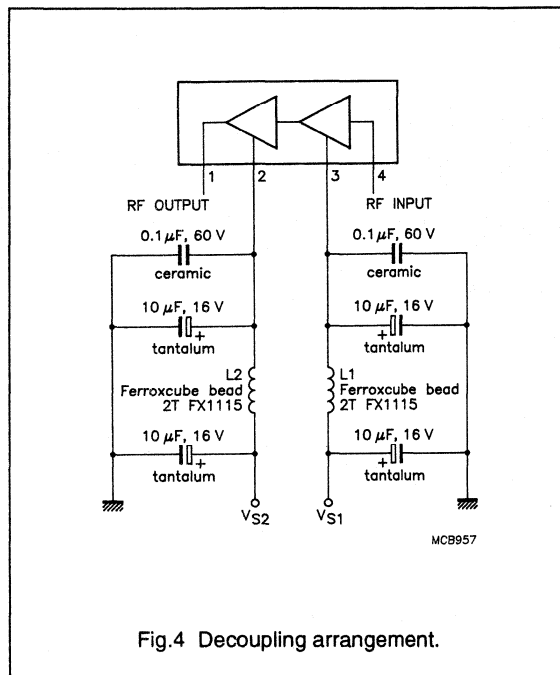
Track width 'c' = 3 mm.

Circles indicate the positions of through rivets.

Fig.3 Test jig.

## VHF amplifier module

BGY145B

**STABILITY**

The module is stable when operated into a load of 3:1 at all phases, providing the operating conditions are as follows:

$$P_D \text{ 30 to 450 mW; } P_L \geq 3 \text{ to } \leq 40 \text{ W;} \\ V_{S1} = 3 \text{ to } 15.5 \text{ V;} \\ V_{S2} = 10.5 \text{ to } 15.5 \text{ V and } V_{S1} < V_{S2}.$$

**RUGGEDNESS**

The output power of the module into a 50  $\Omega$  load will be unchanged after one minute of operation into a load mismatch of 20:1 (any phase), providing maximum ratings are not exceeded.

$$V_{S1}, V_{S2} \leq 15.5 \text{ V; } T_h \leq 90 \text{ }^\circ\text{C;} \\ P_L \leq 40 \text{ W; } P_D < 450 \text{ mW.}$$

**RF POWER CONTROL**

The module is not designed to be operated at constant output power.

However, the module may be operated over a range of output power levels by varying the input drive power level,  $P_{IN}$ . For stable operation, care must be taken to maintain conditions within the specified range:

$$P_D \text{ 30 to 450 mW; } V_{S1} = 3 \text{ V to } V_{S2}; \\ P_L = 3 \text{ to } 28 \text{ W.}$$

**CAUTIONS**

The main earth return path for this module is via the flange. Therefore, it is important that the heatsink is well earthed and that the return paths are kept as short as possible. Failure to do this may result in loss of output power or oscillation, which will have a detrimental effect upon the life of the module.

The RF output connection should be made to correctly designed 50  $\Omega$  terminals. Failure to do so will result

in a mismatch being presented to the module, with a resultant reduction in module life.

The leads of the devices may be soldered directly into a circuit using a soldering iron with a maximum temperature of 245  $^\circ\text{C}$ , for not more than 10 seconds at a distance of at least 1 mm from the plastic.

Under no circumstances must the maximum specified operating or storage temperatures be exceeded, even for short periods.

VHF amplifier module

BGY145B

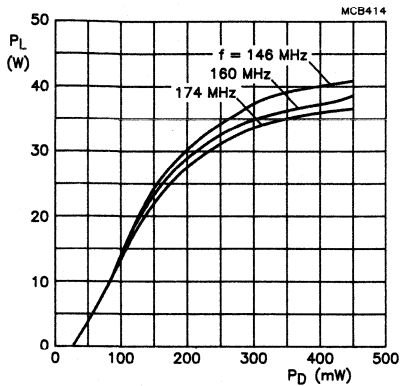


Fig.5 Load power as a function of drive power;  $V_{S1} = V_{S2} = 12.5$  V; typical values.

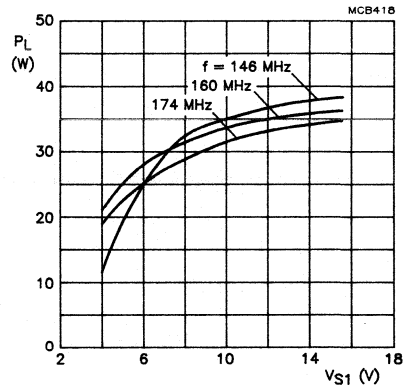


Fig.6 Load power as a function of supply voltage  $V_{S1}$ ;  $P_D = 300$  mW;  $V_{S2} = 12.5$  V; typical values.

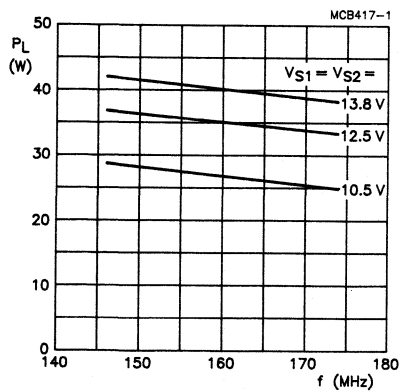


Fig.7 Load power as a function of frequency;  $P_D = 300$  mW; typical values.

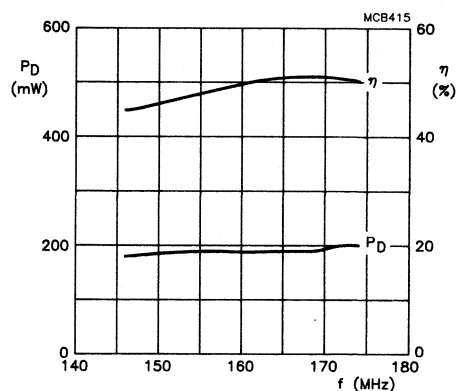


Fig.8 Efficiency and drive power as functions of frequency;  $P_L = 28$  W;  $V_{S1} = V_{S2} = 12.5$  V; typical values.

VHF amplifier module

BGY145B

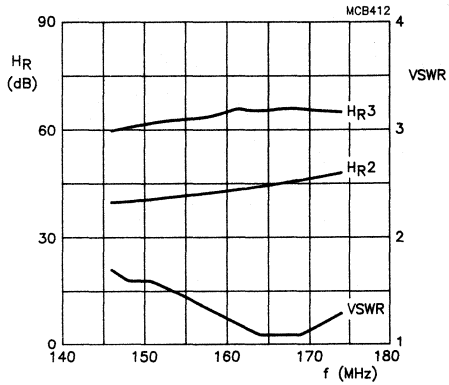


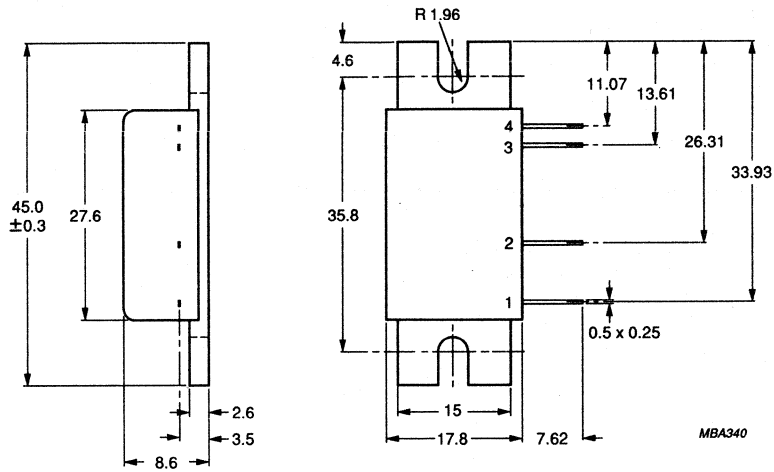
Fig.9 Second and third harmonic rejection as a function of frequency;  $P_L = 28$  W;  $V_{S1} = V_{S2} = 12.5$  V; typical values.



VHF amplifier module

BGY145B

PACKAGE OUTLINE



Dimensions in mm.

Fig.10 SOT183A.



## VHF amplifier module

BGY145C

## DESCRIPTION

An RF amplifier module designed for use in transmitters of mobile communications equipment powered by a 12.5 V battery supply.

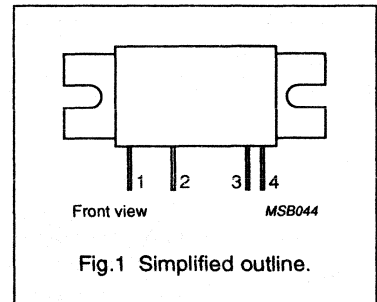
The module is a two stage transistor amplifier and consists of two RF npn transistors mounted on a ceramic substrate, together with surface mounted components that make up the matching and bias circuits.

The module will provide 27 W RF power into a 50  $\Omega$  load, when operated at nominal conditions within the frequency range of 174 to 200 MHz.

## PINNING - SOT183A

PIN	DESCRIPTION
1	output
2	$V_{S2}$
3	$V_{S1}$
4	input
flange	ground

## PIN CONFIGURATION



## QUICK REFERENCE DATA

Mode of operation: continuous wave.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f	frequency range		174	–	200	MHz
$P_L$	RF output power	$P_D = 300 \text{ mW}$	27	–	–	W
$G_p$	RF power gain	$P_L = 27 \text{ W}$	19.5	–	–	dB
$\eta$	efficiency	$P_L = 27 \text{ W}$	35	–	–	%
$V_{S1}, V_{S2}$	DC supply voltage		–	12.5	–	V
$Z_i$	input impedance		–	50	–	$\Omega$
$Z_L$	output load impedance		–	50	–	$\Omega$

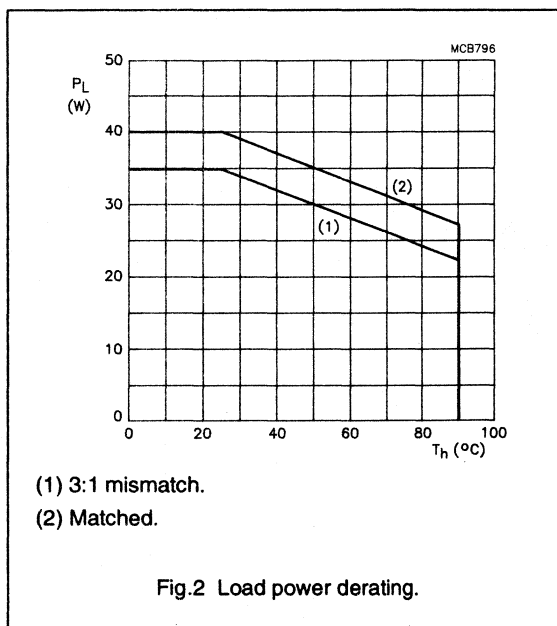
## VHF amplifier module

BGY145C

## LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
$V_{S1}, V_{S2}$	DC supply voltage	–	15.5	V
$\pm V_i$	RF input terminal voltage	–	25	V
$\pm V_o$	RF output terminal voltage	–	25	V
$P_D$	RF input power	–	450	mW
$P_L$	RF output power (see Fig.2)	–	40	W
$T_{stg}$	storage temperature range	–30	100	°C
$T_h$	heatsink operating temperature	–	90	°C



## CHARACTERISTICS

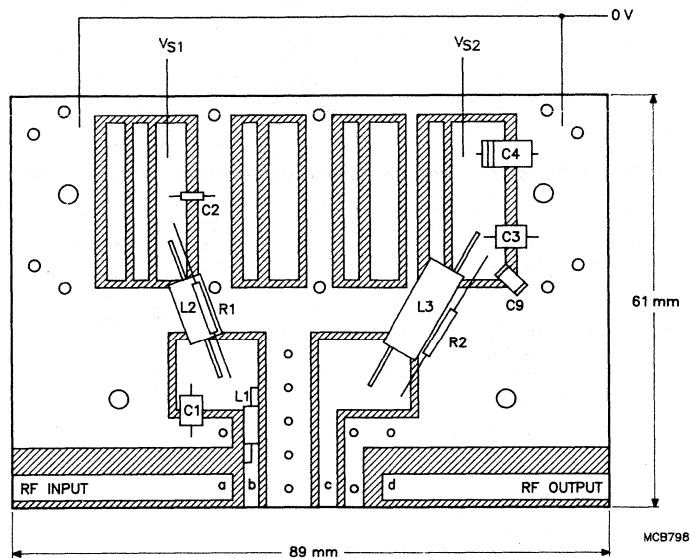
 $T_h = 25\text{ °C}$ ;  $V_{S1} = V_{S2} = 12.5\text{ V}$ ;  $R_S = R_L = 50\ \Omega$ ; frequency range = 174 to 200 MHz.

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$I_{Q1}$	quiescent current	$P_D = 0$	–	25	mA
$I_{Q2}$	quiescent current	$P_D = 0$	–	55	mA
$P_L$	RF output power	$P_D = 300\text{ mW}$	27	–	W
$G_p$	RF power gain	$P_L = 27\text{ W}$	19.5	–	dB
$\eta$	efficiency	$P_L = 27\text{ W}$	35	–	%
$H_{R2}$	2nd harmonic output	$P_L = 27\text{ W}$	–	–30	dBc
$H_{R3}$	3rd harmonic output	$P_L = 27\text{ W}$	–	–40	dBc
	input VSWR with respect to 50 $\Omega$	$P_L = 27\text{ W}$	–	2:1	

## VHF amplifier module

BGY145C

## APPLICATION INFORMATION



Epoxy fibre-glass board, 1/16 inch thick,  $\epsilon_r = 4.5$ .

L2 to be 90 degrees to L3.

Track widths 'a' and 'd' ( $50 \Omega$ ) = 4 mm.

Track width 'b' = 2.5 mm.

Track width 'c' = 3 mm.

Circles indicate the positions of through rivets.

Fig.3 Test jig.

## LIST OF COMPONENTS (Fig.3)

DESIGNATION	DESCRIPTION	VALUE	DIMENSIONS
C1, C3	63 V miniature polyester film capacitor	470 nF	
C2	35 V tantalum bead capacitor	4.7 $\mu$ F	
C4	35 V tantalum capacitor	1 $\mu$ F	
C9	50 V multilayer ceramic capacitor	47 nF	
L1	4 turns 0.45 mm diameter copper wire		int. dia. 2.5 mm
L2	4 turns 1 mm diameter copper wire		int. dia. 9 mm
L3	12 turns 1 mm diameter copper wire		int. dia. 9 mm
R1, R2	0.5 W resistor	12 $\Omega$	

## VHF amplifier module

BGY145C

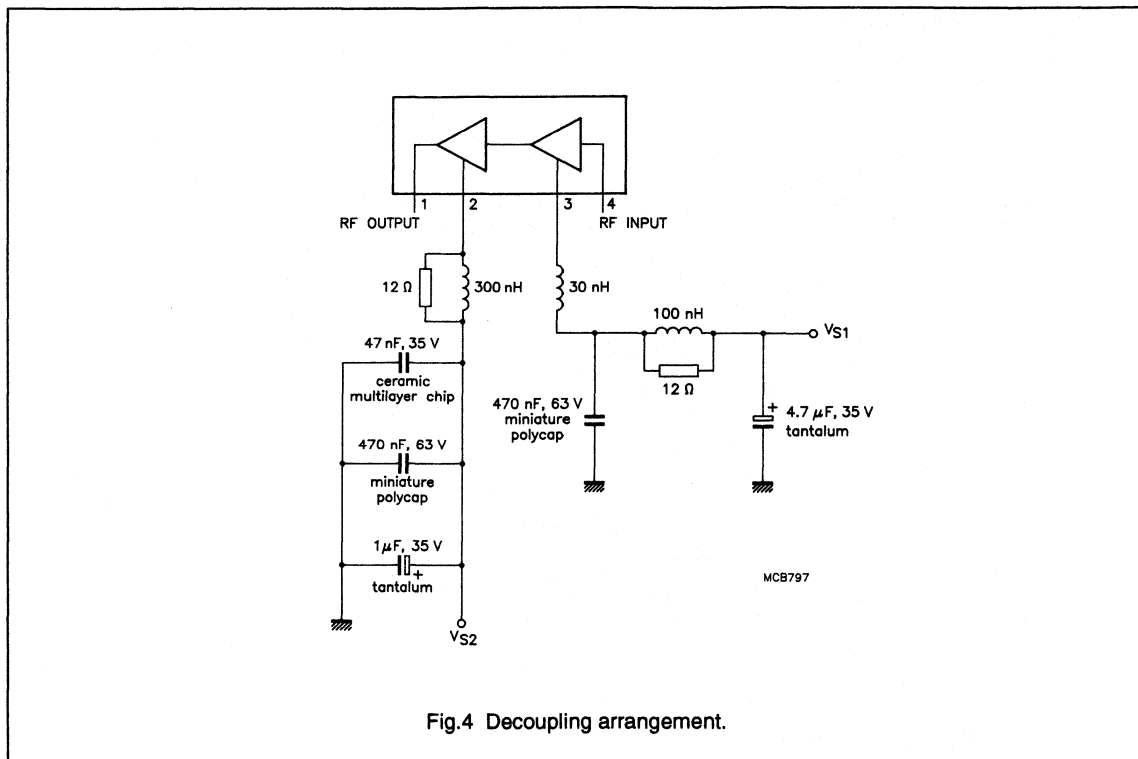


Fig.4 Decoupling arrangement.

**STABILITY**

The module is stable when operated with a load of up to 3:1 at all phases, providing the operating conditions are as follows:

$$P_D \text{ 15 to 450 mW; } P_L \geq 3 \text{ to } \leq 40 \text{ W;}$$

$$V_{S1} = 1.5 \text{ to } 15.5 \text{ V;}$$

$$V_{S2} = 10.5 \text{ to } 15.5 \text{ V and } V_{S1} < V_{S2}.$$

**RUGGEDNESS**

The output power of the module into a 50 Ω load will be unchanged after one minute of operation into a load mismatch of 20:1 (any phase), providing maximum ratings are not exceeded.

$$V_{S1}, V_{S2} \leq 15.5 \text{ V; } T_h \leq 90 \text{ }^\circ\text{C;}$$

$$P_L \leq 40 \text{ W; } P_D < 450 \text{ mW.}$$

**RF POWER CONTROL**

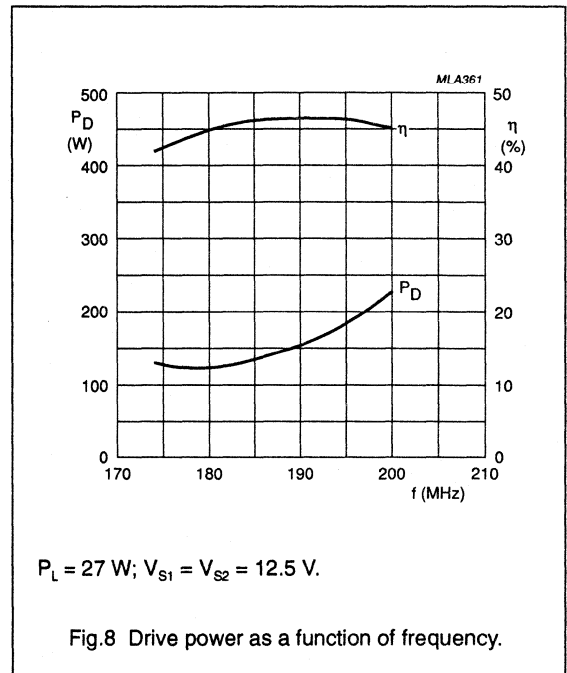
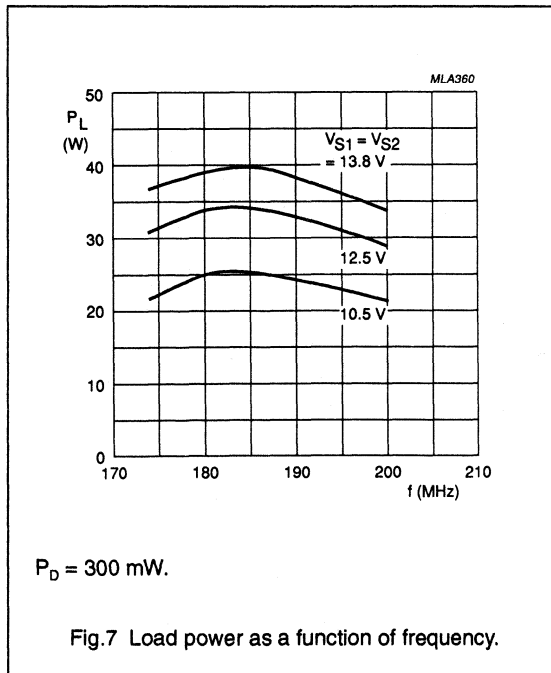
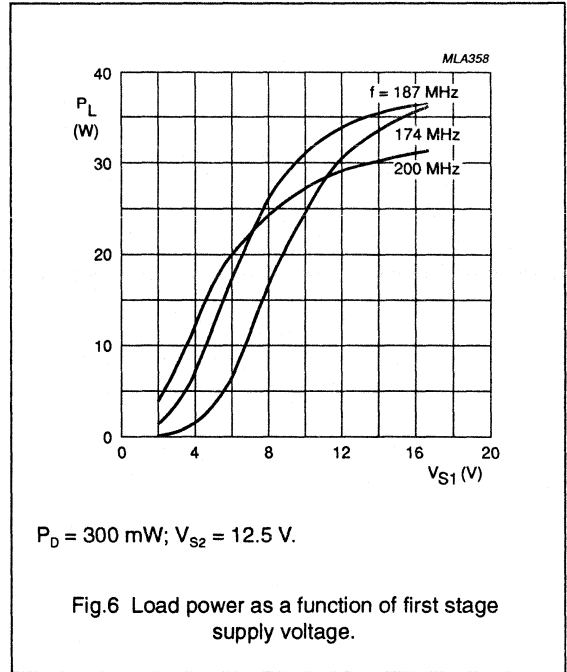
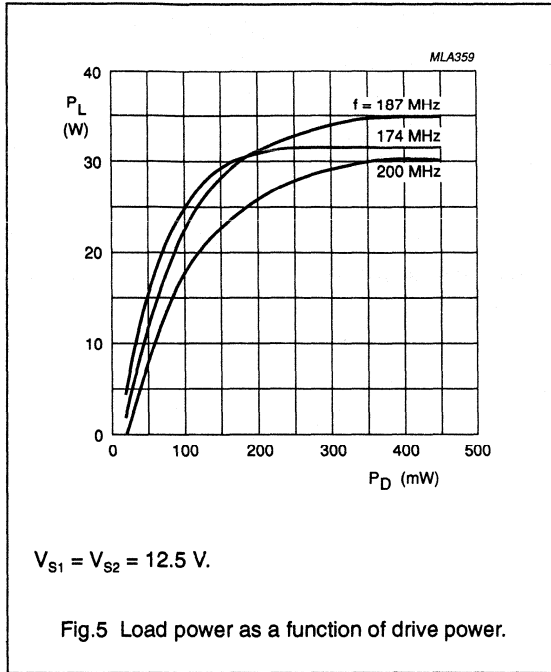
The module is designed to be operated over a power range up to 27 W, under nominal conditions. The output power may be controlled by adjusting the input power,  $P_D$ , or the first stage supply voltage,  $V_{S1}$ .

$$P_D = 15 \text{ to } 450 \text{ mW;}$$

$$V_{S1} = 1.5 \text{ V to } V_{S2}.$$

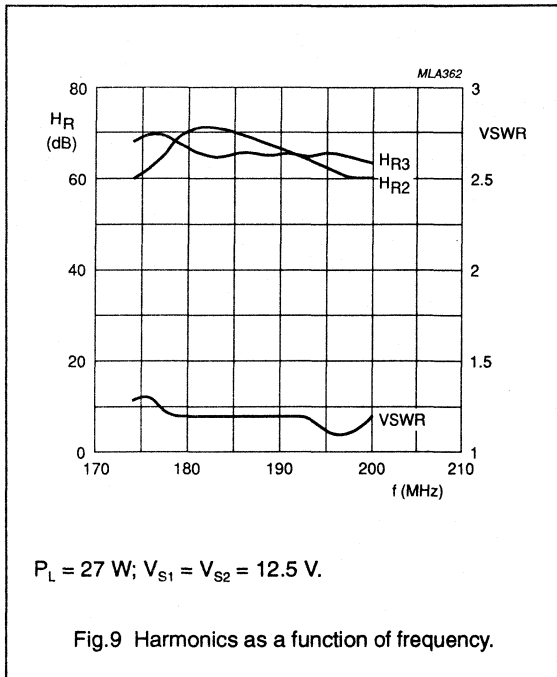
VHF amplifier module

BGY145C



VHF amplifier module

BGY145C

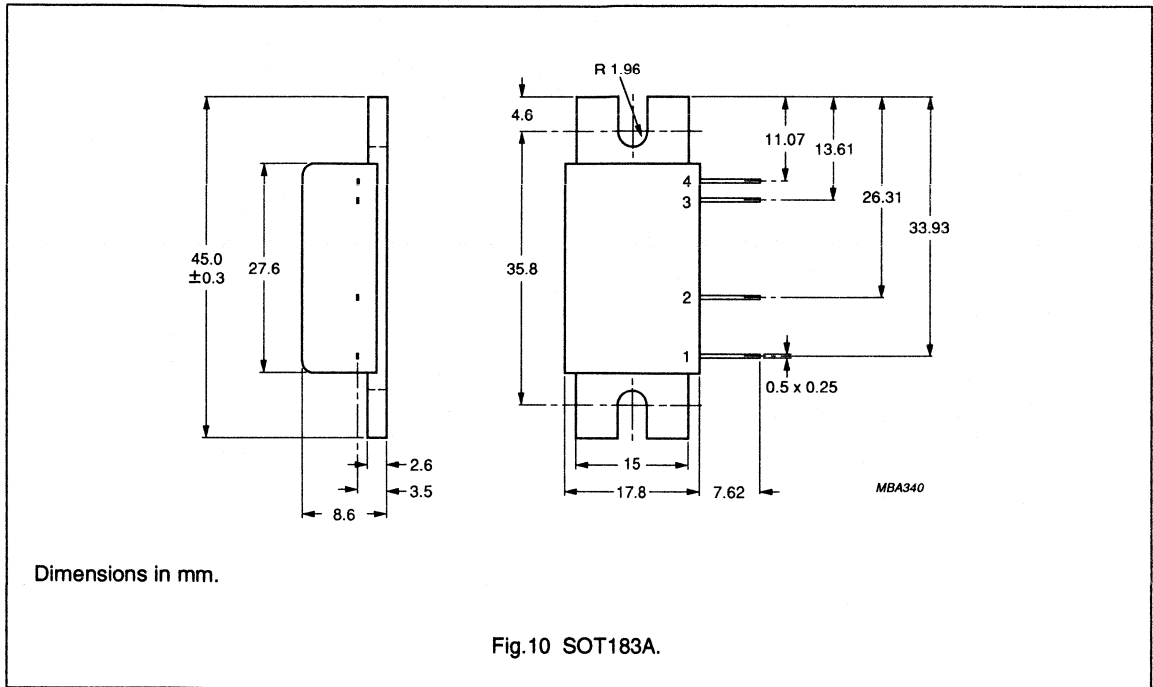




VHF amplifier module

BGY145C

PACKAGE OUTLINE





## DATA HANDBOOK SYSTEM

**INTRODUCTION**

Our data handbook system comprises more than 65 books with subjects including electronic components, subassemblies and magnetic products. The handbooks are classified into seven series:

INTEGRATED CIRCUITS;  
DISCRETE SEMICONDUCTORS;  
DISPLAY COMPONENTS;  
PASSIVE COMPONENTS;  
PROFESSIONAL COMPONENTS;  
MAGNETIC PRODUCTS;  
LIQUID CRYSTAL DISPLAYS.

Data handbooks contain all pertinent data available at the time of publication and each is revised and reissued regularly.

Loose data sheets are sent to subscribers to keep them up-to-date on additions or alterations made during the lifetime of a data handbook.

Catalogues are available for selected product ranges (some catalogues are also on floppy discs).

For more information about data handbooks, catalogues and subscriptions, contact one of the organizations listed on the back cover of this handbook. Product specialists are at your service and enquiries are answered promptly.

**INTEGRATED CIRCUITS**

IC01	Radio, Audio and Associated Systems Bipolar, MOS
IC02a/b	Video and Associated Systems Bipolar, MOS
IC03	ICs for Telecom Subscriber Sets, Cordless, Mobile and Cellular Telephones, Radio Pagers
IC04	HE4000B Logic Family CMOS
IC05	Advanced Low-power Schottky (ALS) Logic Series
IC06	High-speed CMOS; 74HC/HCT/HCU Logic Family
IC07	Advanced CMOS Logic (ACL)
IC07 supplement:	Additional ACL data

**INTEGRATED CIRCUITS (continued)**

IC08	10/100k ECL Logic/Memory/PLD
IC09	TTL Logic Series
IC10	Memories MOS, TTL, ECL
IC11	Linear Products
IC12	I <sup>2</sup> C-bus-compatible ICs
IC13	Programmable Logic Devices (PLD)
IC14	8048-based 8-bit Microcontrollers
IC15	FAST TTL Logic Series
IC15 supplement:	Additional FAST data
IC16	CMOS Integrated Circuits for Clocks and Watches
IC17	ICs for Telecom ISDN
IC18	Microprocessors and Peripherals
IC19	Data Communication Products
IC20	8051-based 8-bit Microcontrollers
IC23	Advanced BiCMOS Interface Logic

**DISCRETE SEMICONDUCTORS**

SC01	Diodes
SC02	Power Diodes
SC03	Thyristors and Triacs
SC04	Small Signal Transistors
SC05	Low-frequency Power Transistors and Hybrid IC Power Modules
SC06	High-voltage and Switching Power Transistors
SC07	Small-signal Field-effect Transistors
SC08a	RF Power Bipolar Transistors
SC08b	RF Power MOS Transistors
SC09	RF Power Modules
SC10	Surface Mounted Semiconductors
SC12	Optocouplers
SC13	PowerMOS Transistors
SC14	Wideband Transistors and Wideband Hybrid IC Modules
SC15	Microwave Transistors
SC17	Semiconductor Sensors

**DISPLAY COMPONENTS**

- DC01 Colour Display Components  
Colour TV Picture Tubes and Assemblies  
Colour Monitor Tube Assemblies
- DC02 Monochrome Monitor Tubes and Deflection  
Units
- DC03 Television Tuners, Coaxial Aerial Input  
Assemblies
- DC04 Loudspeakers
- DC05 Flyback Transformers, Mains Transformers  
and General-purpose FXC Assemblies

**PASSIVE COMPONENTS**

- PA01 Electrolytic Capacitors; Solid and Non-solid
- PA02 Varistors, Thermistors and Sensors
- PA03 Potentiometers and Switches
- PA04 Variable Capacitors
- PA05 Film Capacitors
- PA06 Ceramic Capacitors
- PA07 Piezoelectric Quartz Devices
- PA08 Fixed Resistors
- PA11 Quartz Oscillators

**PROFESSIONAL COMPONENTS**

- PC01 High-power Klystrons and Accessories
- PC02 Cathode-ray Tubes
- PC03 Geiger-Müller Tubes
- PC04 Photo Multipliers
- PC05 Plumbicon Camera Tubes and Accessories
- PC06 Circulators and Isolators
- PC07 Vidicon and Newvicon Camera Tubes and  
Deflection Units
- PC08 Image Intensifiers
- PC09 Dry-reed Switches
- PC11 Solid-state Image Sensors and Peripheral  
Integrated Circuits
- PC12 Electron Multipliers

**MAGNETIC PRODUCTS**

- MA01 Soft Ferrites
- MA02 Permanent Magnet Materials
- MA03 Piezoelectric Ceramics

**LIQUID CRYSTAL DISPLAYS**

- LCD01 Liquid Crystal Displays and Driver ICs for  
LCDs

## Philips – a worldwide company

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